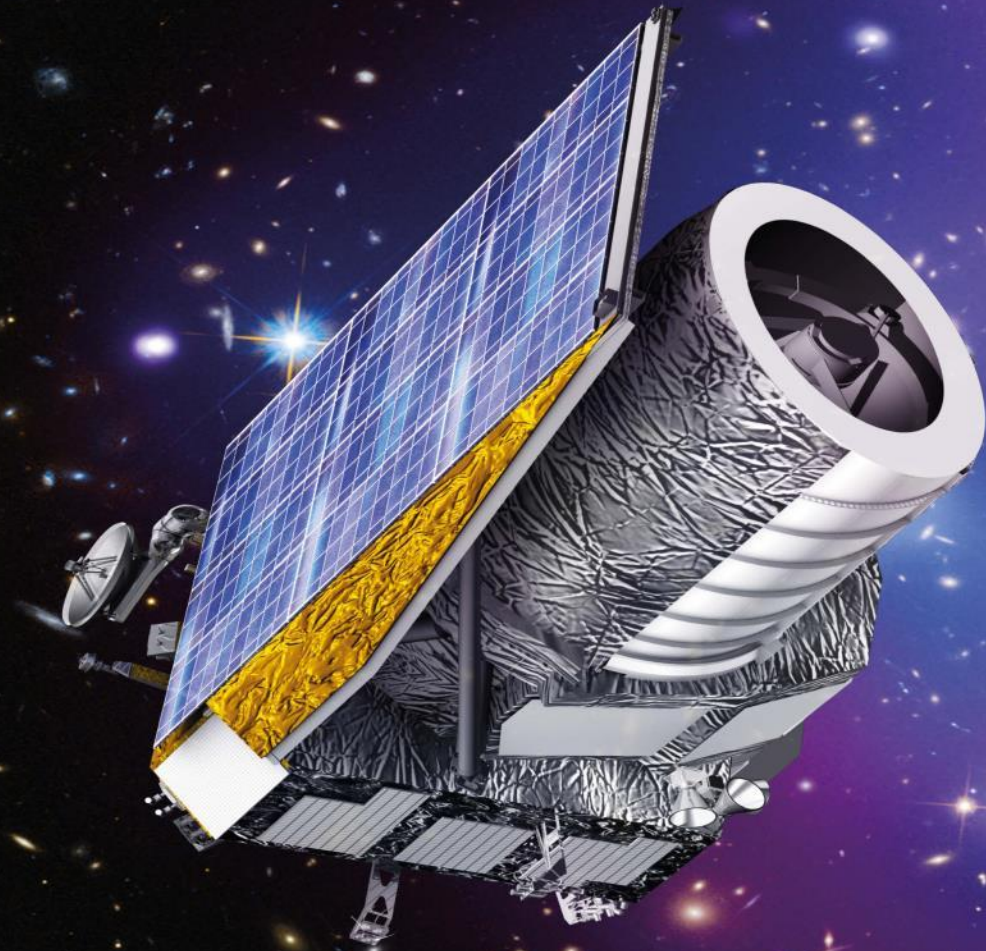


MBSE approach for the Euclid mission: Benefits and lessons learned (so far)

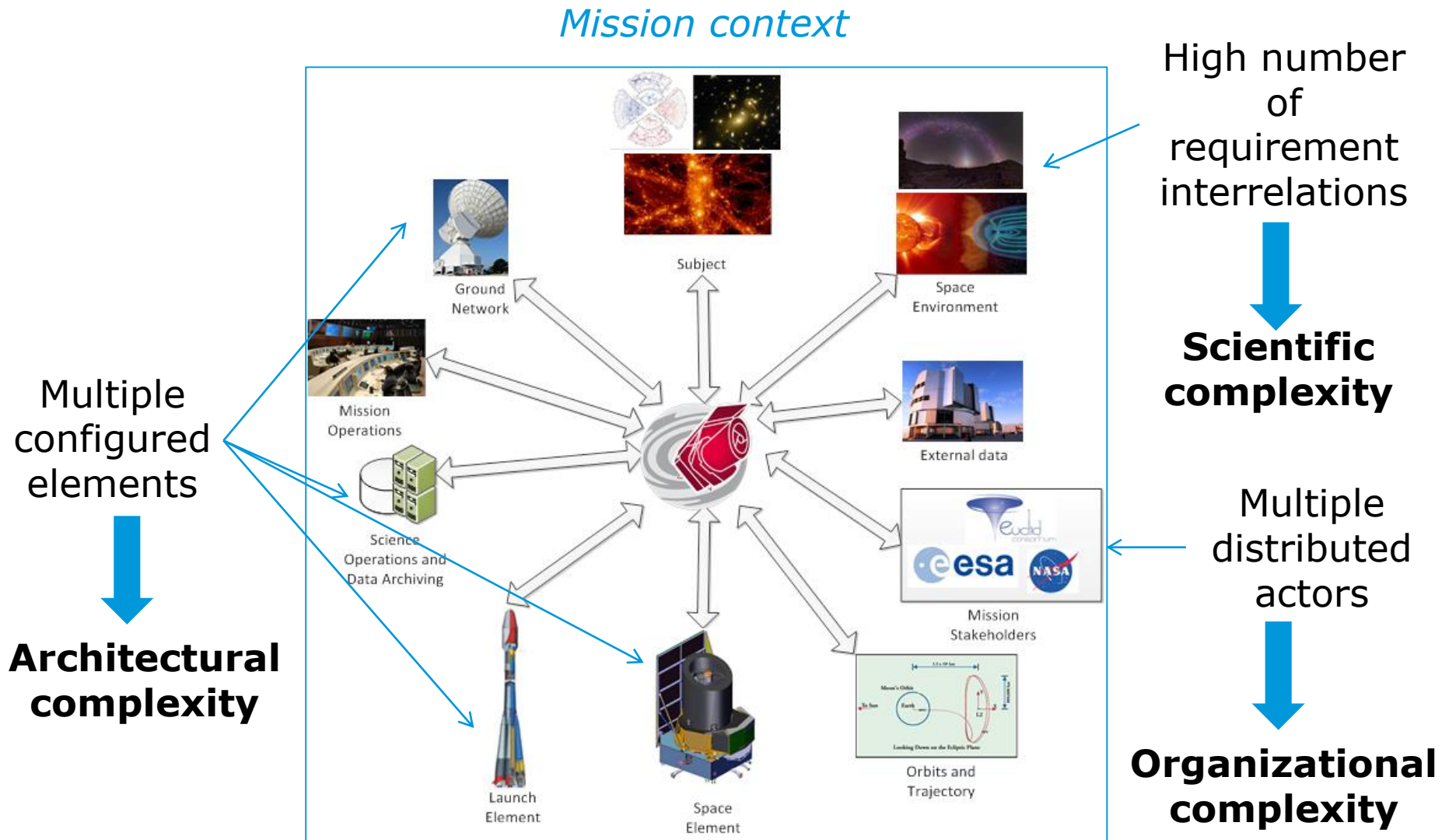
J. Lorenzo Alvarez, H. Metselaar, M. Kretzenbacher (ESA)

INCOSE IW 2017, Torrance, CA, 28-31 Jan 2017



Background image: NASA, ESA, DGC, C. Ma, H. Ebeling and E. Barrett (University of Hawaii/JPL), et al./and STSD

Mission Complexity definition

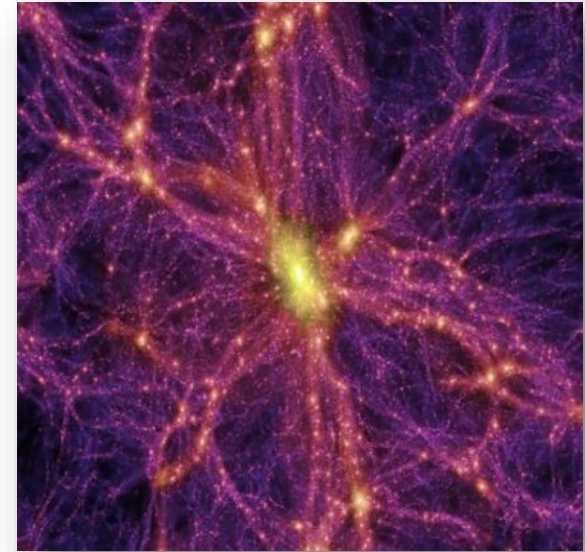


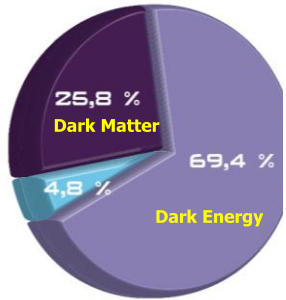
Euclid Mission Objectives

The Euclid Mission will measure the universe expansion history and growth of large-scale structure with a precision that will allow to distinguish time-evolving dark energy models from a cosmological constant, and to test the theory of gravity on cosmological scales. In addition it will constrain the initial conditions in the very early Universe, by determining the statistical distribution of the primordial density fluctuations with high precision, on scales that cannot be probed using observations of the cosmic microwave background (CMB).

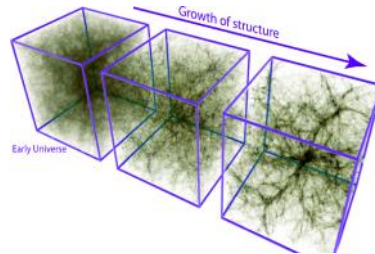
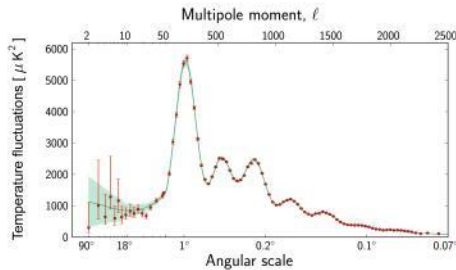
The mission will address the following four key cosmological questions:

- **Dynamical Dark Energy:** *Is the dark energy simply a cosmological constant, or is it a field that evolves dynamically with the expansion of the Universe?*
- **Modification of Gravity:** *Alternatively, is the apparent acceleration instead a manifestation of a breakdown of General Relativity on the largest scales, or a failure of the cosmological assumptions of homogeneity and isotropy?*
- **Dark Matter:** *What is dark matter? What is the absolute neutrino mass scale and what is the number of relativistic species in the Universe?*
- **Initial Conditions:** *What is the power spectrum of primordial density fluctuations, which seeded large-scale structure, and are they described by a Gaussian probability distribution?*





The Planck collaboration.
Ade et al 2013

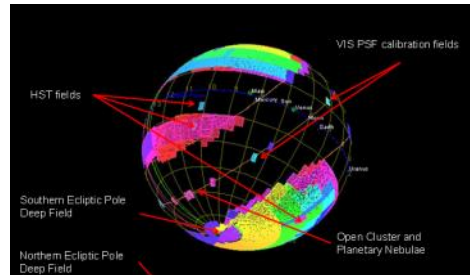
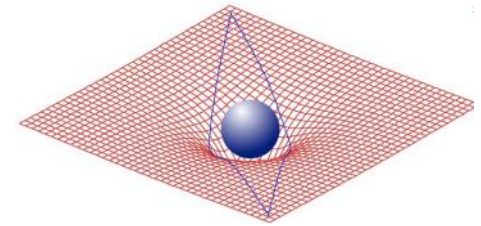
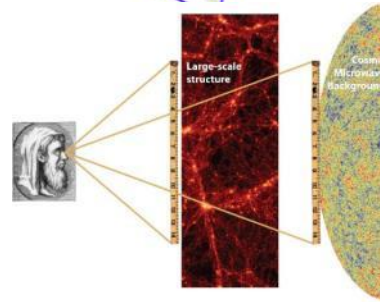


WHAT? Cosmology beyond the Planck mission:

- ❖ Dark Matter distribution
- ❖ Dark Energy nature

HOW?

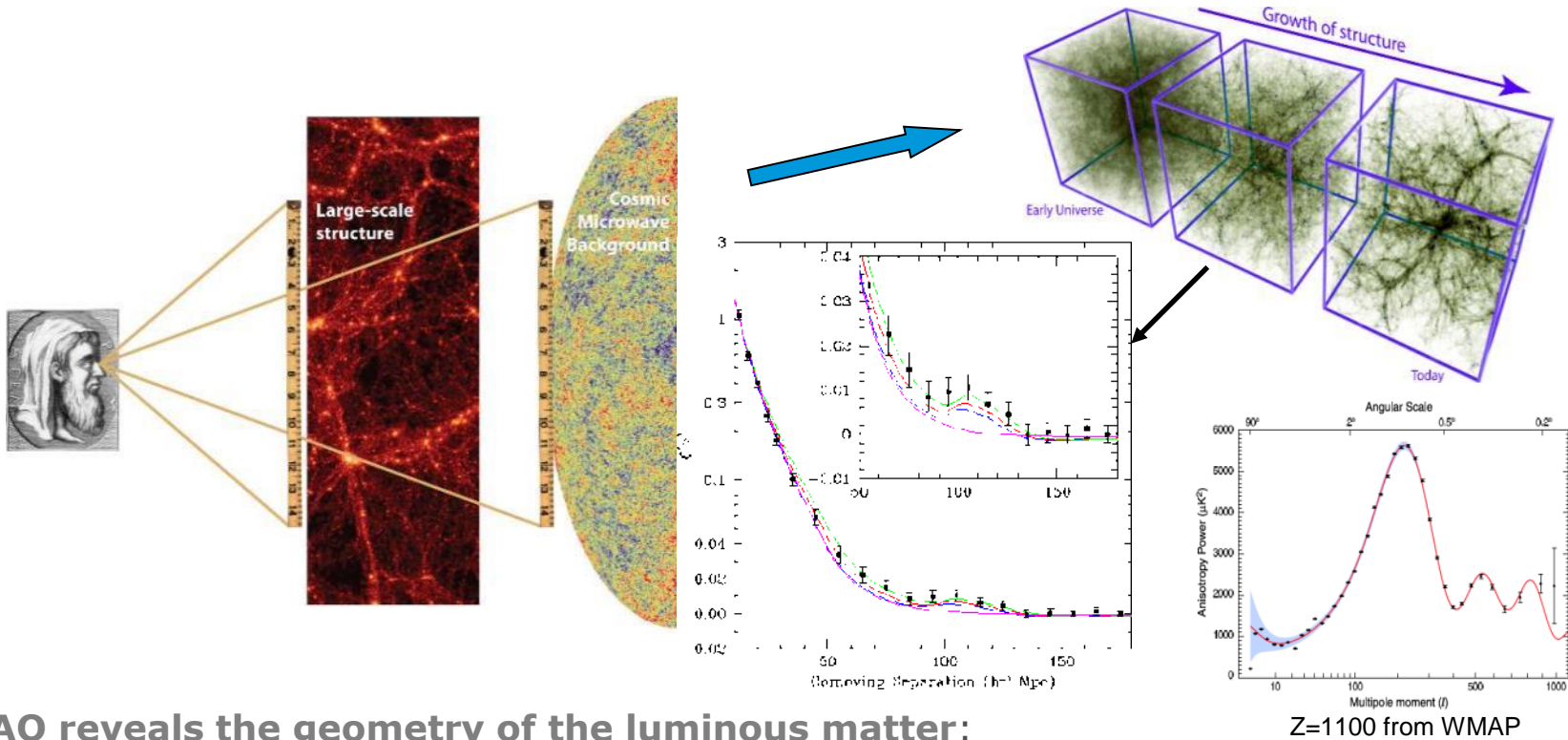
- ❖ Probed through:
 - ❖ BAO
 - ❖ Weak Gravitational Lensing



The Mission:

- ❖ Large Sky Survey:
 - ❖ 15,000 deg²
 - ❖ Visible imaging
 - ❖ Near-Infrared Photometry
 - ❖ Near-Infrared Spectroscopy

Baryonic Acoustic Oscillations



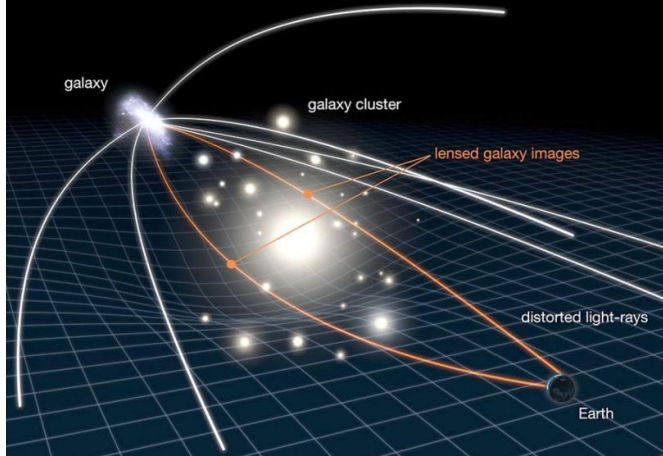
BAO reveals the geometry of the luminous matter:

- Measure redshifts of galaxies over a large volume
- Obtain the power spectrum for a given redshift bin
- Determine the “wiggles” – the acoustic peaks
- The peaks correspond to a typical scale length

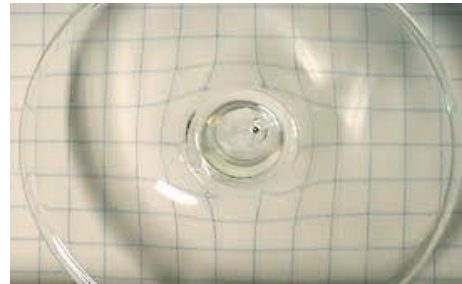
Requirement complexity

Weak Lensing

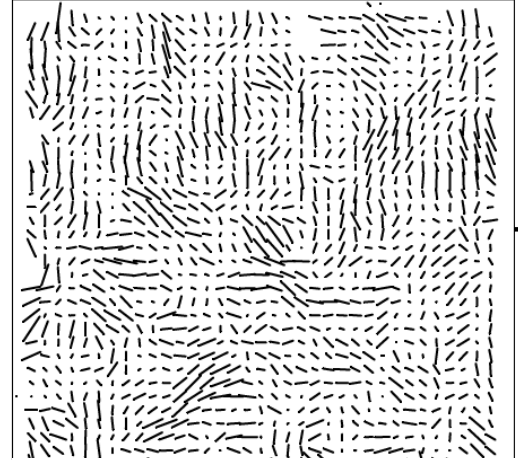
The weak lensing distortion is simply a (very small) change in ellipticity and position angle of a galaxy



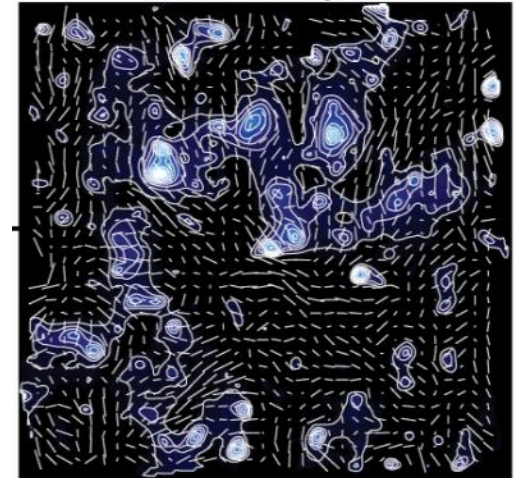
Shear Field



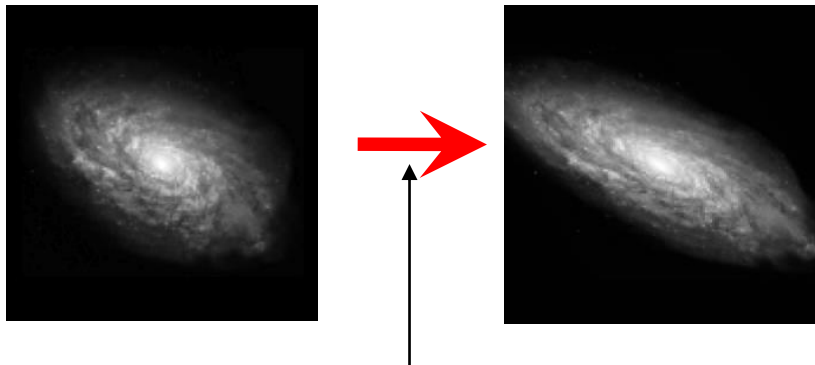
Direction and magnitude of mean shear (~100 galaxies per tick)



Reconstructed foreground mass distribution

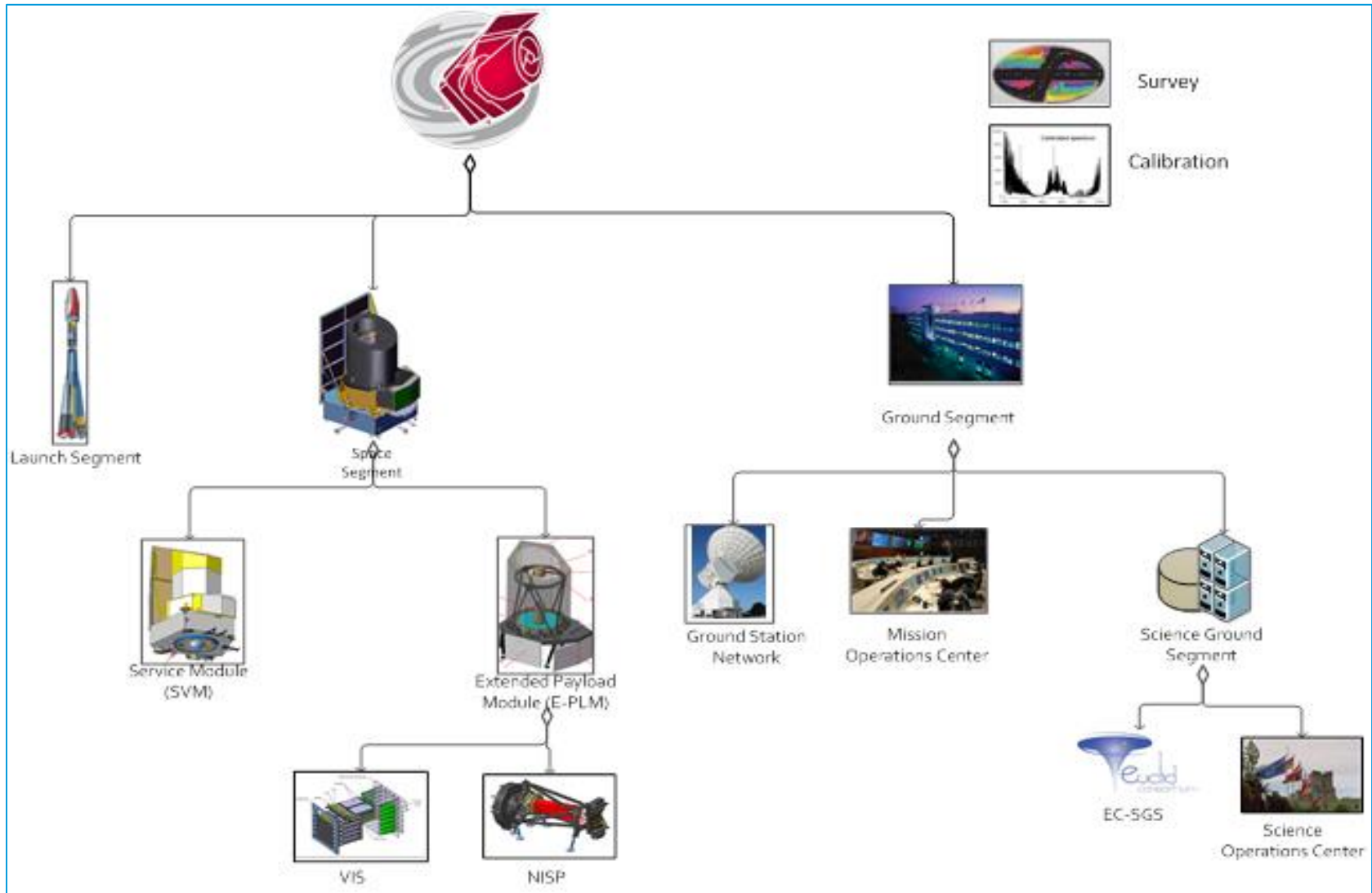


Matter distribution



Gravitational Lensing by Matter

Architectural complexity



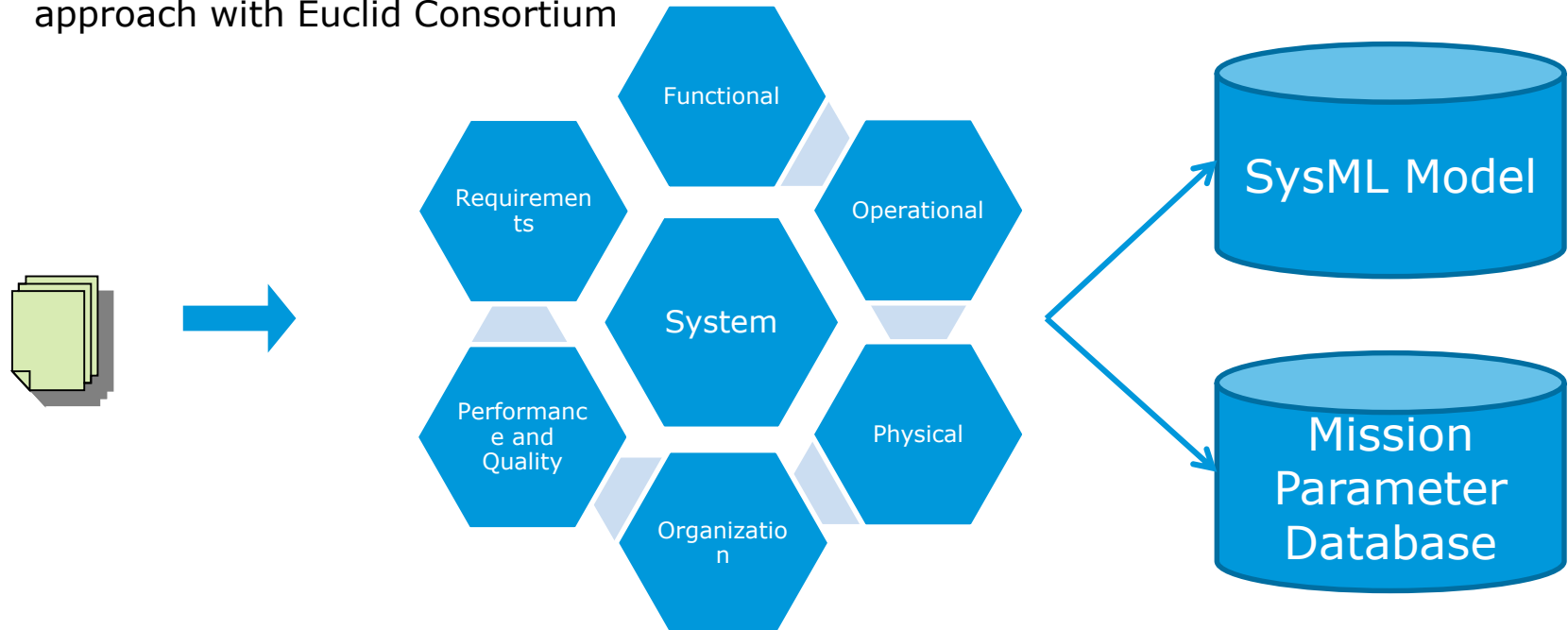
Organizational Complexity



- **Model Based System Engineering (MBSE) approach for Euclid**
 - Complex system and requirement interaction
 - Several actors in the system: ESA, Industry, NASA, large/distributed Euclid Consortium
 - Need to manage information exchange and control efficiently and coherently



- Decided to implement a Model Based System Engineering (MBSE) collaborative approach with Euclid Consortium





Methodology

- Language / Semantics: SysML, Euclid ontology
- Processes and guidelines



Tools and infrastructure

- Enterprise Architect ®, MySQL DB, WebServer
- Mission Parameter Database, DB Viewer, Integration



Modelling Scope / Patterns

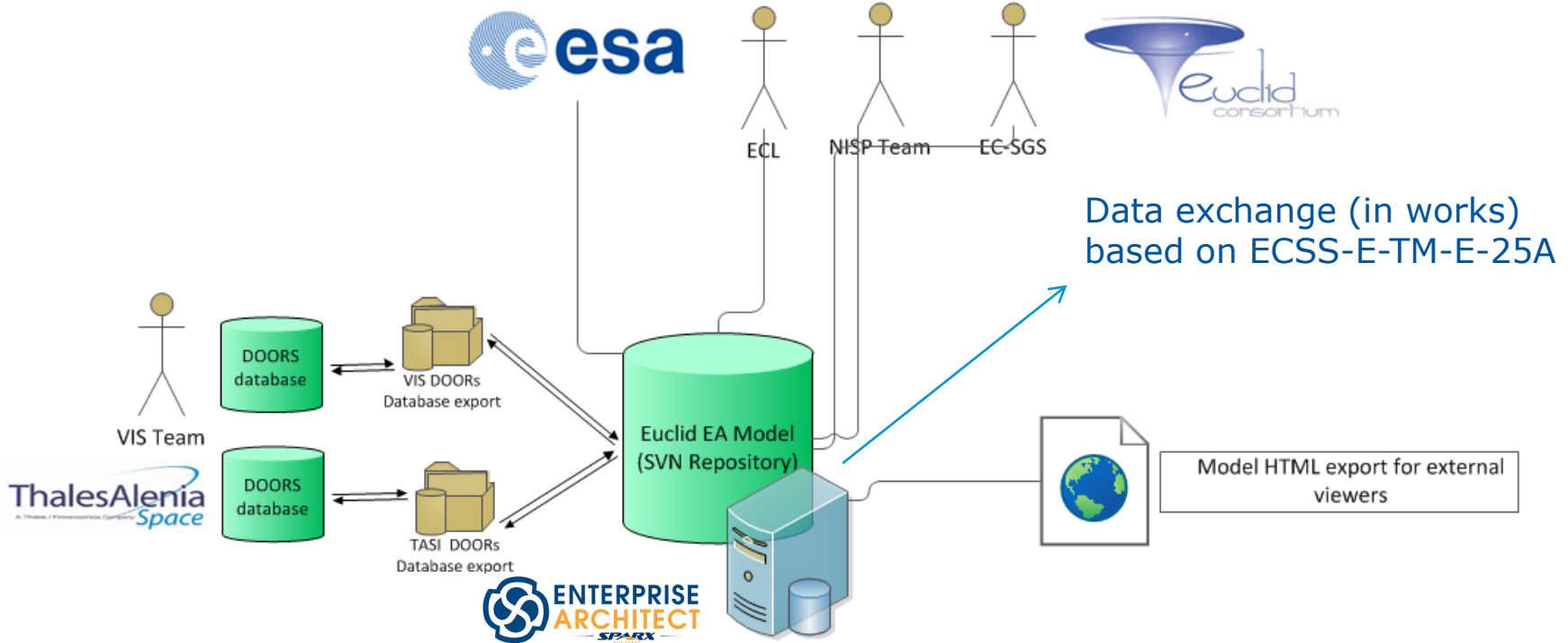
- What to model and too which level.
- Information to include in model.



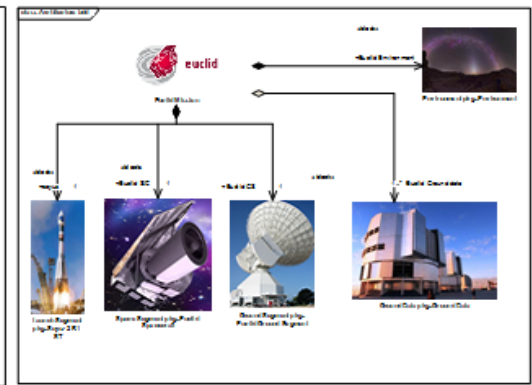
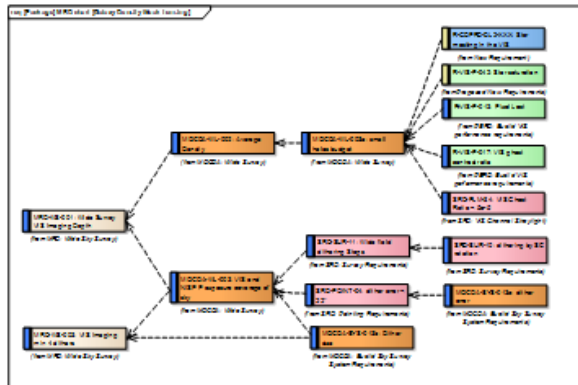
Views / Usability

- 'Hybrid' approach: Model vs document
- Dedicated created for different stakeholders

Euclid System Model deployment and collaboration



Data exchange (in works) based on ECSS-E-TM-E-25A



Consistent assumptions for all analysis, studies and software development: Mission Database (MDB):

- Contains performance parameters for all mission elements and inputs.
- Maintained by European Consortium. Viewers implemented by ESAC.
- Change controlled by CCB with Mission System Engineering Working Group members participation.



The screenshot shows the Euclid Mission Parameters Database interface. At the top, there is a banner with the Euclid logo and the text "euclid mission database" and the ESA logo. Below the banner, there are two buttons: "Collapse all" and "Expand all". On the left, there is a tree view showing the hierarchy of parameters. The "SpaceSegment" folder is expanded, showing sub-folders like "Instrument", "PLM", "PLMAsDesigned", "PLMAsRequired", "PLMAsSimulated", "PLMCurrentBestEstimate", "SVM", and "Survey". The "PLMAsDesigned" folder is further expanded, showing a file named "EUC-MDB-SpaceSegment-PLM-PLMAsDesigned_R-1.0.xml". On the right, there is a panel titled "Parameters from: EUC-MDB-SpaceSegment-PLM-PLMAsDesigned_R-1.0.xml". The selected parameter is "SpaceSegment.PLM.PLMAsDesigned.PLMTransmissionNISPMInMax". The panel displays the following information:

Description :	Transmission of the telescope in the NISP channel (including filter and transmission. The third column gives the maximum transmission.
Source :	Input by J.A. As Required. Non validated, for MDB testing
Release :	0.1
Validation:	

pkg Euclid Mission start page



Euclid Mission

Euclid Mission Model: This model is designed to support System Engineering activities.

It aims a containing the suitable information to ensure that the Euclid Mission is designed, built and verified to comply with its mission needs.



jerome.amiaux@cea.fr



Jose.Lorenzo.Alvarez@esa.int

double click on the icons to navigate.

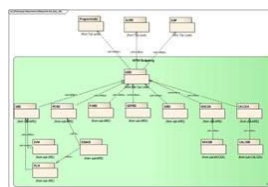
« allocate Activity Partition » Model Components



Actor

Actor package describe the different structure and key people contributing to the Euclid Mission.

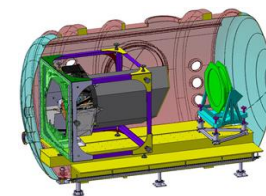
Status: preliminary



Requirement

Requirement package contains the requirement specification flow down from top level Science Requirements to implementation.

Status: Advanced



Verification

Verification package contains the test cases and verification approach description that allow verifying that current mission implementation meet the expected needs.

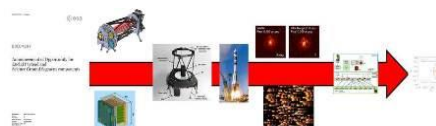
Status: empty



Architecture

Architecture package describe the design architecture of the mission, including the Mission product tree, the Mission environment and the Mission interface.

Status: advanced



Lifecycle

Lifecycle package contains description of the different steps in the life of the Euclid Mission from selection to scientific analysis of the processed data.

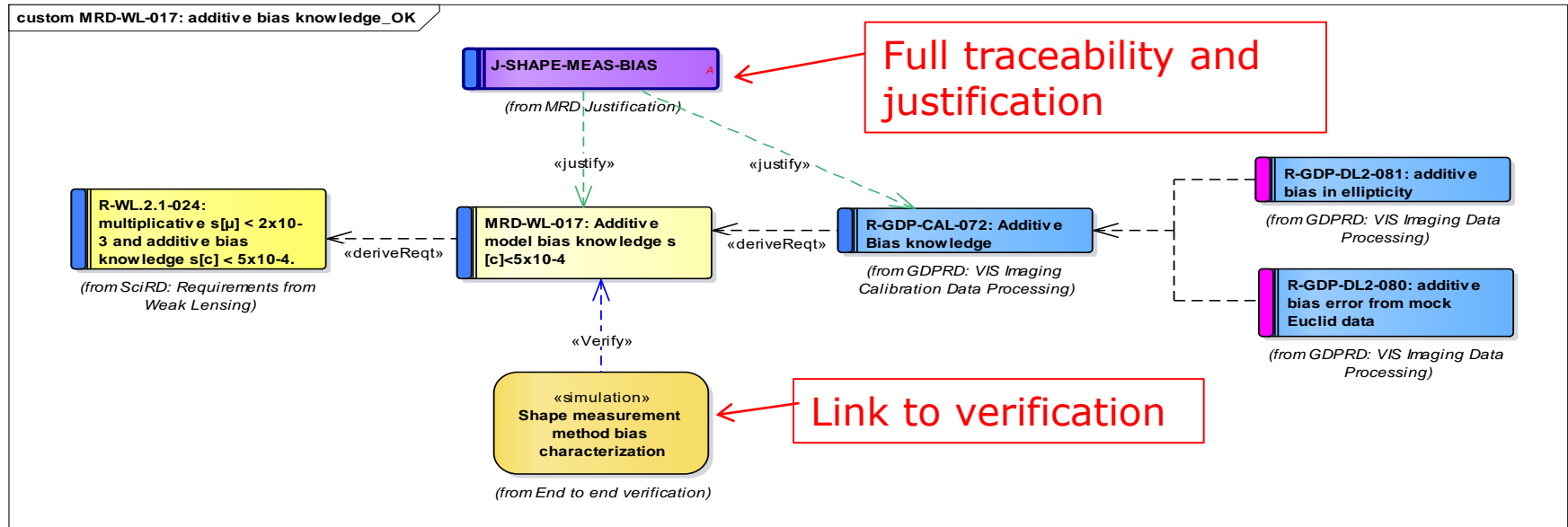
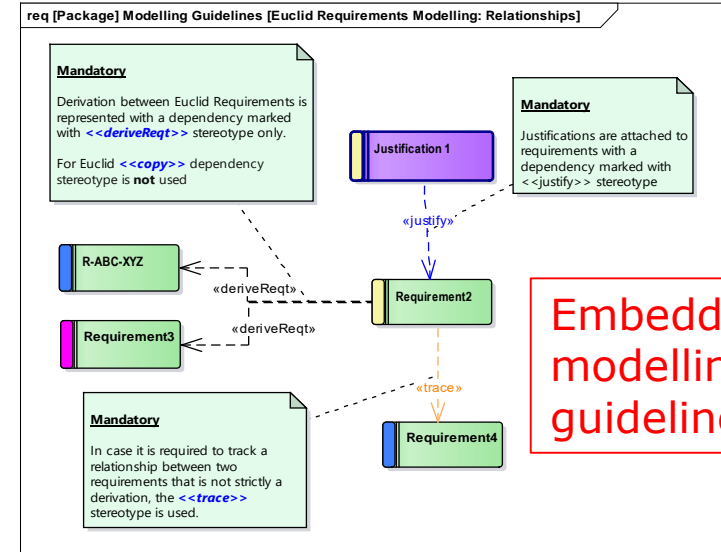
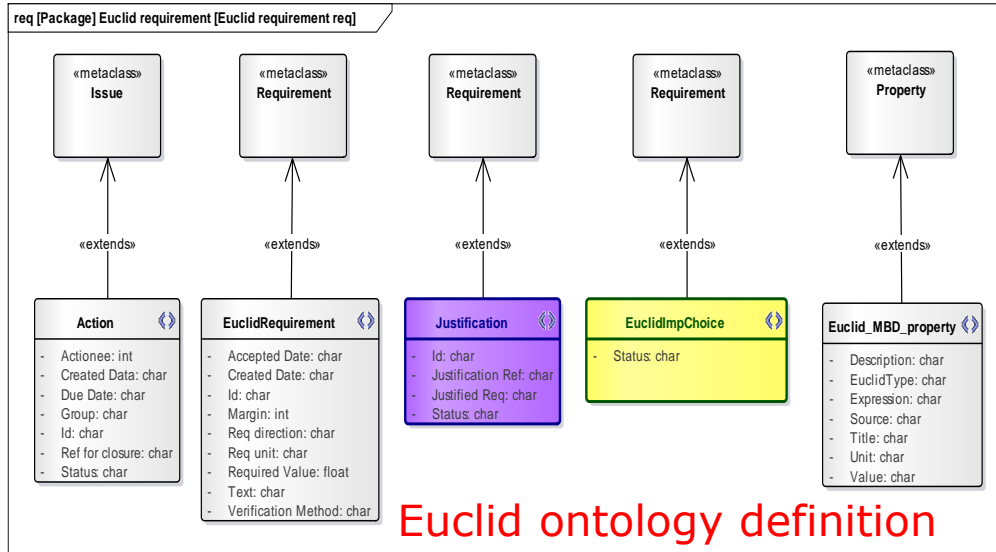
Status: empty



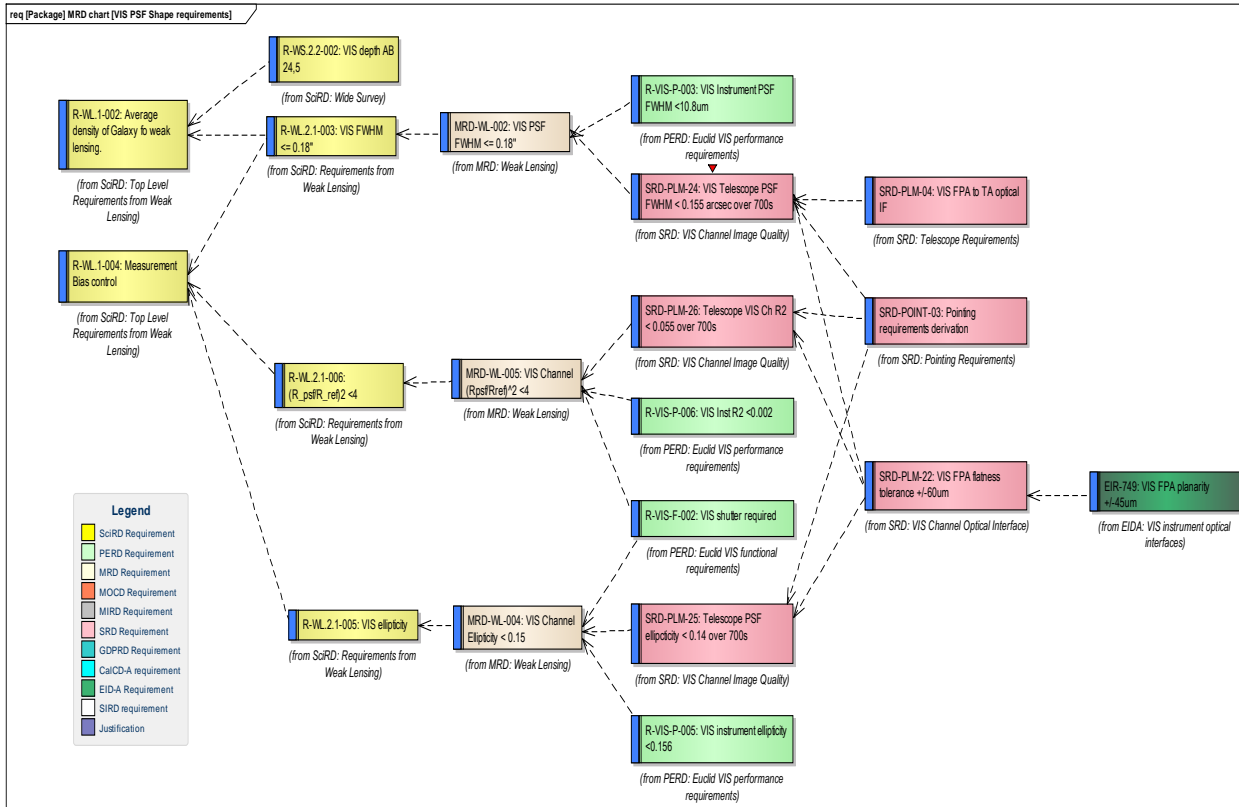
Model Library

Model Library contains reference definition, profiles and stereotypes used in the model.

Status: advanced

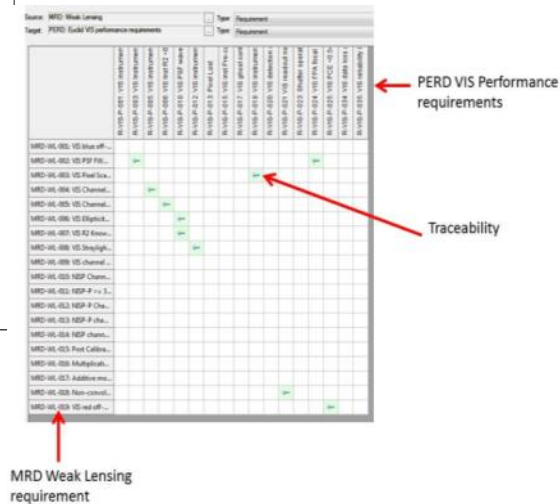


Maintenance and traceability



Generation of "Traditional" views provided in reviews:

- Reqs documents
- Traceability matrix
- Verification matrix
- ...

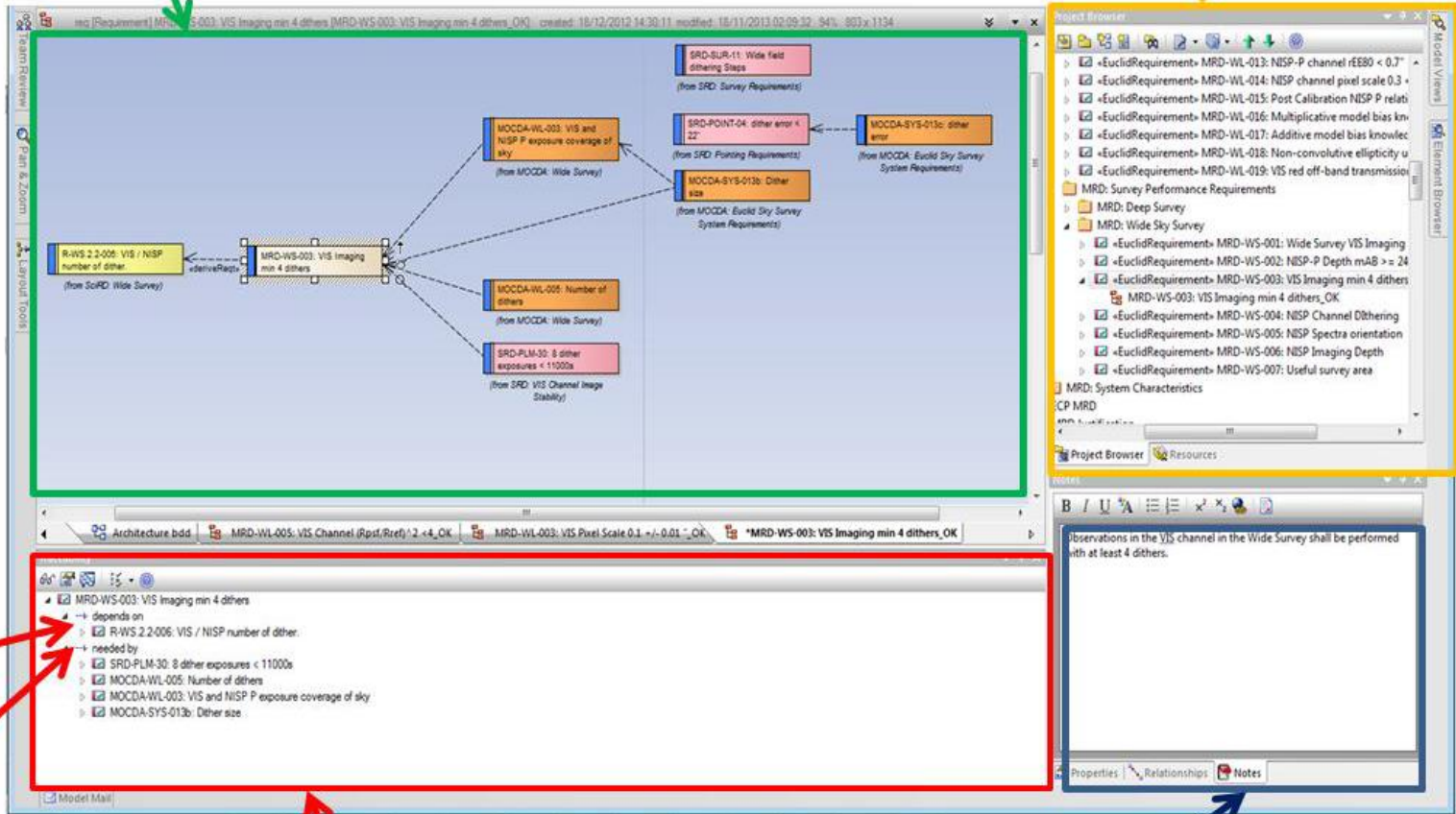


> From Euclid Mission Model: Example of requirements traceability and documentation.

Requirements modelling

Requirement Diagram view

Requirement browser



Up-link

Down-link

Traceability window

Req. text and properties window

- **Benefits:**

Start from Ops Concept at Phase A/B1 and systematic analysis of requirements and relationships:

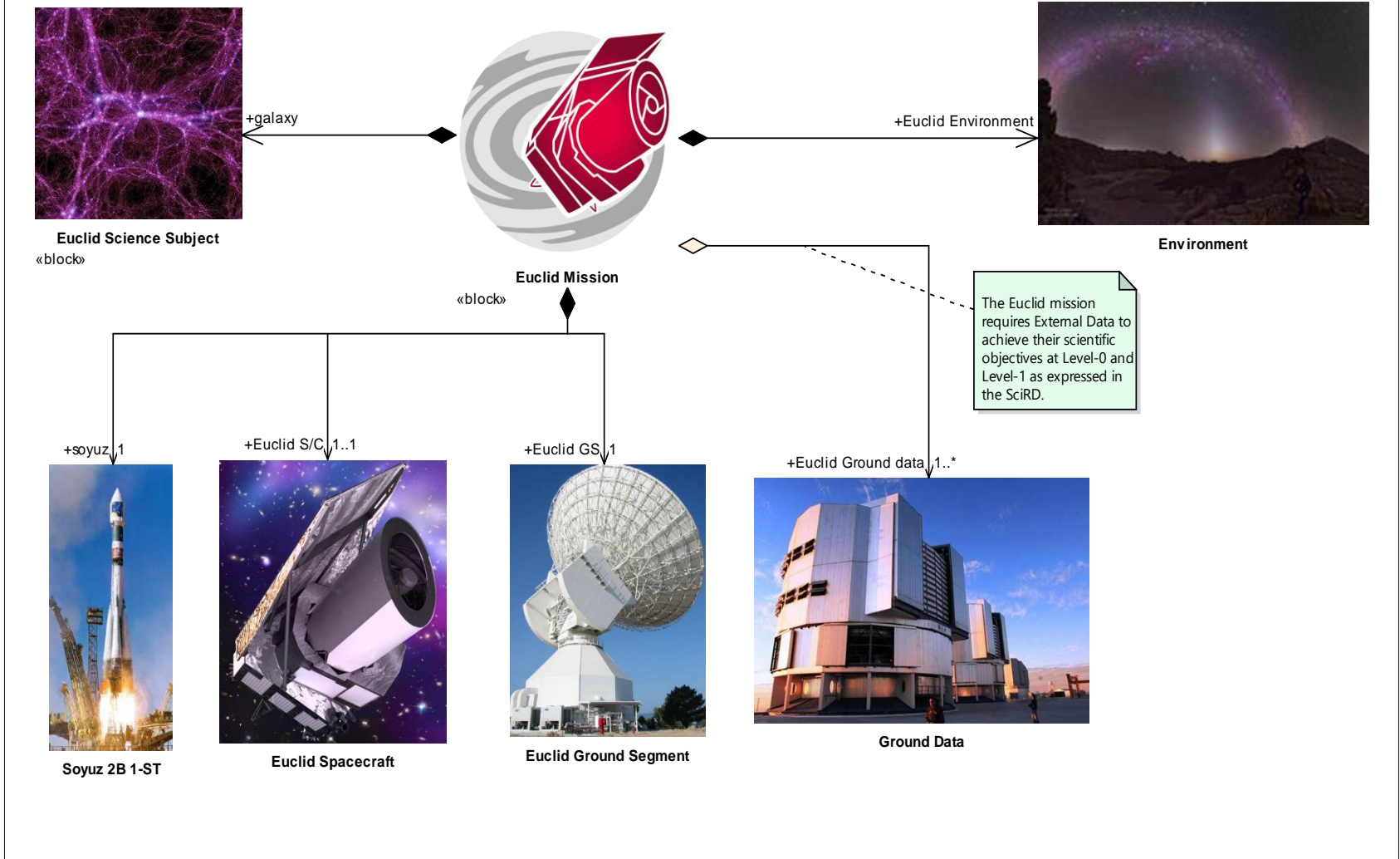
- Top level requirements reduced to 40 (from over 200...).
- Clearly differentiated needs from assumed architectural choices.
- Knowledge Management: Systematic documentation for justification for all requirements – central project knowledge
- Change Assessment: Quick and complete assessment of impact of changes to all levels. Change control processes driven by the model: annotated issues, request for changes, etc.
- Mission Requirements Review very successful.

- **Lessons learned / Open Work:**

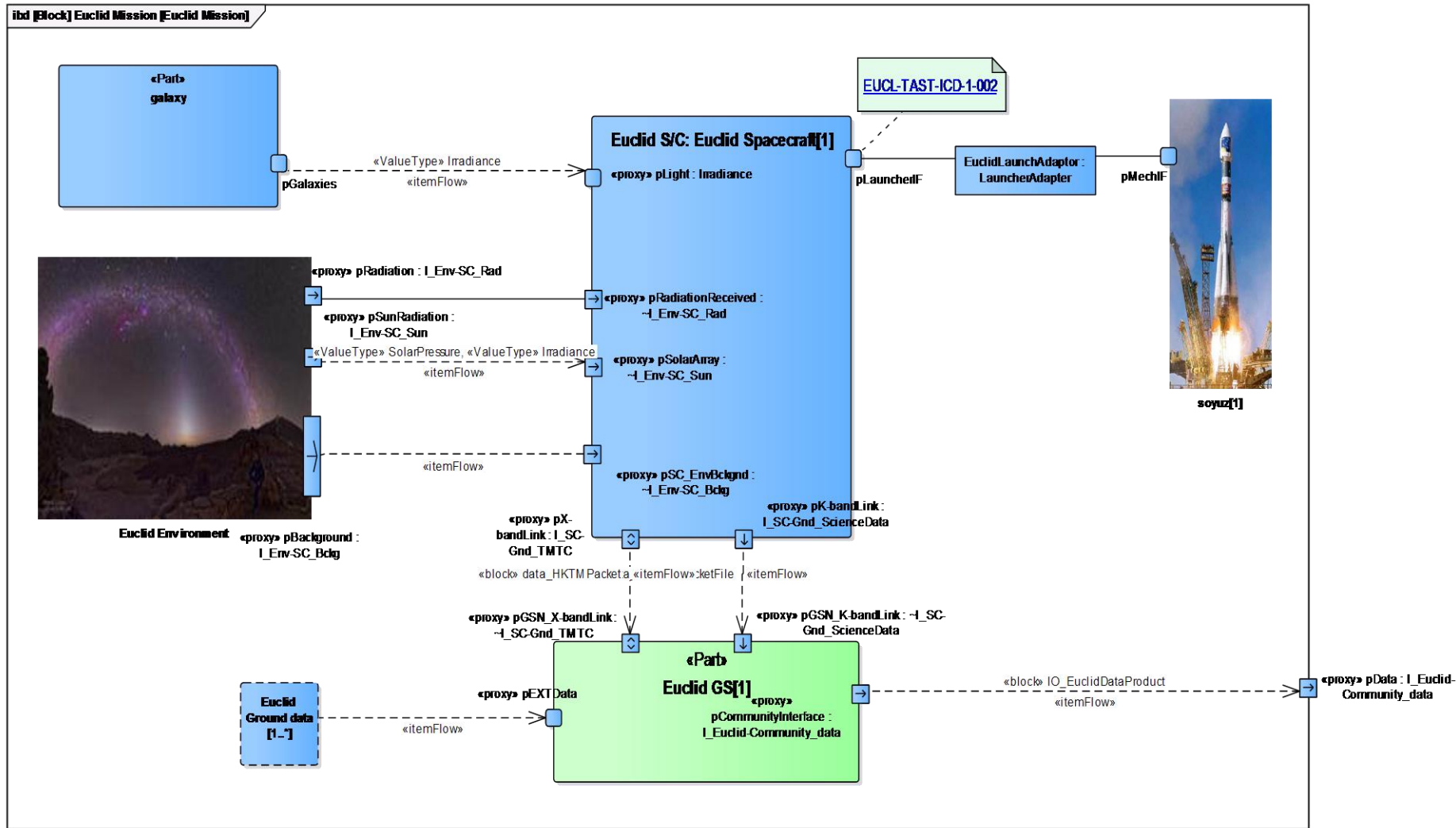
- Seamless with classic requirements management (DOORS): Easy import, difficult to maintain linkage. Tool issue.
- Need to establish **baselines** at regular time intervals for contractual reasons.

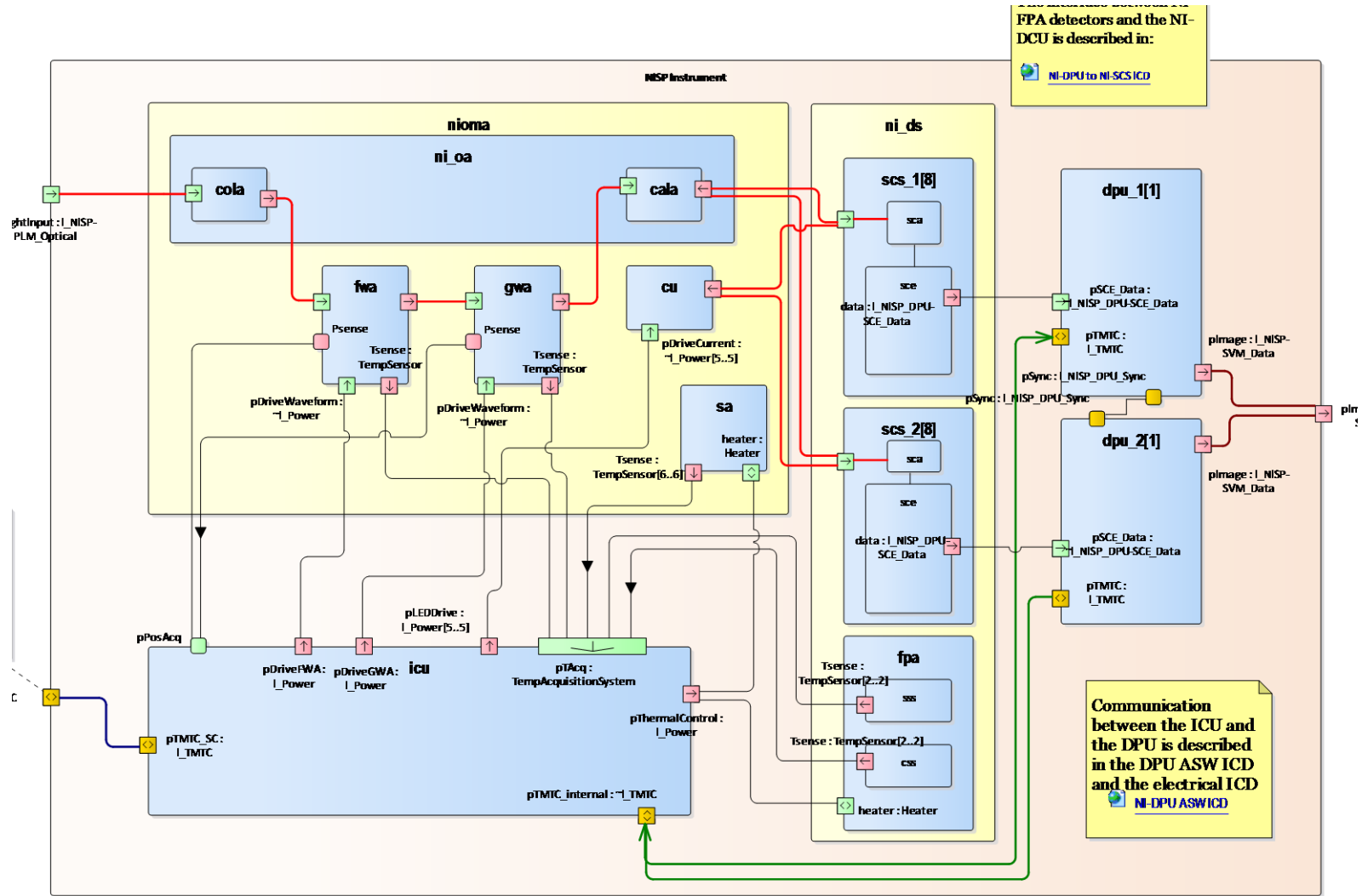
Architecture modelling

bdd [Package] Architecture [Euclid Mission Architecture]



Architecture modelling



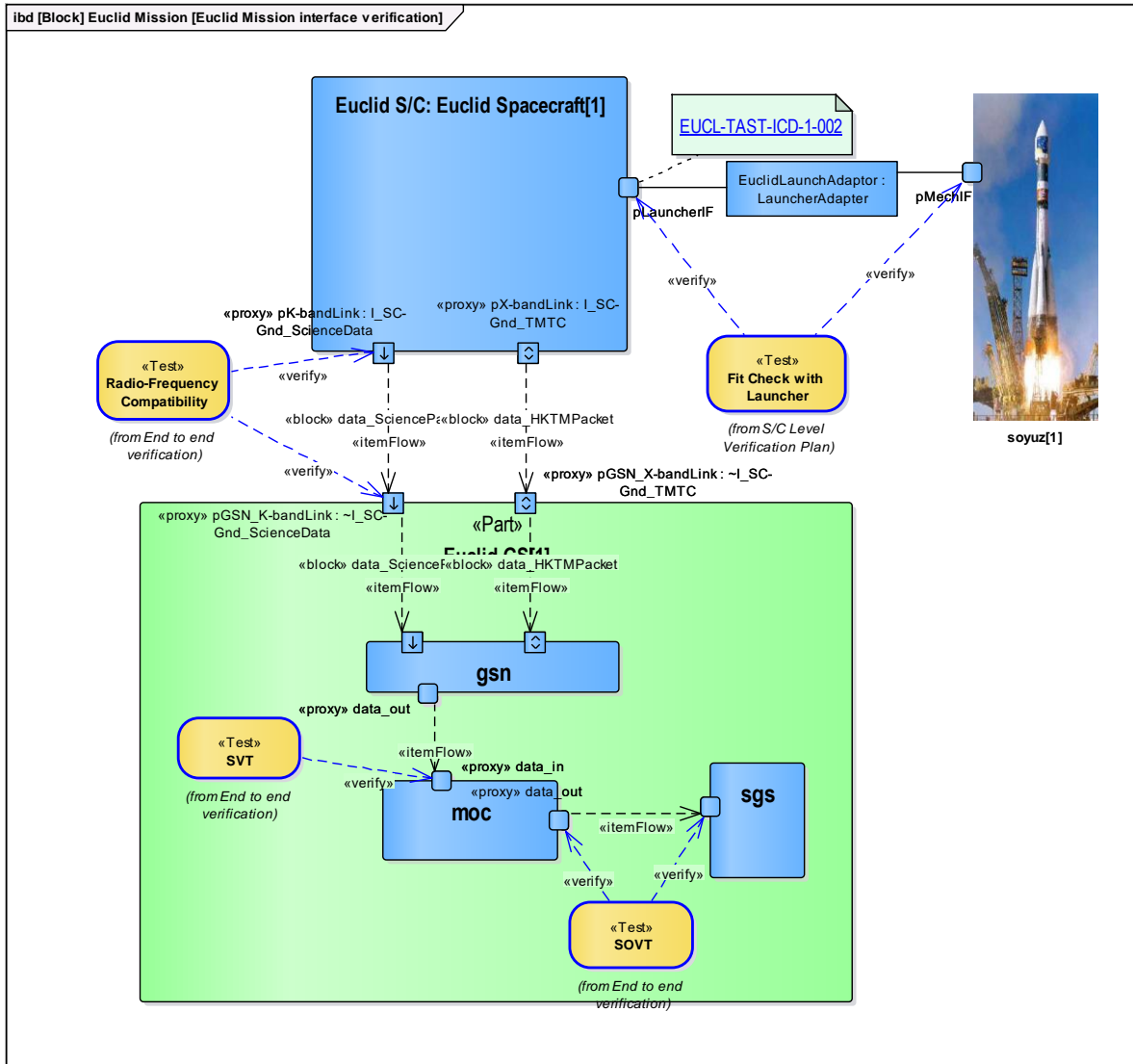


- **Benefits:**

- Systematic identification/definition of all interfaces.
- Coherent view of functions and allocation.
- Definition of clear blocks for reusability.
- Allows completeness in assessment of non nominal conditions and failures.

- **Lessons learned / Open Work:**

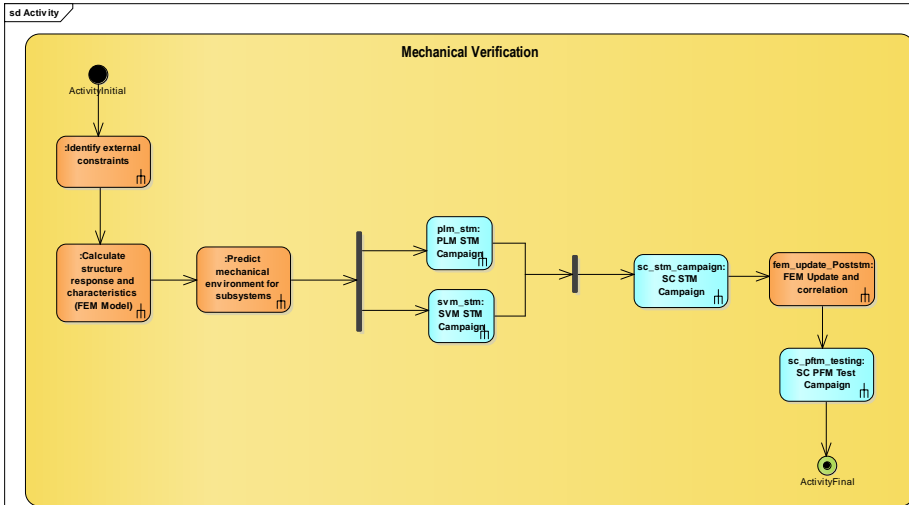
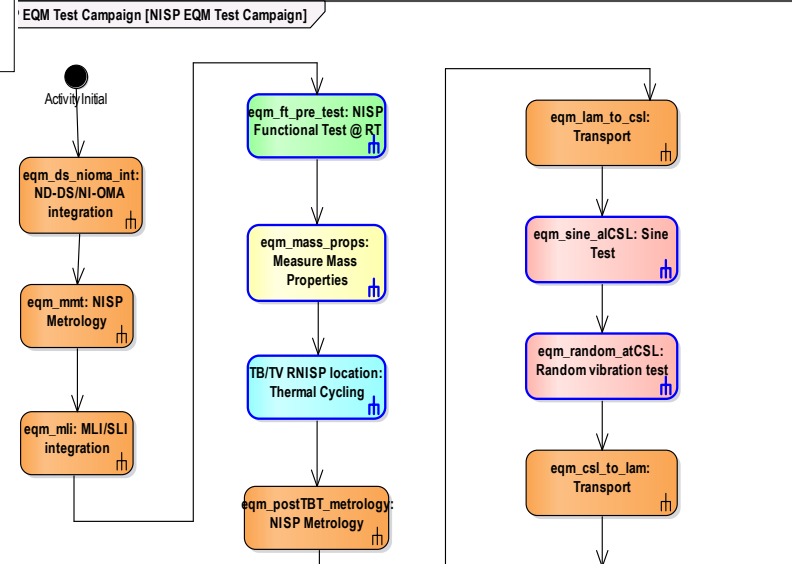
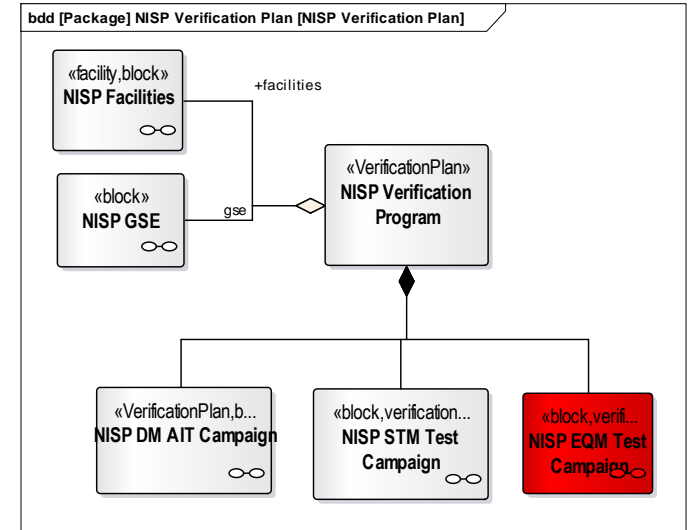
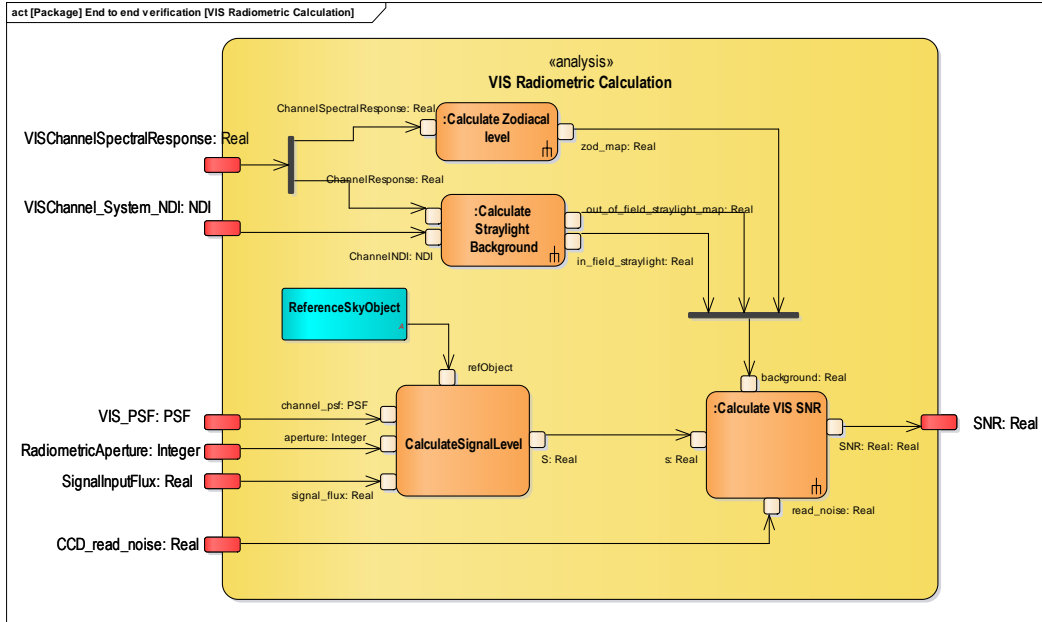
- Level of modelling: When to stop?
- Maintenance of history of changes and evolution for easy access, tracing of decisions for change.
- Modelling of variants: how to model trade-offs? -> Currently employing cloned branches of the model
- Interfaces modelling in SysML: Use of Ports and Association blocks still cumbersome. Association of requirements and behaviour to interfaces not immediate.

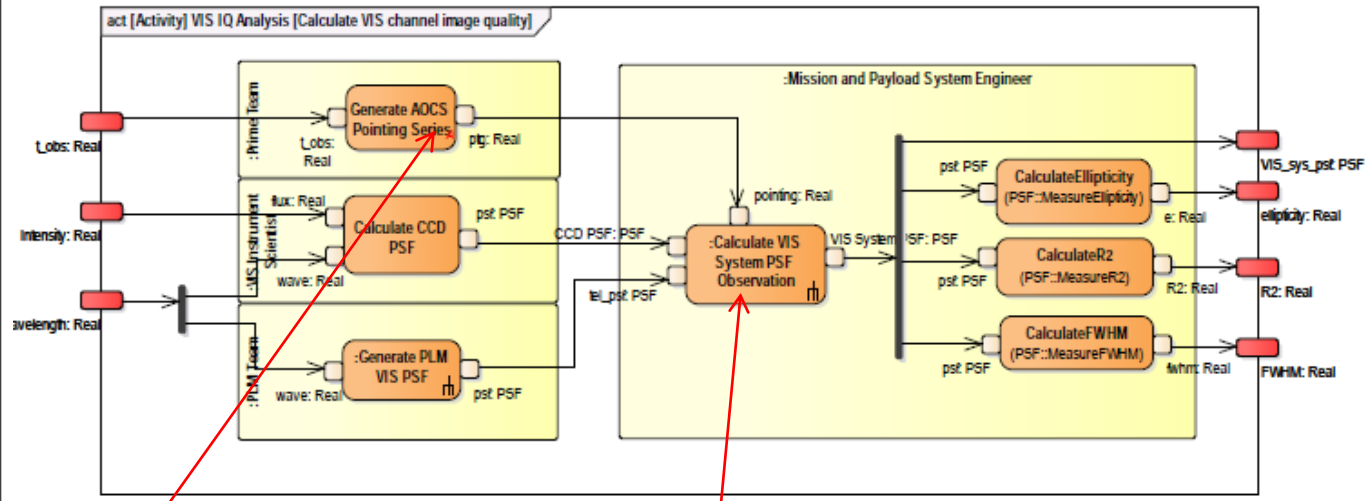
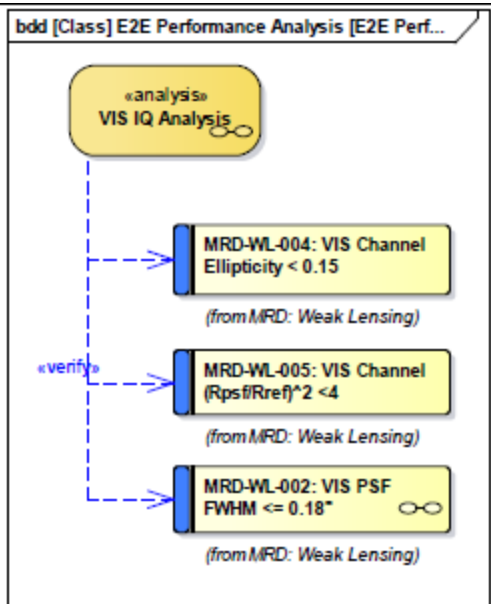


Systematic assignment of verification to interfaces.

Automated search allows to quickly identify gaps, progress in verification.

Verification modelling

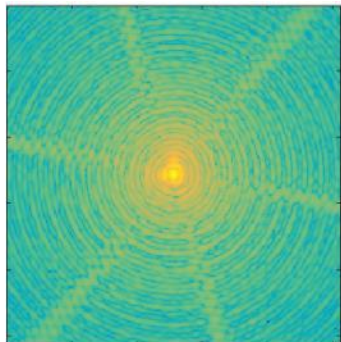




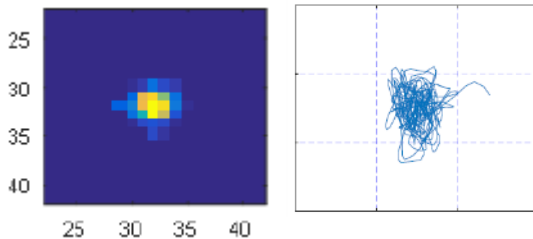
$$PSF_{system}(\theta_X, \theta_Y, \lambda, I) = PSF_{telescope}(\theta_X, \theta_Y, \lambda) * PSF_{instr}(\theta_X, \theta_Y, \lambda) * PSF_{aocs}(\theta_X, \theta_Y) * PSF_{detector}(\lambda, I)$$

$$FWHM_y(l, I) = \frac{a_{Int1y} + b_{Int1y} \times Int}{a_{Int1y} + b_{Int1y} \times Int_0} \times a_{lambda1y} \times |b_{lambda1y}|$$

$$FWHM_y(l, I) = \frac{a_{Int1y} + b_{Int1y} \times Int}{a_{Int1y} + b_{Int1y} \times Int_0} \times a_{lambda1y} \times |b_{lambda1y}|$$



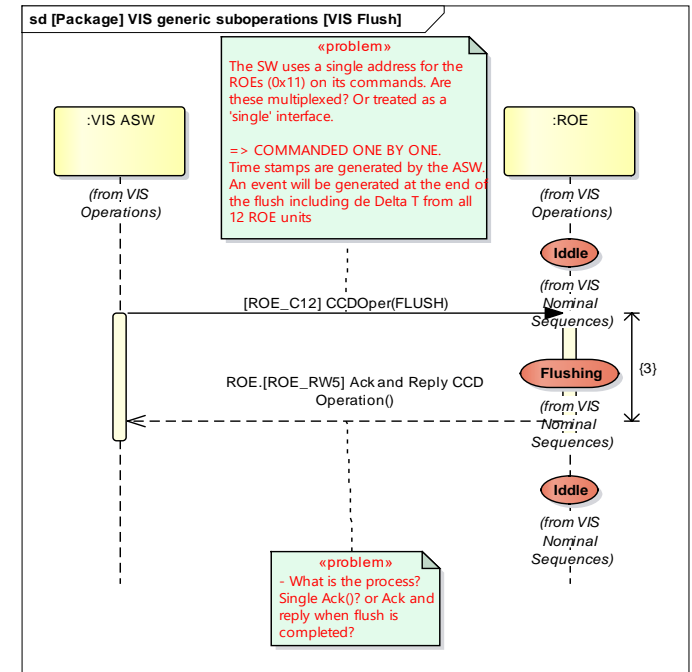
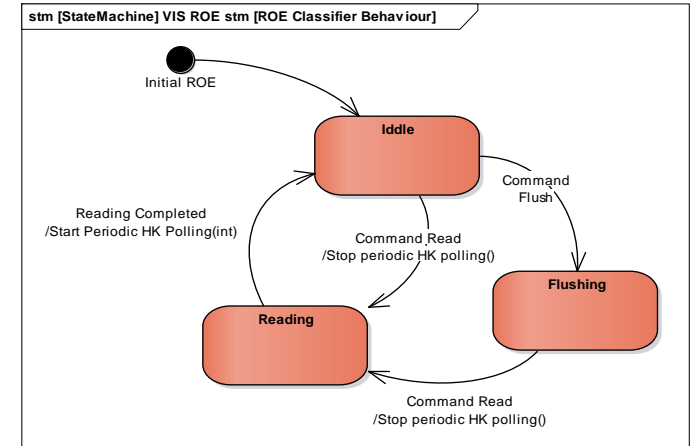
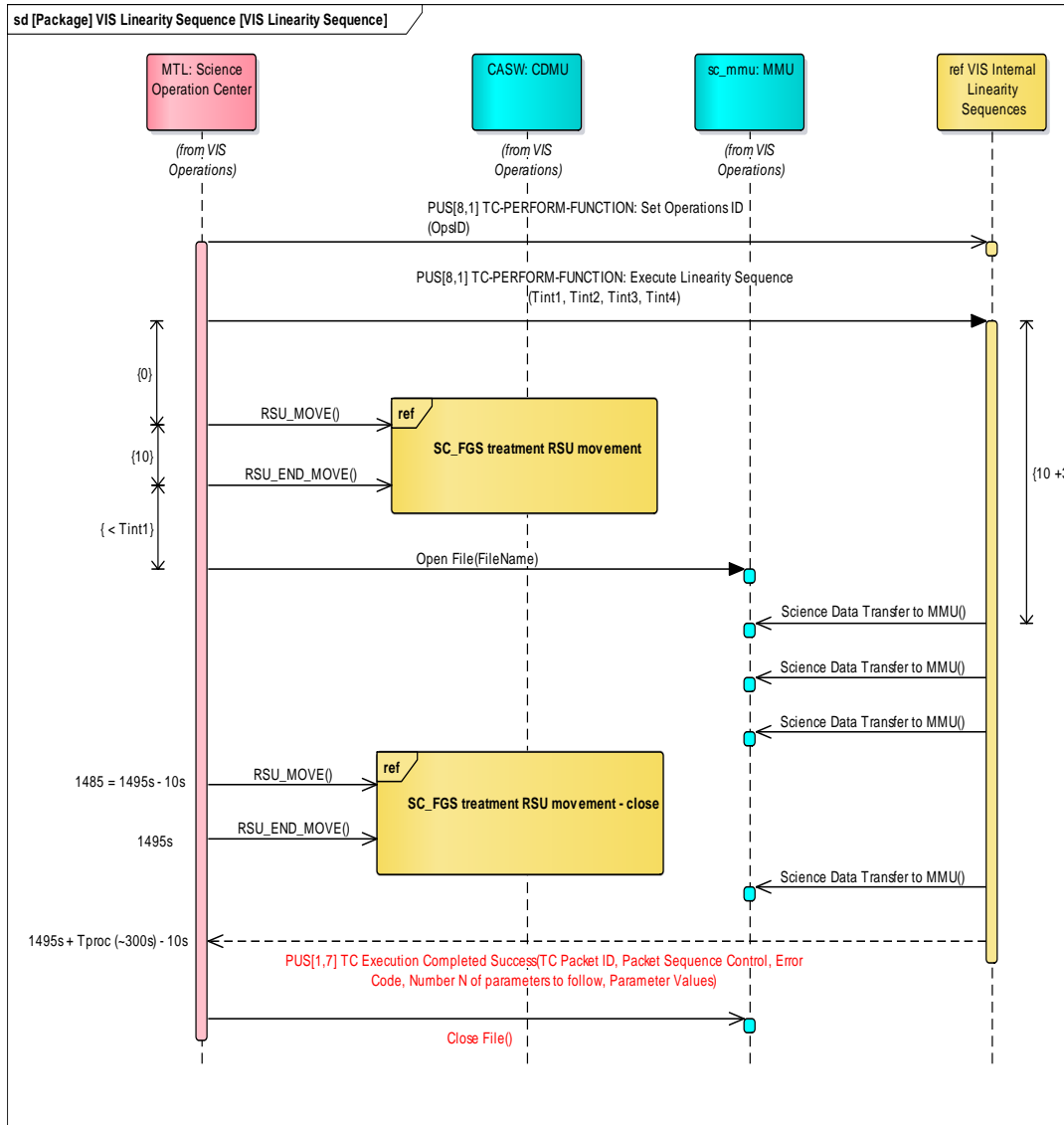
Telescope PSF
(9 field points,
4μm sampling)

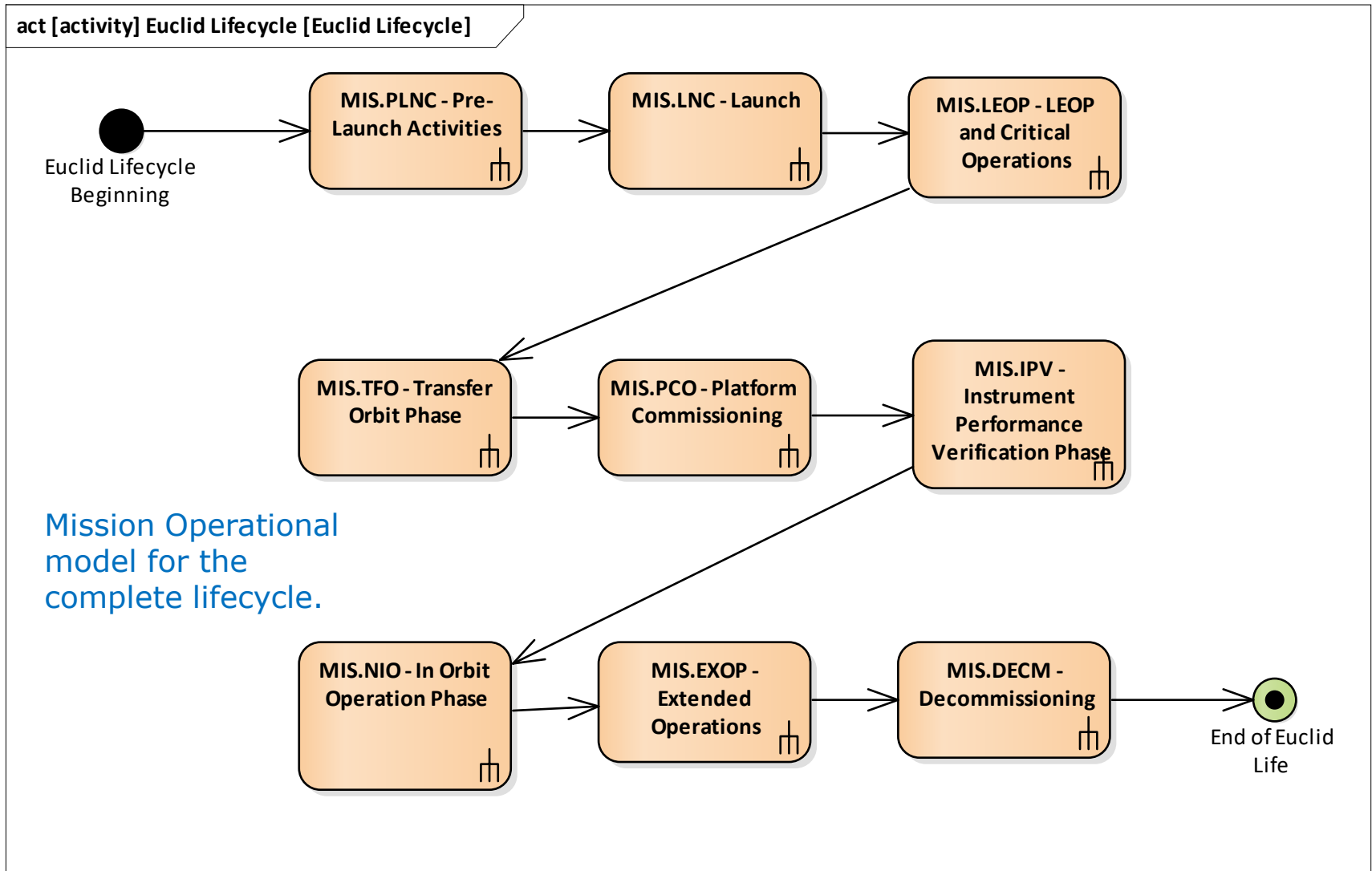


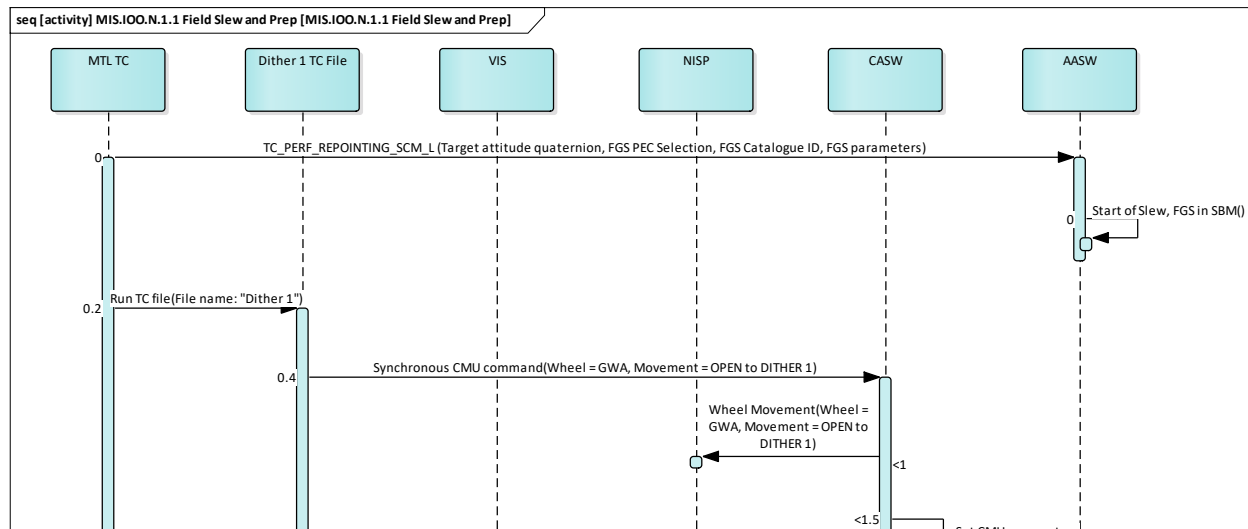
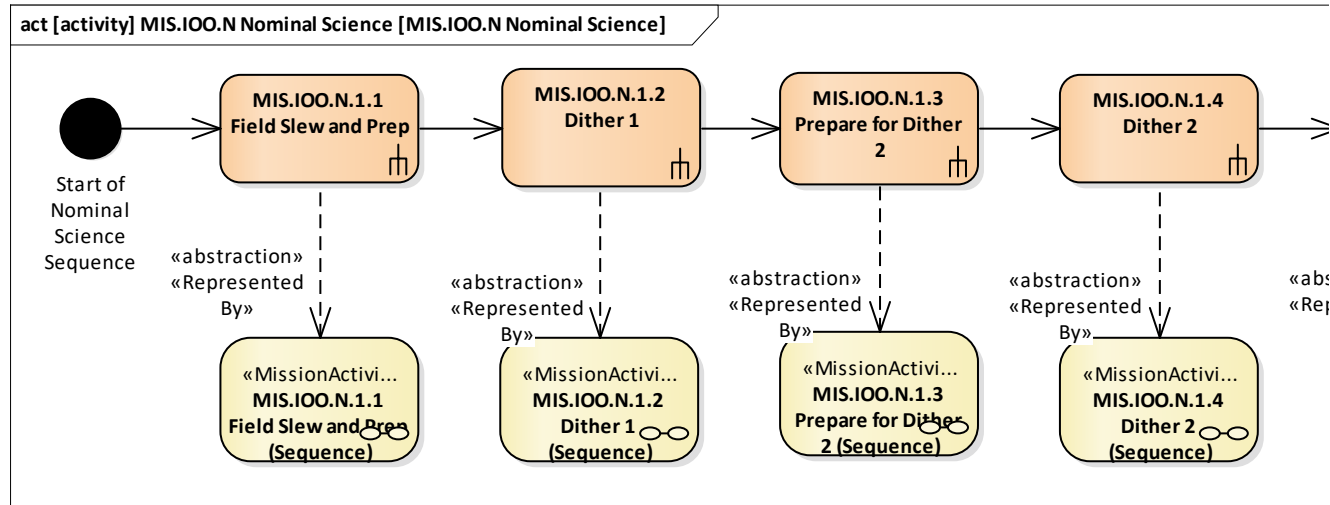
AOCs PSF

Mission verification tasks are linked to expressions or requirements that are implemented in code. **No automation, just representation in SysML Model.**

Inputs, products and processing functions maintained in **Mission Parameters Database**







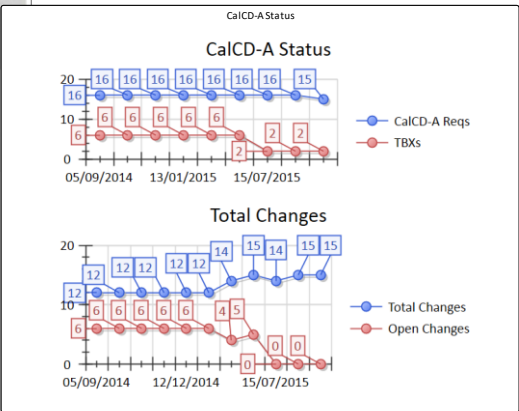
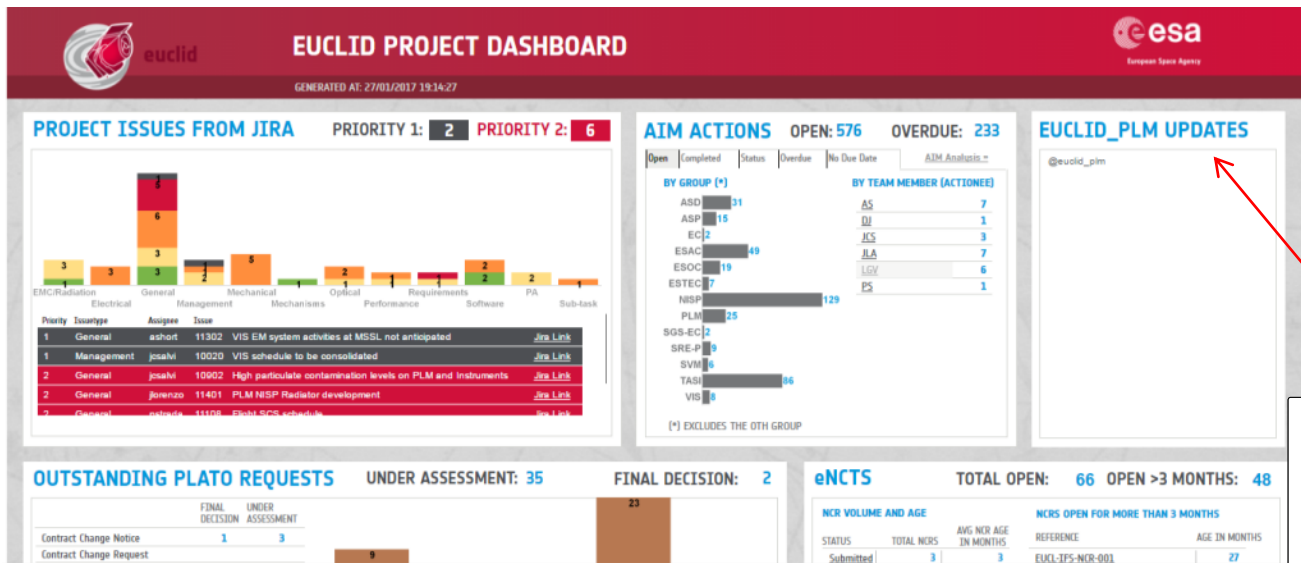
- **Benefits:**

- Completeness of verification by full coverage check of requirements (incl. functions) and interfaces.
- Identification of common/repeated tasks: better use of synergies between analysis and tests, reducing duplication and optimizing flow.
- Key for communication between different players to develop verification plans:
 - Commonly agreed analysis flows, sequences, etc instead of documents.

- **Lessons learned / Open Work:**

- Integration of model with operations and science operations groups models: currently separate activities
- Link with verification results: currently we link to test, analysis reports. Appropriate for the use in Euclid. For future missions it should be incorporated in System Knowledge Database.


- SysML model is in essence a DB with object and connections between them.
 - Knowledge of the semantics allows custom searches and visualizations (both in tool or with external data display applications)
 - Integration into generic project Dashboards:



Currently working on integration of model metrics into system Management Dashboard

Dedicated views created for reviews in HTML, integrating model and the traditional document based ESA review process

NISP Instrument Control Unit (NI-ICU) Summary View



The NI-ICU handles all the NISP control functionalities, and interfaces the NISP instrument to the S/C control system for TM&TC tasks.

- Exchanges TM&TC data with the NI-DPU using a dedicated intra-instrument interface.
- Provides the control electronics for the NI-FWA, the NI-GWA and the NI-CU.
- It is responsible for the monitoring of the NI-OMADA temperature sensors and powering the heaters, and it maintains HK data of the NISP warm electronics (NI-WE).

The NI-ICU generates the secondary power supplies which are needed to perform all these functions except from the DPU-DCU, whose main power supply and secondary power needs are self-provided

Requirements

- [NI-ICU Requirement Spec](#)
- [NI-ICU VCD](#)

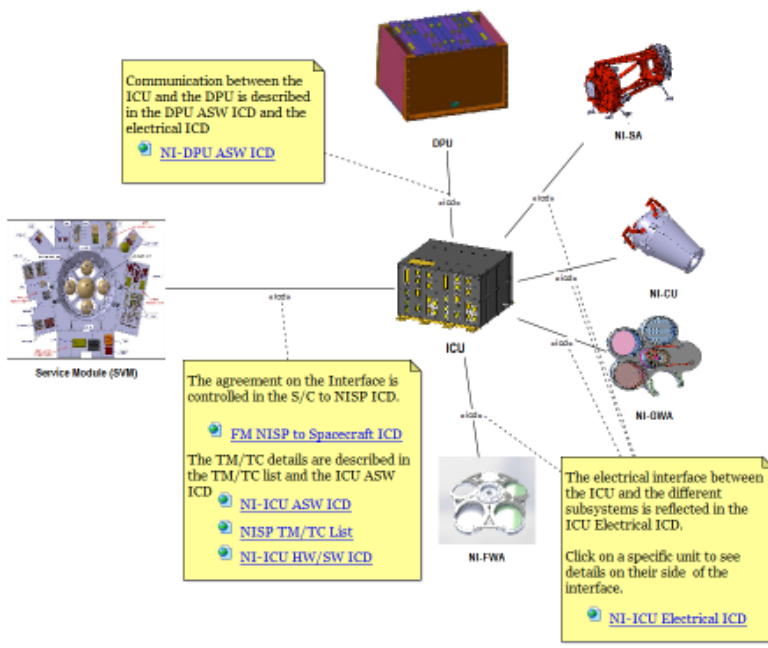
Design

- [NI-ICU Design Definition Document](#)
- [NI-ICU ASW Design Definition Document](#)
- [NI-ICU Design Justification File](#)

Relevant Analysis

- [NI-ICU Worst Case Analysis](#)
- [NI-ICU Radiation Analysis](#)
- [ICU HW / Boot SW and ASW Integration Report](#)
- [Preliminary Tests on ICU-DPU Communication](#)

Interfaces



Communication between the ICU and the DPU is described in the DPU ASW ICD and the electrical ICD

- [NI-DPU ASW ICD](#)

The agreement on the Interface is controlled in the S/C to NISP ICD.

- [FM NISP to Spacecraft ICD](#)


The TM/TC details are described in the TM/TC list and the ICU ASW ICD


- [NI-ICU ASW ICD](#)
- [NISP TM/TC List](#)
- [NI-ICU HW/SW ICD](#)

The electrical interface between the ICU and the different subsystems is reflected in the ICU Electrical ICD.

Click on a specific unit to see details on their side of the interface.

- [NI-ICU Electrical ICD](#)





- *Use modeling as Systems Thinking "lighthouse"*
- *Define and document a clear modeling approach*
- *Start early: Phase A/B1*
- *Identify to what level is necessary to model*
- *Facilitate Sharing and usage: Observers don't want to know you have a 'model'*

Thanks!