AVSI's System Architecture Virtual Integration Program:

Proof of Concept Demonstrations



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Outline



SAVI Proof of Concept

- Motivation for Virtual Integration
- Phase 1 Proof of Concept
- Phase 2 Expanded Proof of Concept
- Phase 3 Initial Shadow Projects
- Results

Program Status Next Steps

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MOTIVATION FOR SYSTEMS ARCHITECTURE VIRTUAL INTEGRATION (SAVI)











The trend is to add features / functionality

- Functionality is often implemented in software
- Size and complexity are growing exponentially
 - Software-based systems are becoming dominant
 - This marriage of hardware/software enables systems of systems
- Examples

Portable phones

Airliner cockpits





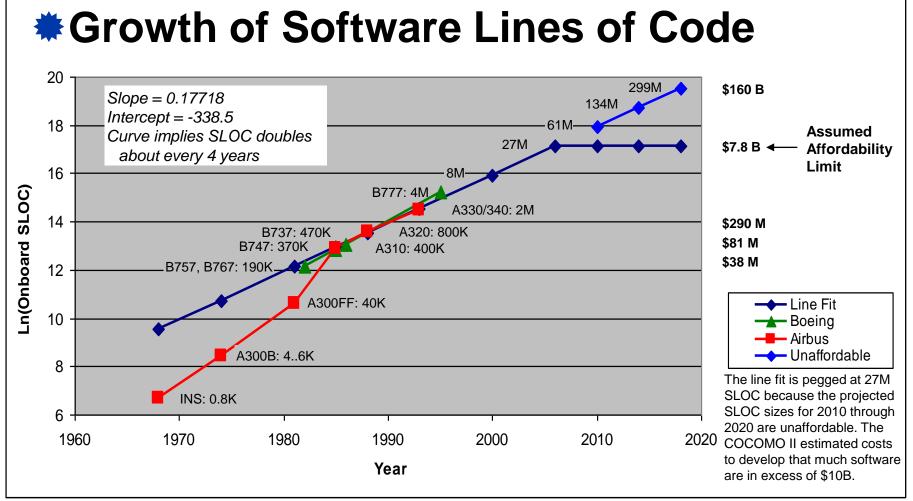






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One Measure of Complexity



Airbus data source: J.P. Potocki De Montalk, Computer Software in Civil Aircraft, Sixth Annual Conference on Computer Assurance (COMPASS '91), Gaithersburg, MD, June 24-27, 1991. Boeing data source: John J. Chilenski. 2009. Private email.







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New integration problems result from combining:

- Rapid technological advancement and obsolescence
- Increasingly complex hardware and software evolution
- > Migration to increasingly software-based systems

Increased software \rightarrow increased interfaces \rightarrow increase in integration problems

- Software interfaces not as "transparent" as mechanical interfaces
 goes beyond inputs and output
- Most complex system interfaces cross multiple suppliers (hardware and software)

Complicating Issues - It's not going to get better, it's only going to get worse

- Increased software lines of code
- > Increased integration, verification and validation efforts





Industry is moving toward Model-Based

- Engineering
- > Development
- > Manufacturing
- Production
- Verification
- Validation
- Integration



For both Systems and Software

EXPLOSION IN MODELS









The complete Model Set for a system needs to be in compliance (i.e. consistent)

- with the top-level specification of what is intended/wanted/ required
- > with the physics of the system environment

Do the Models within the Model Set need to be consistent with each other?

If they are not consistent, then there are multiple truths about the system in the Model Set







SAVI Program Concepts

- 1. Start integrated, stay integrated
- 2. Integrate, analyze, then build
- 3. Architecture-centric, single truth Model Repository
- 4. Distributed and Heterogeneous Data Exchange Layer
- 5. Standards based
- 6. Semantically precise for quantitative analyses
- 7. Mixed maturity development incremental V&V
- 8. Support the business case
- 9. Collaborate leverage "Best-In-Class"

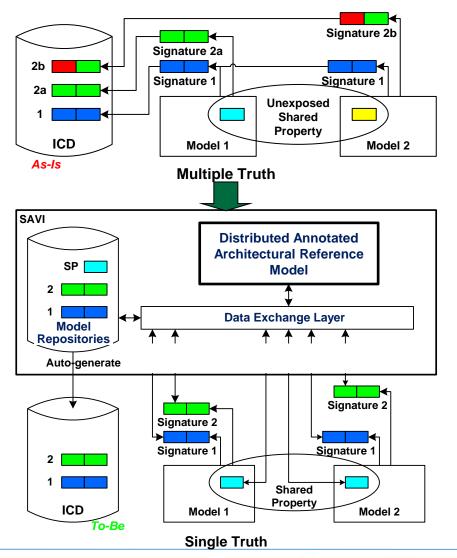








As-Is to To-Be → Single Truth



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Models from multiple design teams contain multiple interdependent properties

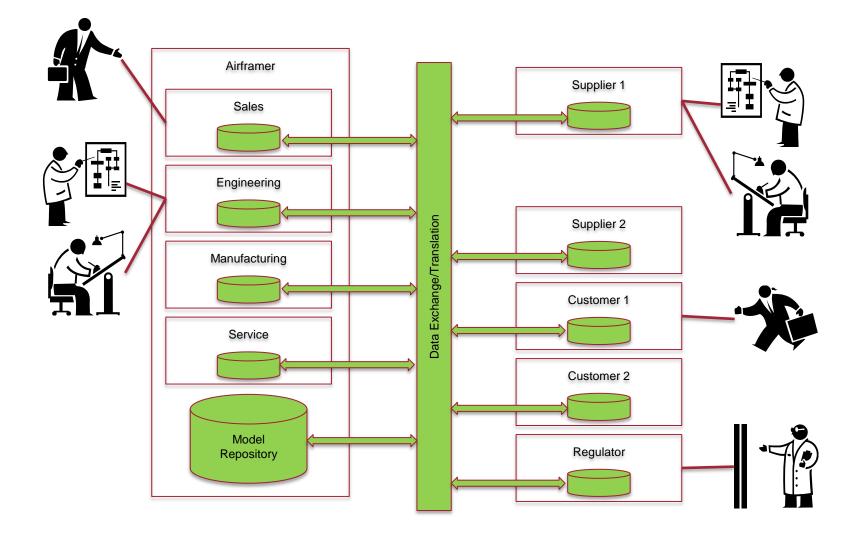
- Each design team identifies multiple ways of modeling (abstracting) these common properties - multiple models and tools
 - Each team abstracts properties in different ways
 - Each team's approach to modeling common properties may not be equivalent

Results: multiple truths





Multiple Groups/Tools/Repositories





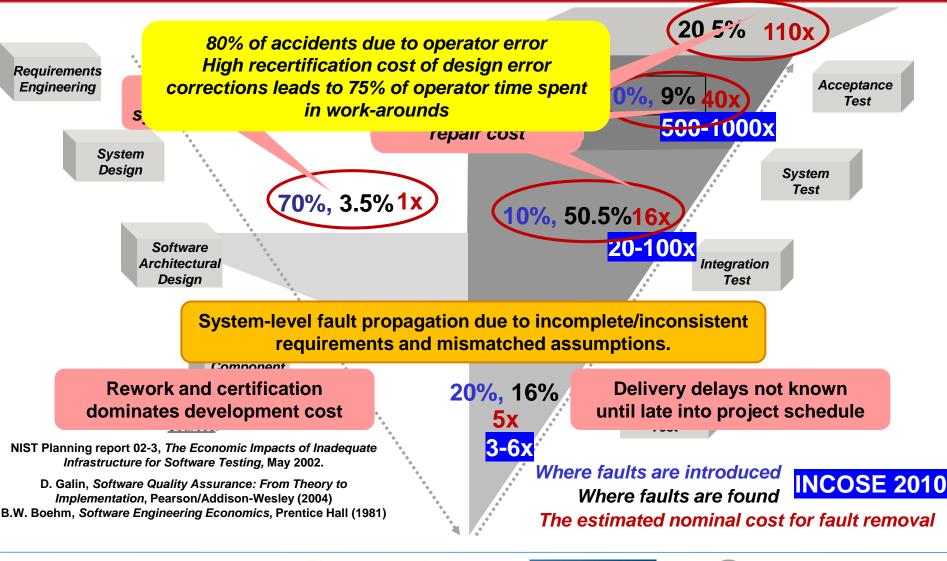






S-A-V-I

Late Discovery of Problems



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POC PHASE 1 RESULTS



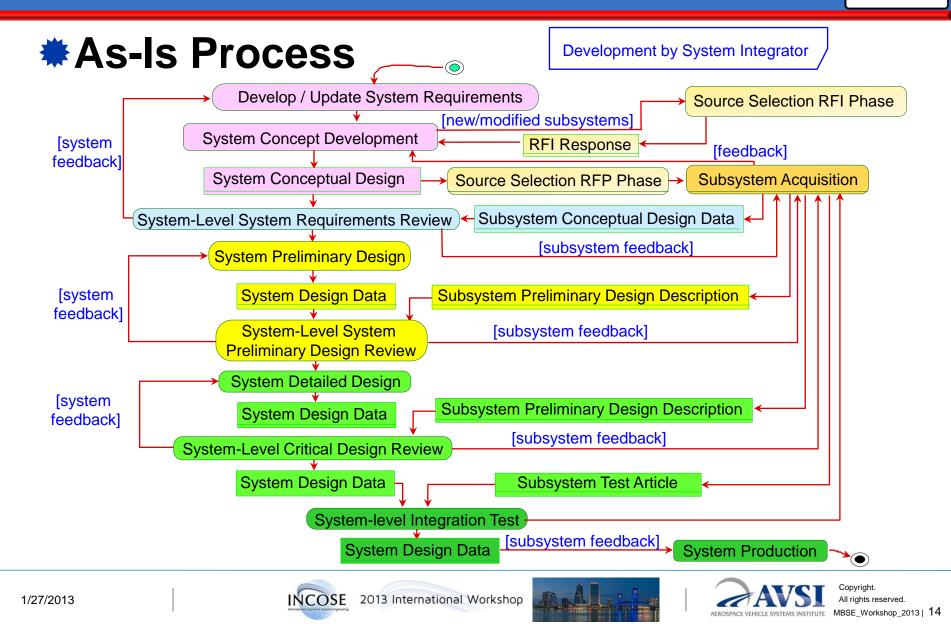






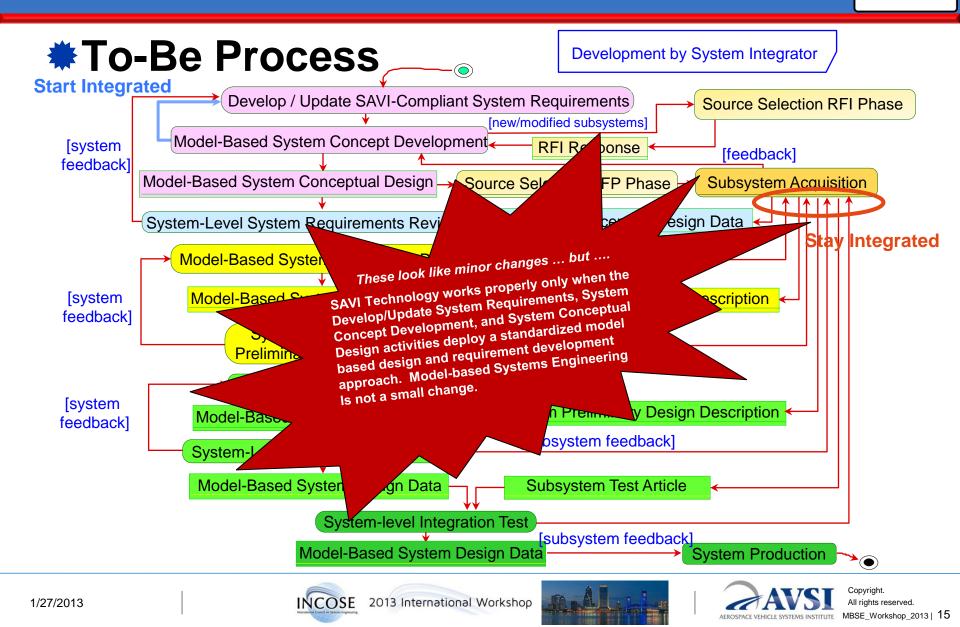
AFE 58 As-Is Acquisition Process

S-A-V-J



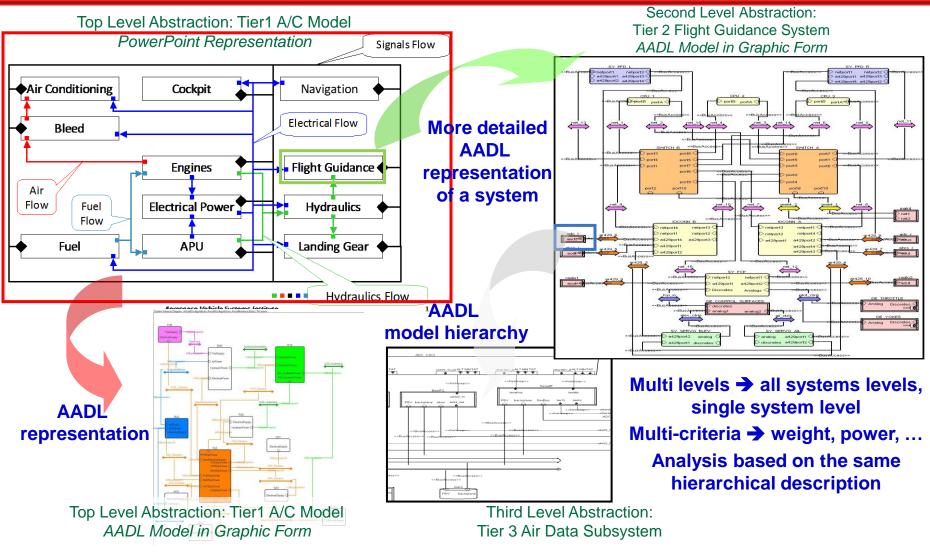
AFE 58 To-Be Acquisition Process

 $S^{T}A_{T}V^{T}I$



AFE 58 PoC Models





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AFE 58 Models Based on AADL



Connection Consistency

```
system Engines
features
ElectricalPower: requires bus access ElectricalPower
{ SAVI::PowerSupply => access 20000.0 W;};
HydraulicPower: requires bus access HydraulicPressure
{ SAVI::PressureCapacity => access 5000.0 psi;};
AirPower: requires bus access AirFlow;
FuelSupply: requires bus access FuelFlow
{ SAVI::FuelBudget => access 5000.0 GalpH;};
Signals: requires bus access SignalFlow;
properties
SAVI::System_Tier => tier2;
SEI::NetWeight => 15000.0 kg;
SAVI::Requirement => "Req 2";
end Engines;
```

AADL is a strongly-typed Architectural Definition Language

Generates code that supports analysis

Allows consistency checking to be implemented



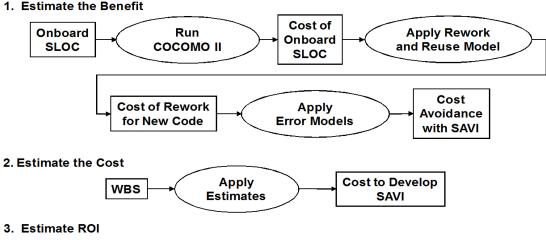




AFE 58 Return on Investment



Estimation flow – software dominates



 $Rol = \frac{NPV(Cost \ avoidance \ with \ SAVI \ implemente \ d... \ discounted \ @ 10\%)}{NPV(Cost \ to \ develop \ SAVI...discounted \ @ 10\%)* \ Years}$

COCOMO II Results (Multiplier of 1.55 used to include hardware

	NPV (Cost Avoidance)	Total Cost Avoidance	NPV (Cost to Develop)	ROI % per year
Pessimistic	\$64 M	\$99 M	(\$85.7 M)	2%
Expected	\$256 M	\$398 M	(\$85.7 M)	40%
Optimistic	\$768 M	\$1.193 B	(\$85.7 M)	144%

effects)



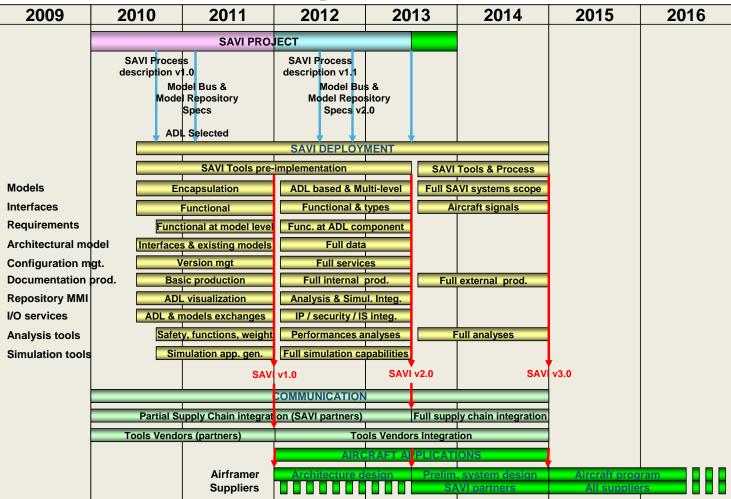




AFE 58 Road Map



Based on Assumptions Prior to 2008









AFE 58 Assessment



Will AFE 58 sufficiently evaluate the technical risks to know that SAVI is possible?

Yes: we have demonstrated the key concepts and technologies to a level that will reduce technical risk to an acceptable level for the participating member companies.

Will the ROI development reasonably scope the financial commitment and potential return for participating member companies?

The ROI methodology is very conservative - built on accepted precedent and explicit assumptions and validated with multiple sources of data. It will allow participating companies to fine tune the ROI for their own, unique situations.

Is the SAVI program too ambitious for AVSI?

Jury is out: member companies must individually assess the validity of the ROI and the level of technical risk in the context of their own business environments. AFE 58 demonstrates feasibility (it can be done) and points to mutually benefits with the right level of resource commitment. The upside potential benefits are very enticing, but it requires considerable investment to reap the benefits. We will need to be innovative in structuring the path forward to make this palatable to participants.









EPOC PHASE 2 RESULTS







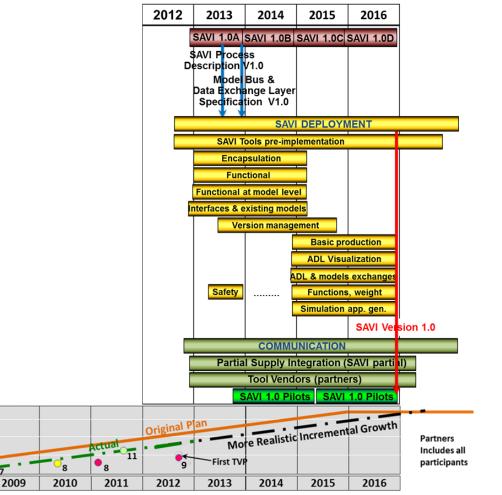




Revised Road Map



Incremental Development Emphasized









"Fit" Demonstration

Electronic Case Element

Reliability Demonstration

- > MTBF Model
- Interface with Moebis

Safety Demonstration

- > FHA
- **FMECA**

Behavior Demonstration

> Aeroelastic (FEM) Model of Lifting Surface

Hydromechanical Model of Control Elements







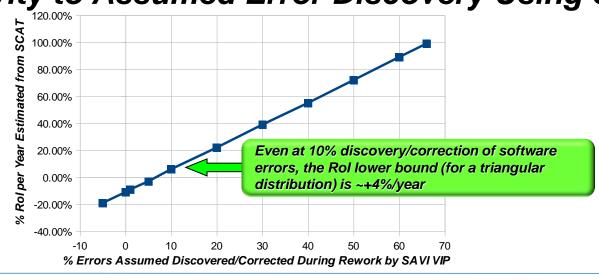
AFE 59 Return on Investment

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Still Using COCOMO II with SCAT Added *Rol Estimates Still Very High*

Average Rol - average deviation for ten Monte Carlo runs				Assumes 66% of software
30% new SLOC	40 % new SLOC	50 % new SLOC		defects are discovered and corrected during the SAVI VIP
78 % 0.81%	98 % 1.05%	115% 1.73%	¢	

Small Deviation in Results from Monte Carlo Runs Sensitivity to Assumed Error Discovery Using SAVI







EPOC SHADOW PROJECT RESULTS



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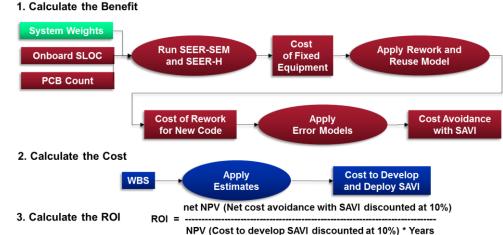
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AFE 59S1 Return on Investment

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Compared Estimates with SEER Results



*****SEER Model Shows Similar Rol

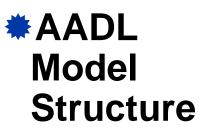
AP Systems	HW + SW		AP Systems	SW Only		Enter the rose-green-rose color block of values in I			
No Rework			No Rework			Will need to do this twice, once with rework value			
\$7,433,252,909	\$12,264,867,299	\$17,034,537,916	\$6,711,266,260	\$11,073,589,329	\$15,379,985,179	CDF Output	COCOMO II cost to develop this amount of new SLC		
						CDF Output	Labor months		
With rework			With rework						
\$9,737,561,310	\$16,066,976,162	\$22,315,244,669	\$8,791,758,801	\$14,506,402,021	\$20,147,780,585	CDF Output	COCOMO II cost to develop this amount of new S		
						CDF Output	Labor months		
\$2,304,308,402	\$3,802,108,863	\$5,280,706,754	\$2,080,492,541	\$3,432,812,692	\$4,767,795,406	Aircraft Summary	Cost of rework		
	78.95%					Cost Escalation	% of cost of rework due to requirement	ts errors	
\$1,819,350,545	\$3,001,928,400	\$4,169,344,999	\$1,642,638,301	\$2,710,353,197	\$3,764,379,440	Aircraft Summary	Cost of requirements errors rework		
	15.79%					Cost Escalation	% of cost of rework due to design erro	rs	
\$363,941,505	\$600,503,483	\$834,032,616	\$328,592,122	\$542,177,001	\$753,023,612	Aircraft Summary	Cost of design errors rework		
	94.75%					Cost Escalation	% of rework due to requirements errors	s and design err	
\$2,183,292,050	\$3,602,431,883	\$5,003,377,615	\$1,971,230,423	\$3,252,530,197	\$4,517,403,052	Aircraft Summary	Cost of rework due to requirements and design errors		
	10%					Benefit NPV	Discount rate		
33%	66%	99%				Error Model	Triangular distribution of % of requirem	ients & design e	
52.53%	66.00%	79.47%				Triang. Distr.	Expected % of errors prevented		
\$1,146,835,422	\$2,377,605,043	\$3,976,293,944	\$1,035,444,100	\$2,146,669,930	\$3,590,079,298	Aircraft Summary	Cost avoidance with SAVI		
\$373,409,832	\$774,148,655	\$1,294,682,066	\$337,140,796	\$698,956,138	\$1,168,930,504	Aircraft Benefit NPV	NPV(Cost avoidance with SAVI)		
(\$53,533,236)	(\$88,329,840)	(\$122,680,334)	(\$48,333,591)	(\$79,750,425)	(\$110,764,479)	Aircraft Total Cost NPV	Cost to develop SAVI		
(\$1,161,965)	(\$1,161,965)	(\$1,161,965)	(\$1,049,104)	(\$1,049,104)	(\$1,049,104)	Aircraft Deploy Cost	Cost to deploy SAVI		
(\$37,709,068)	(\$62,219,963)	(\$86,416,615)	(\$34,046,413)	(\$56,176,581)	(\$78,023,029)	Aircraft Total Cost NPV	NPV(Cost to develop SAVI) of 5.5 year development		
(\$596,272)	(\$596,272)	(\$596,272)	(\$538,356)	(\$538,356)	(\$538,356)	Aircraft Total Cost NPV	NPV(Cost to deploy SAVI) after 5.5 year development		
97%	126%	154%	97%	126%	154%	Summary	Arithmetic Rate of Return (ROI) over	r 9 years from	



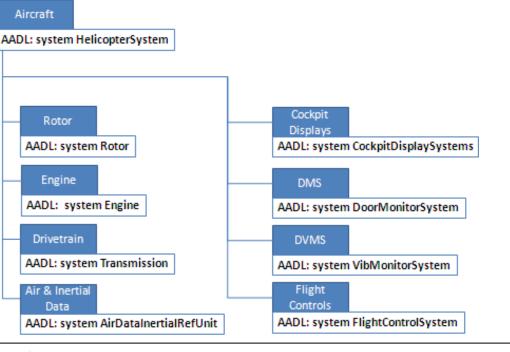




Aircraft Monitoring System



Interface uses AADL features structure



features

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```
Signals: requires bus access SignalFlow;
Mountings: requires bus access MountPoints;
HydraulicPower: requires bus access HydraulicFlow;
ElectricPower: requires bus access ElectricPowerFlow;
-- Interfaces for other subsystems - added per 3/29/12 minutes
FCS_DMS: port group FCStoDMS;
FCS CDS: port group FCStoCDS;
```







- CAAS "fully integrated flight and mission management capability..."
 - Common digital architecture for U. S. Army rotary wing aircraft
 - Fully open, non-proprietary system embracing commercial standards
 - Consistent, intuitive user interface for displays that allows control of all avionics subsystems









NEXT STEPS









SAVI Proof of Concept Takeaways

No Roadblocks

Architecture-centric Analysis Works

- Model-based Elements Feasible
 - Narrative elements were captured
 - Property exchanges were carried out
 - Inconsistencies were detected and quantified
- Cyber-Physical Interfaces Were Demonstrated with AADL Model
 - ✓ MATLAB/Simulink, LISA (FEM) simple scripts (need to be automated and verified)
 - Simple fit geometries (CATIA)
 - Safety and Reliability tools for FHA and FMECA; MTBF analysis
- Major Lessons Focus for SAVI Version 1.0
 - "Single Truth" Does not Imply Single Language
 - AADL's strong semantics facilitates architectural analyses
 - SysML graphical tools are helpful for data flow and to illustrate Use Cases
 - Two-way translations are available (Cofer's work for DARPA extended for SAVI)
 - Other translations will be needed
 - Repository Interfaces Are Complex
 - Must facilitate consistency checking
 - Must provide protection for intellectual property
 - Must provide automated configuration management
 - Must provide verification path
 - Must underpin and encourage formal analysis
 - ✓ Must spell out needed translators/converters for unique project requirements
 - Involve Tool Vendors and Standards Body (ies)

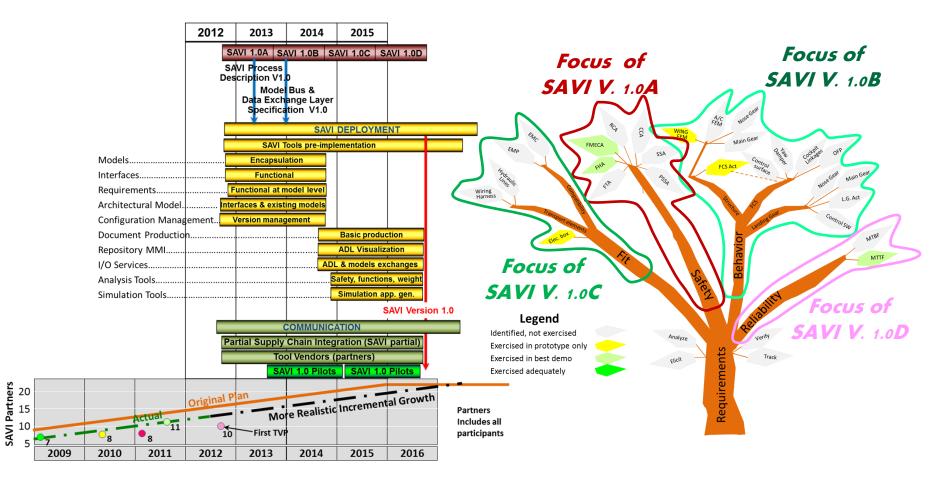






S-A-V

SAVI Roadmap for Next Stage



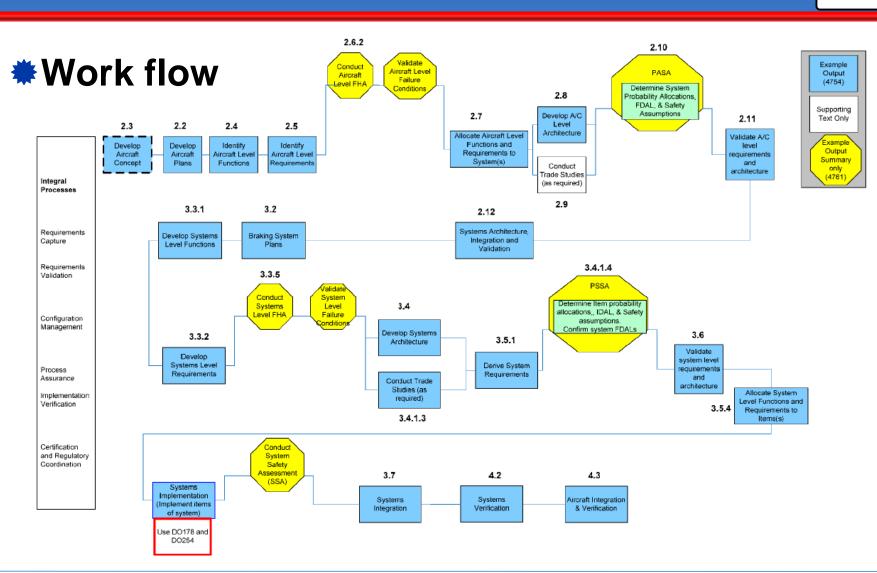


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Aircraft Braking System Safety



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S-A-V-I

SAVI Version 1.0 Actions



- SAVI Initial Capability Phase (Version 1.0A)
 - Specify the SAVI Virtual Integration Process
 - Use AADL Requirements Annex
 - Requirements Generation
 - Requirements Validation
 - Requirements Traceability
 - Spell Out Multiple Language Interfaces
 - Define needed translators/mapping tools
 - Evaluate mapping and translators available
 - Document the VIP (set initial baseline)
 - Specify Model Bus and Data Exchange Layer
 - Initiate Application of the VIP Process
 - Apply Analysis Techniques Used in SAVI
 - Illustrate Specification with Models
 - Implement translators
 - Description of Repository Interfaces
 - Capture Functionality of System
 - Encapsulate Consistency Checking
 - Set up Version Management Scheme
 - Illustrate Specification with Models
 - Implement translators
 - Involve Tool Vendors
 - Capture Inputs to Version 1.0 Specification
 - Encourage setting roadmaps for tool development







- The problems caused by escalating complexity are being felt the majority of large aerospace systems developments. Thus the need is immediate to develop the next generation of system design tools and processes.
- The SAVI Program is a collaborative, industry-led project developing the processes and technologies necessary to enable virtual integration of complex systems.
 - The problem space is large and diverse. An industry-consensus effort leading to a set of implementable standards is necessary for a viable solution.
 - The impact will be on the full product lifecycle. All stakeholders in the design, development, manufacture, distribution, operation, and maintenance of complex systems need to be engaged.
- A solution will require continued investment and direction from both government and industry and employ technology development with academic partners.



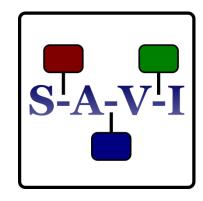






Questions?





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