

Automotive Software Systems Complexity: Challenges and Opportunities



INCOSE International Workshop

MBSE Workshop
January 26th-28th, 2013

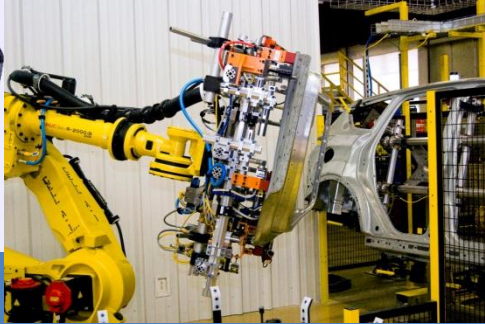
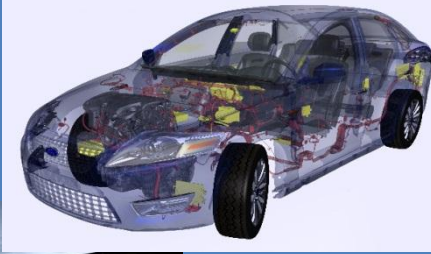


Christopher Davey
Senior Technical Leader
Software & Control Systems Engineering
Global EE Systems Engineering Group
Ford Motor Company



- 1. Ford Motor Company & EE Systems**
- 2. Automotive EE & Software Complexity Challenge and Opportunity**
- 3. A Paradigm Shift: Fully Integrated Systems Engineering**
 - 1. MBSE**
 - 2. Model Based Architectures**
 - 3. Why, When, Where & How**
- 4. Model, Information, Intellectual property re-use: The need for enterprise wide - PLM/ALM Solution**
- 5. Lessons Learned so far.....**

Ford Motor Company



- All Photographs are courtesy of Ford Motor Company

Why do we need all these software Systems?

Past

Present

Future

Propulsion Systems



CARBURETTOR



**HIGH EFF.
FUEL INJ.**



ADVANCED HYBRID/ELECTRIC

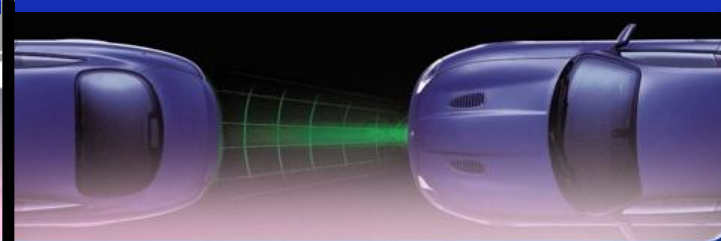
Safety & Accident Prevention



AIRBAGS



**LANE
DETECTION**



AUTONOMOUS DRIVING

Human Machine Interface



RADIO



**TOUCH
SCREEN**



MOTION SENSITIVE CONTROL

- **Technology Progression leverages Vehicle Software & Control Systems -> Proliferation**

Properties of EE Software Systems



*Courtesy of NASA

Space Shuttle (Ref. 1)

- 5 Computers on board
- 700 kByte Software
- 500.000 LOC/Instructions



*Courtesy of Boeing

Boeing 777 (Ref. 2)

- Approx. 3 Million LOC

*Ref: Les Hatton

Enhanced Vehicle Software and Electrical Management

Capabilities are required to maintain the

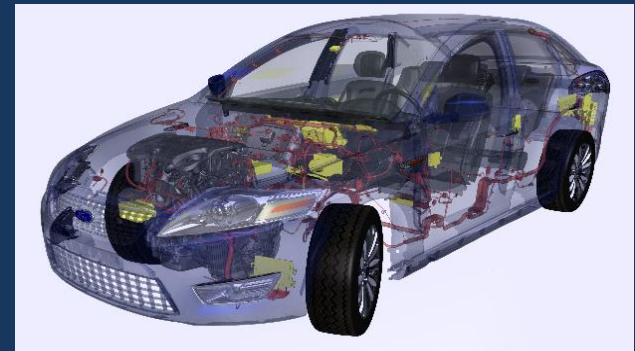
Robustness and Quality

of Electrical Hardware Software and Control Systems

as

Feature Quantity & Complexity Grows

- > 80% of new features are Software enabled EE systems.
- > 70% of new systems are distributed in nature



CD Class Vehicle has approx.

- 50-70 Computers on board with multi-core SW process management
- > 10 MByte of Control Software
- >15 Million LOC/Instructions
- > 5,000 Software Parameters
- > 50,000 functional requirements
- > 1,000,000 pages of specifications
- > 10,000 buildable Vehicle-Series-Variants (based on ECU component permutations per Vehicle line)

⇒ In some aspects a CD class vehicle has higher system, software and build complexity than a commercial aircraft....

General Trends in Vehicle Electronics

E/E Content

Electrical Design focus is now on
Feature/Functional interaction
 Complexity of software
 Relationships and
 Development of
Cross domain requirements
 – Feature focused

Electrical Design focus was
 on **power Distribution and**
packaging-
Component Focused with local
integrations

Vehicle-to-Vehicle; Service; Web-Connectivity

E-Connectivity

Off-Board Communication
 & Connectedness

Consumer
 Electroic Devices
 Sync Module

Remote
 Diagnostics

Adaptive
 Headlamps

Higher Power
 Requirements

LSG

In Car PC

ACC

El. Water
 Pump

Infotainment

Software

EPAS

EM Valves

Telematics

PTC Heater

IVDC

ESP

Displays

Steer-by-
 Wire

Airbag

PA

Drive-by-Wire

Blind Spot
 Detection

Networking
 CAN, MOST, etc.

Body Elec.

Brake-by-
 Wire

ABS

Adv.
 Restraints

ASM

Keyless
 Vehicle

Fuel Cell

Cluster

P/T Electronics

1880

1980

1990

2000

2010

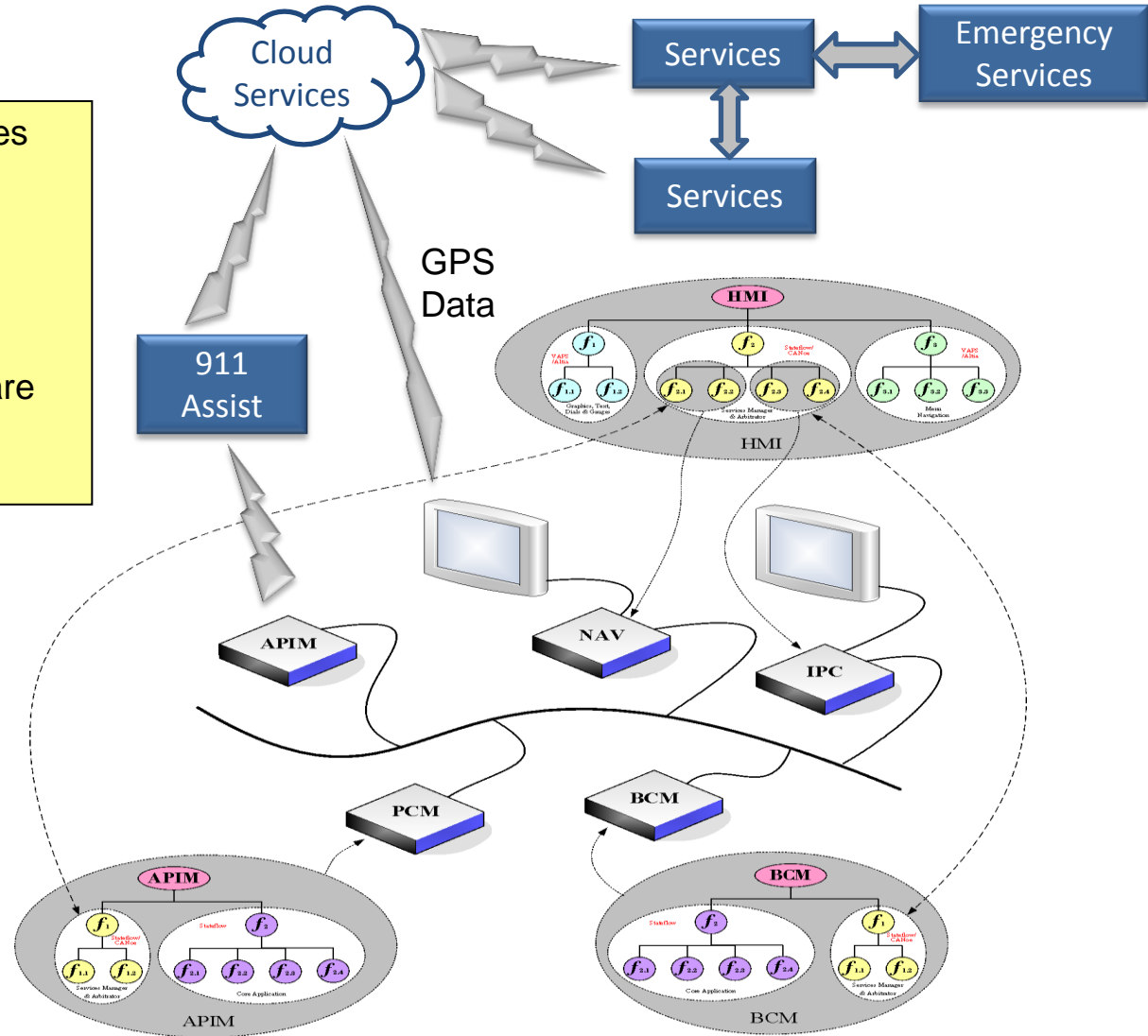
CY

HMI and Off-board Distributed Functionality

Human Machine Interface & Off-board services example

- Delivery of customer features requires the coordinated execution of multiple modules exchanging signals both wirelessly and over a number of multiplexed networks.
- >70% of all new customer features are software enabled and distributed in nature.

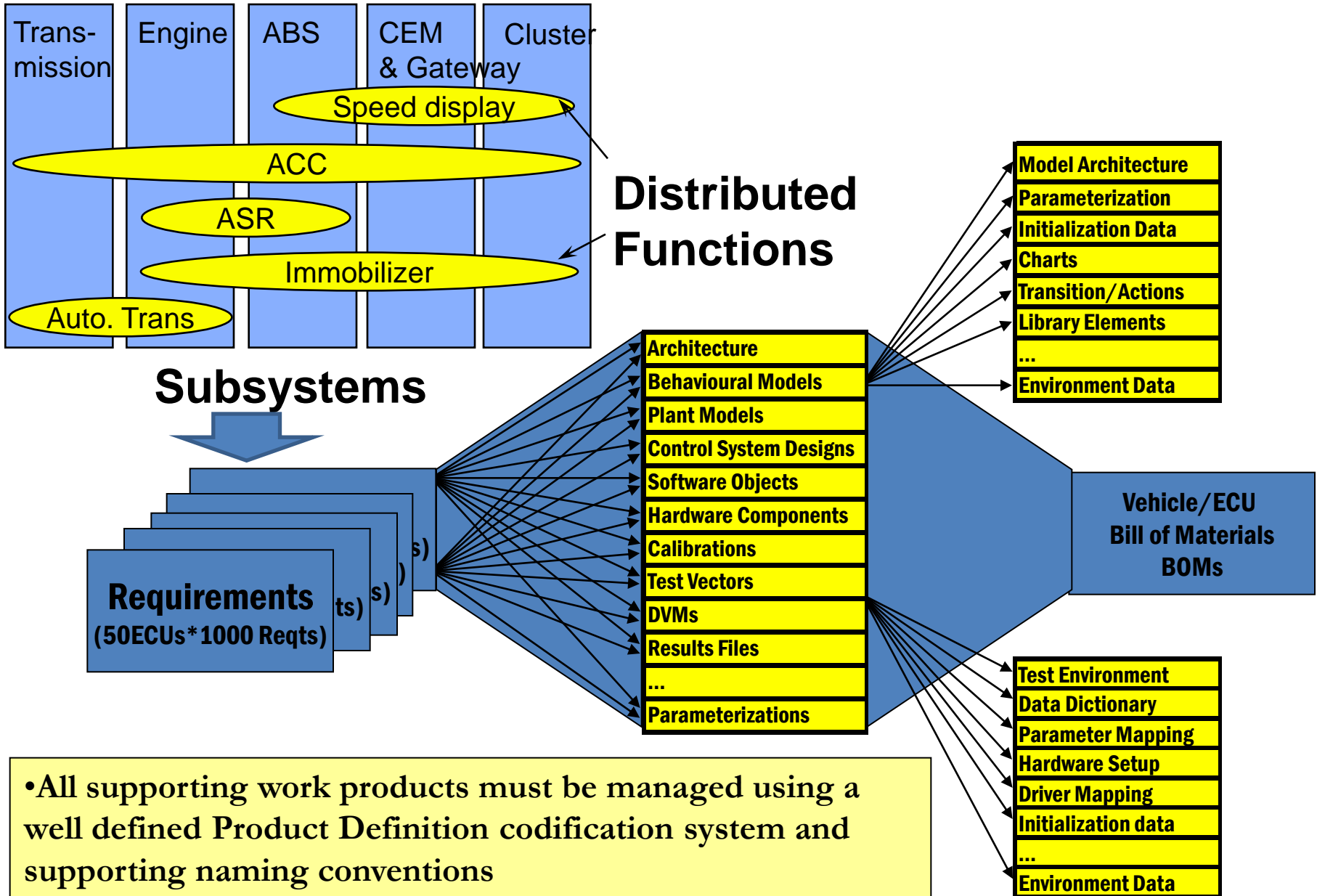
- Service Oriented Architectures (SOA) and well defined functional/software architectures are required to deliver efficient coordination between modules.



APIM – Sync Module
IPC – Instrument Cluster

NAV – Navigation Unit
BCM - Body Control Module
PCM – Power Train Control Module

Complex Mapping of CTQ Work products

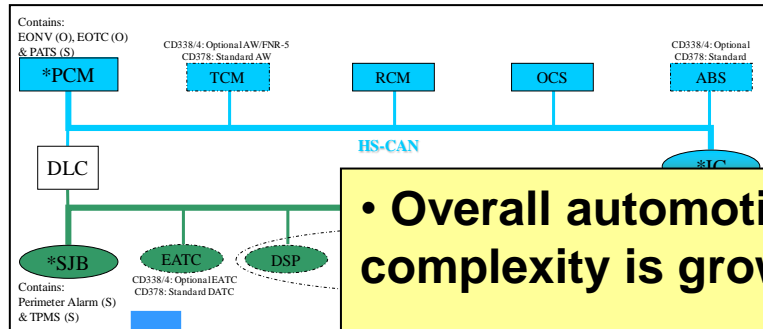


•All supporting work products must be managed using a well defined Product Definition codification system and supporting naming conventions

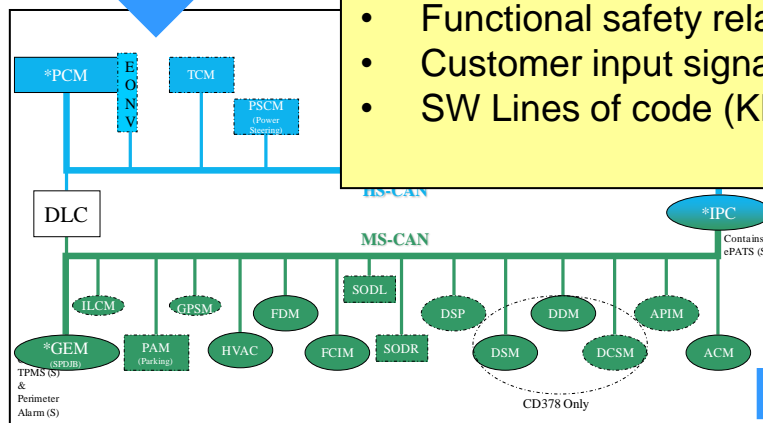
Example Vehicle Electrical System Growth

	Networked ECU [#]	Signals [#]	Software Lines of Code [#]
MY2006	10 - 15	200 - 300	~ 3 Million
MY2010	20 - 30	1000 - 1500	~ 10 Million
MY2012+	50 - 70	3000 - 4000	~15 Million

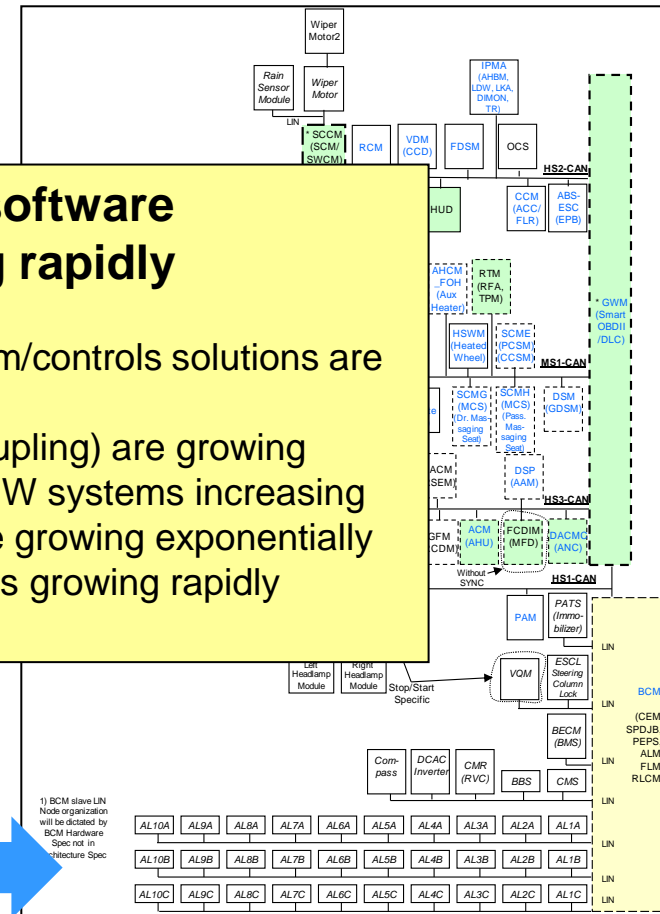
2006



2010



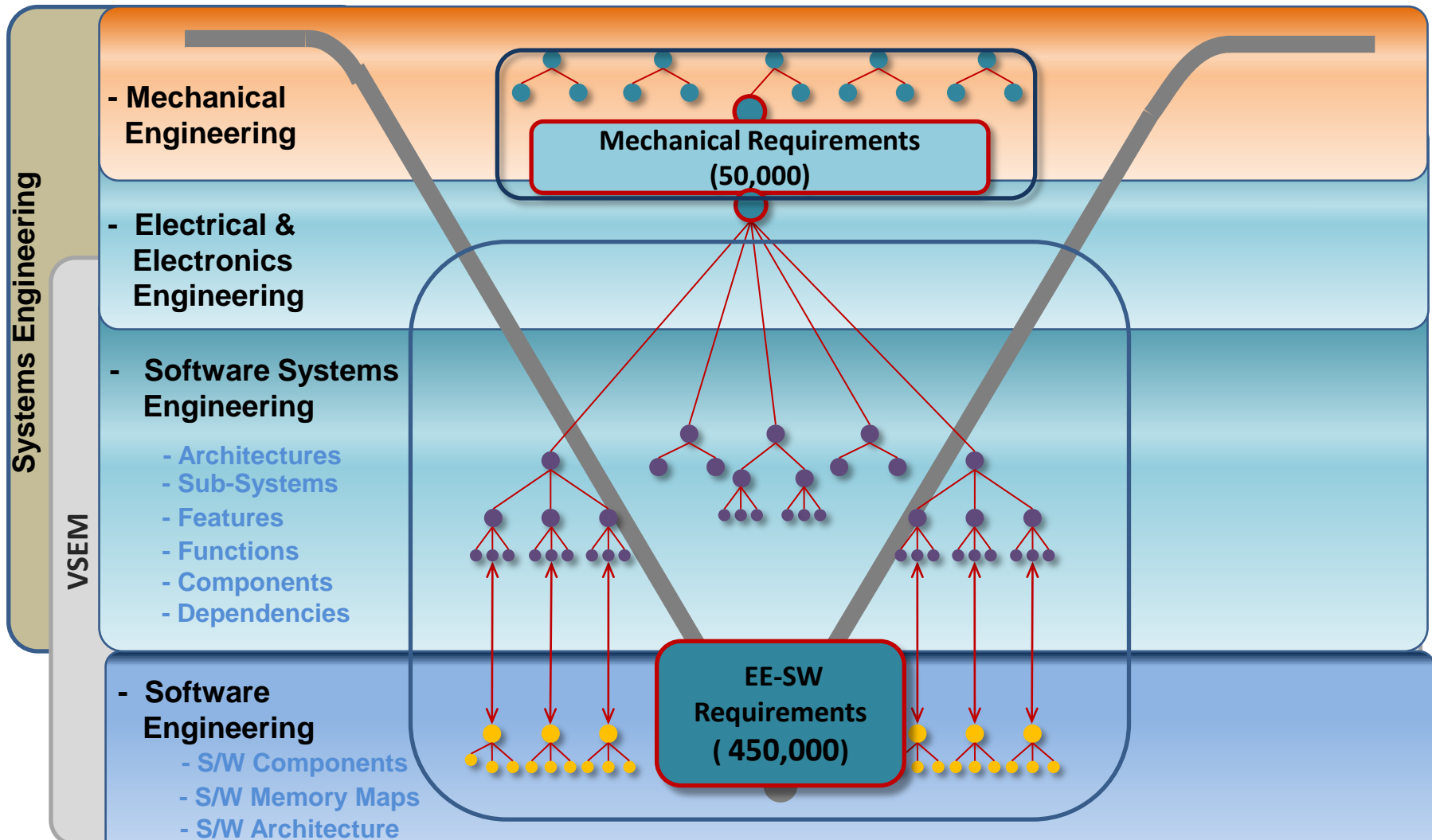
2012+



Overall automotive software complexity is growing rapidly

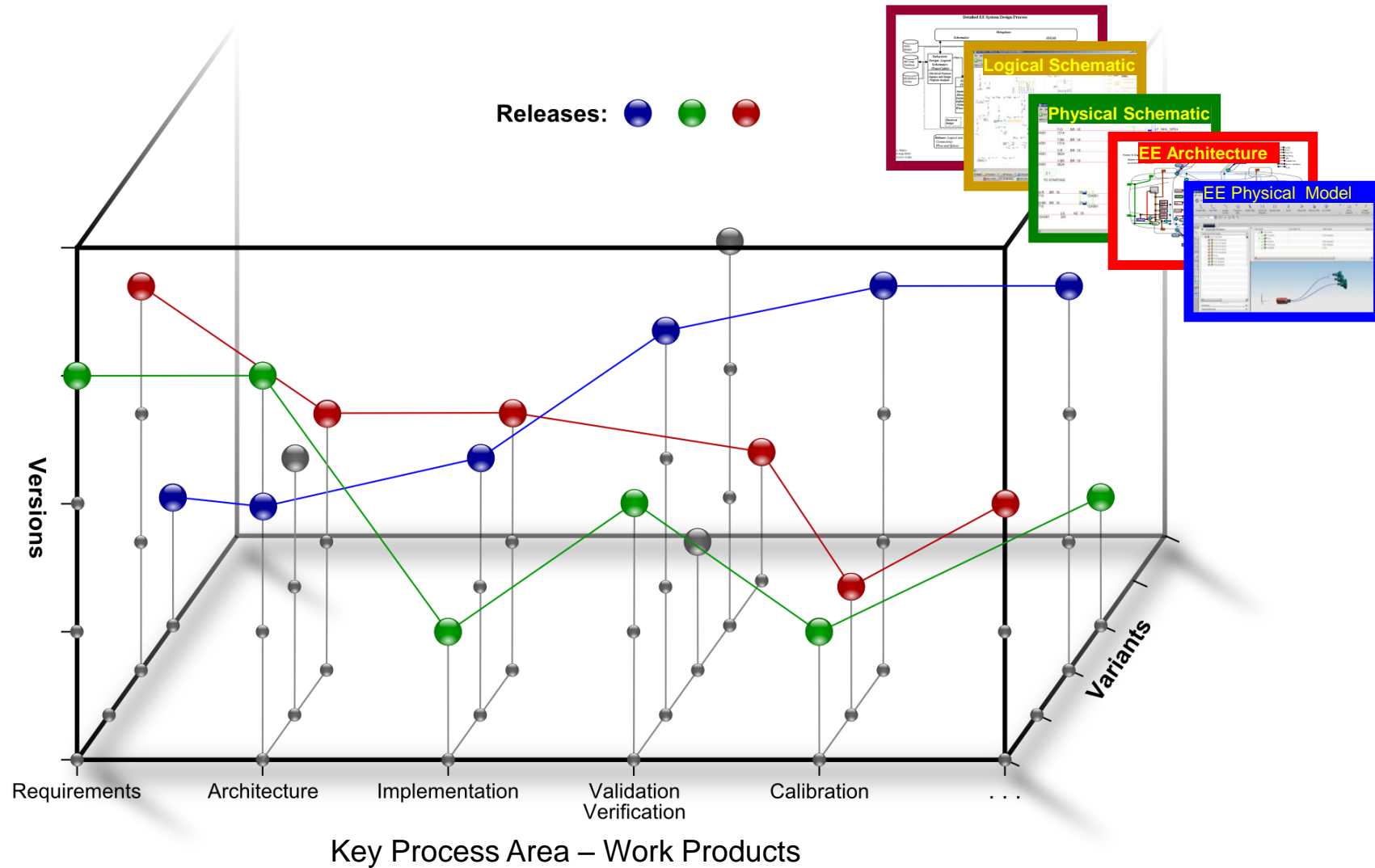
- Distributed software-system/controls solutions are growing rapidly
- System dependencies (coupling) are growing
- Functional safety related SW systems increasing
- Customer input signals are growing exponentially
- SW Lines of code (KLoC) is growing rapidly

Requirements Engineering



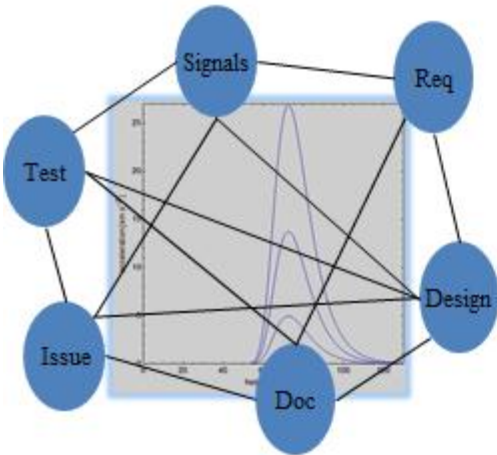
- Mechanical Engineering requirements are typically less complex than EE-SW requirements and more stable
- EE-SW System requirement generate many decomposed levels of requirement-specifications that are more dynamic in nature.
- Software Systems Engineering bridges the gap between Traditional Systems Engineering and Software Engineering, it is an elaboration of the SE principles/practices.

- Release Configurations / Configurable Baselines



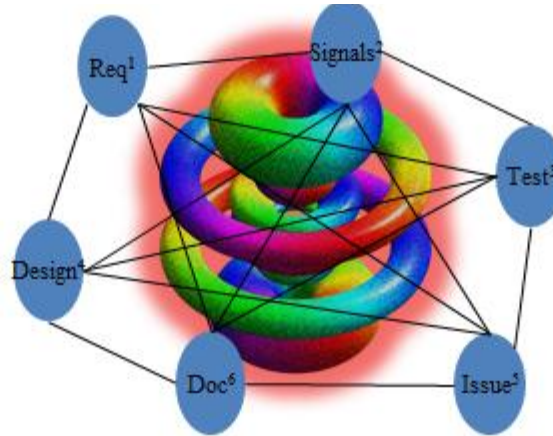
PLM/ALM HW-SW Relationship Management

Mechanical Domain Complexity (10^3 Dependencies)



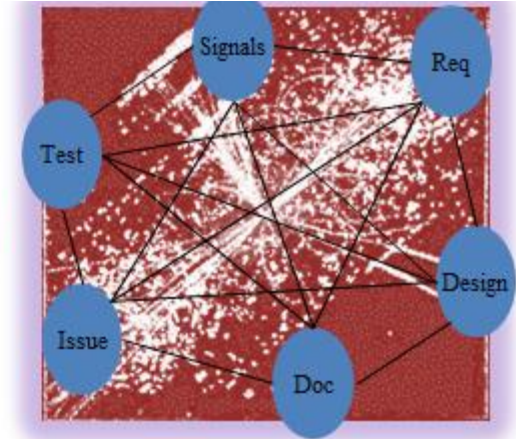
Newtonian Physics

Software Domain Complexity (10^5 Dependencies)



Quantum Physics

On-Board/Off-Board Software Domain Complexity (10^6 Dependencies)



Higgs-Boson event

- All product design work products/artifacts must be managed effectively; preserving their dependencies between content, versions & builds
- This presents a Multi-dimensional, multi-variant, multi-domain challenge that extends off-vehicle.

In conventional engineering, we work in the linear zone where stress is linearly related to strain and the behaviour of the engineering system at 'run-time' is much more predictable. Software is in general, fully chaotic.

* Les Hatton, IEEE Software July/1999.



- Generic Software E/E Failure Mode Mapping:

Work Product Objects

- Architectures
- Features
- Requirements
- Interfaces
- Parameters
- Executable Models
- Test Vectors
- Software Binaries

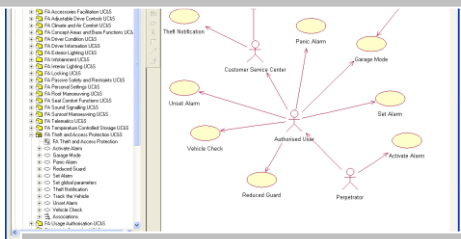
Failure Modes

- Missing
- Incomplete
- Inconsistent
- Incorrect (content)
- Incorrect Version / no versioning
- Inappropriate design
- Unaligned (incorrect configuration)
- Un-accessible (Global Engineering Centers)
- Non-Validated
- Duplicate and/or Conflicting

- **Number of Critical-to-Quality work products and associated failure modes typically increase with: growth in SW-EE Feature content, growth of organizational interfaces, growth in global markets and re-use strategies**

Model Based Systems Engineering/Validation

Customer Requirement - Operational View - (MBA)



Vehicle Level Validation (Ford)

Vehicle Level Testing



Escaped Software Defects Distribution

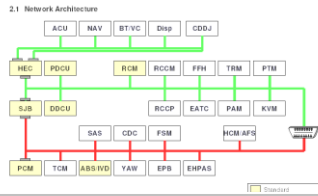
Function Area	Number of Defects
Requirements	~2600
Design and Implementation	~1100
Integration	~1100
Aftermarket	~400

Line No.	Use Case/Function	Defect Category	Performed by	Test Date	Test Pass/Fail
1	Test Preparation		Update Test Performed on field with	VIS_tp_30	
2			Use of new Car.M and CM Input File		
3	Laptop connected to CAN	CANalyser or CANoe running	Run the Car Configuration read-out script and place the log file together with the test report	VIS_tp_30	
4			Check the Car Configuration log file and	VIS tp 40	

HiL System Testing



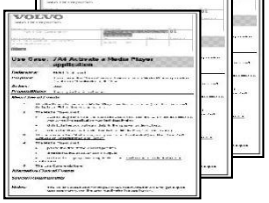
System Requirements - Logical View- (MBR)



BreadBoard Testing



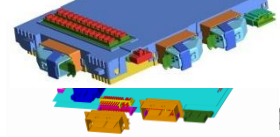
Component Specifications - Physical View - (MBD)



System Verification (Ford)

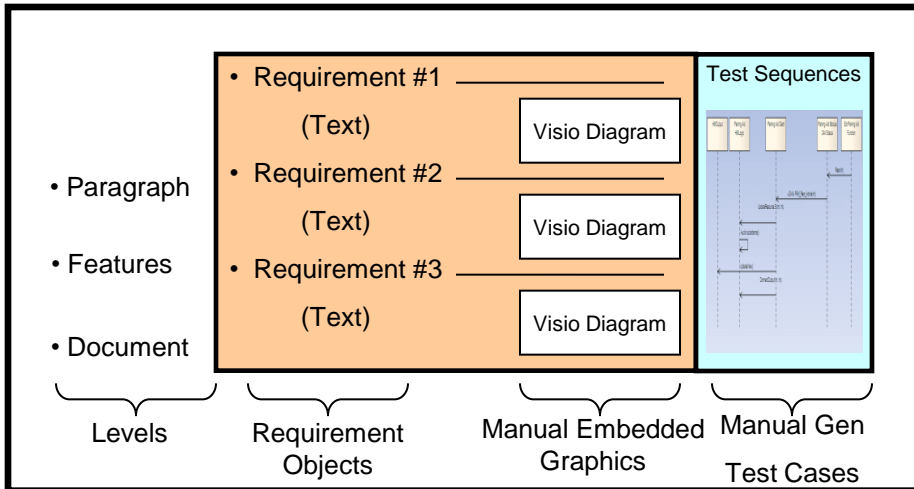
Component Creation/Testing (MBAutoCode/Test)

Model Based Component Testing



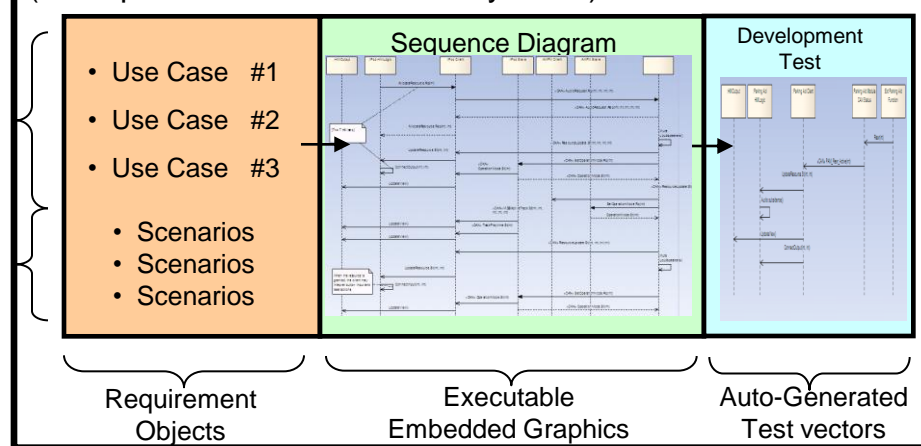
- Software Development/CMMi/SPICE
- Spiral
- Rapid development
- Agile
- Extreme

Traditional Textual Document Approach



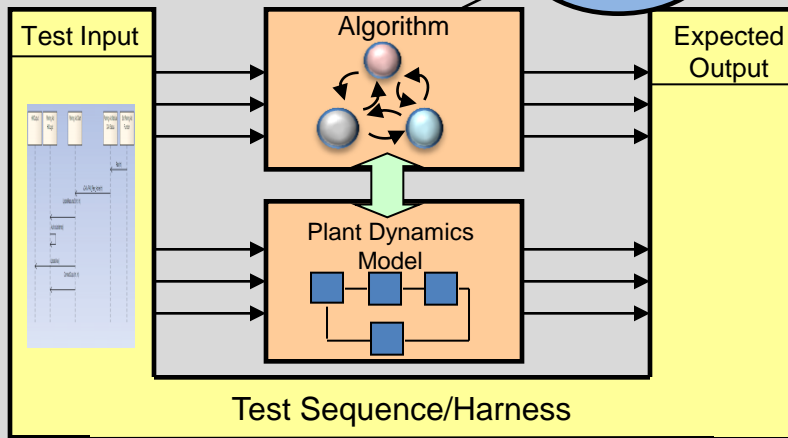
Use Case - Object Oriented Approach (UML)

(Example: Global Infotainment Systems)



Executable Models

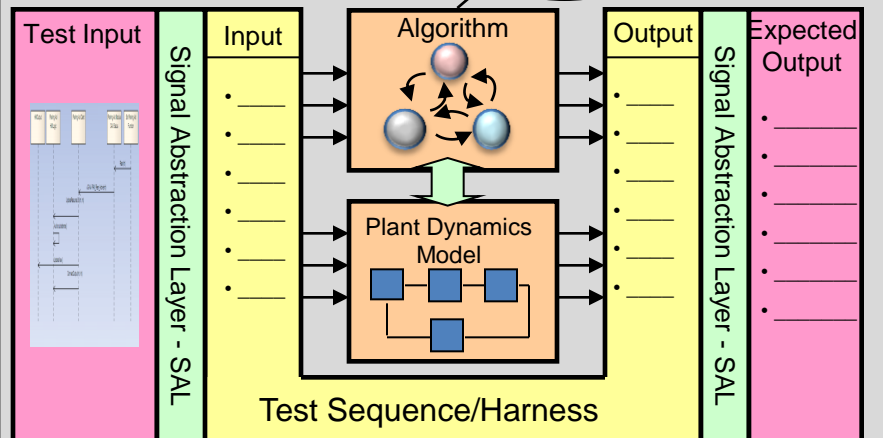
MBSE – The MathWorks Stateflow/Simulink



Platform Independent Model – PIM (Fully Re-usable)

Executable Models

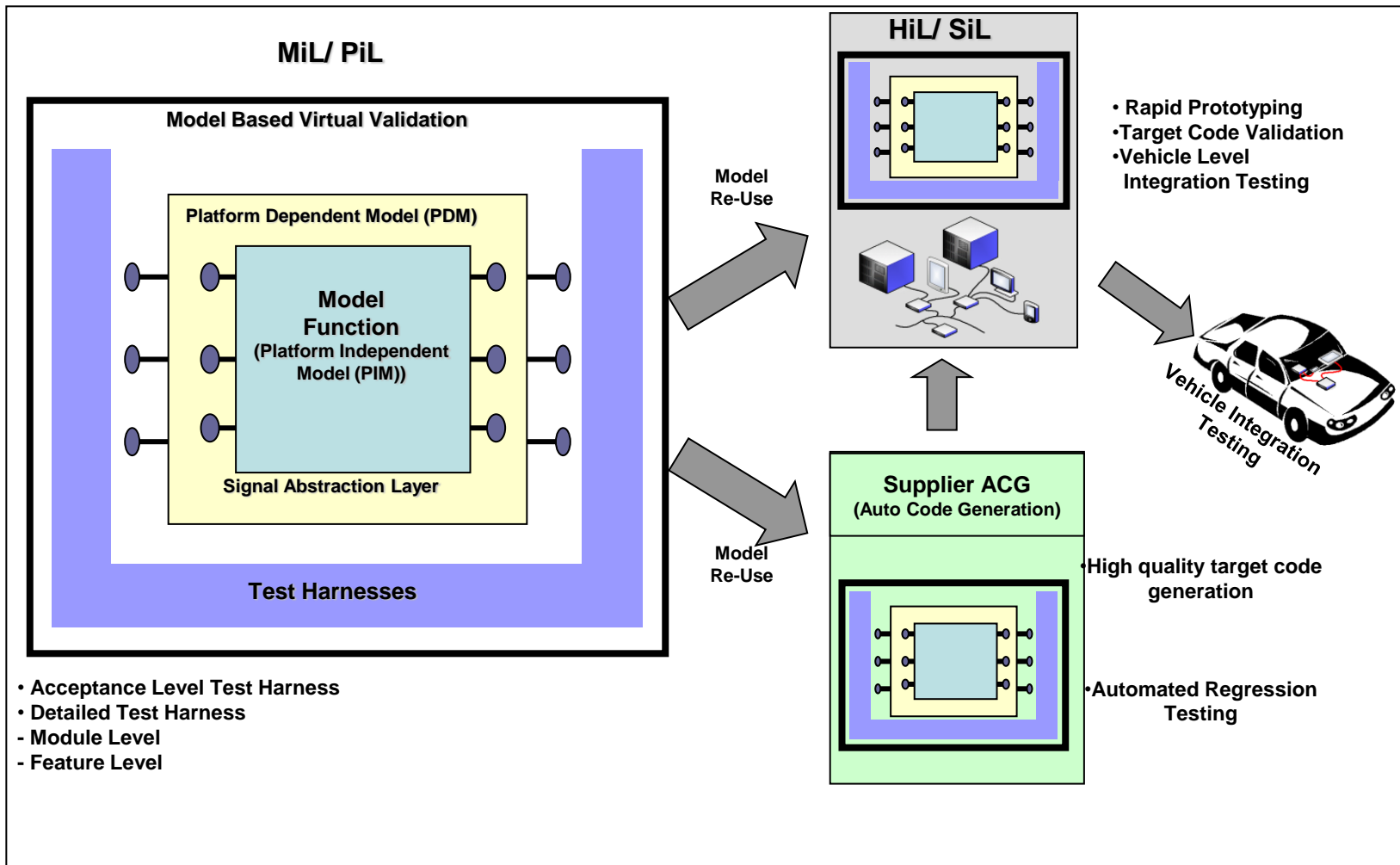
MBSE – Rhapsody - UML



* Test coverage statistic - % MC – Modified Condition - % DC – Decision Coverage

Platform Dependent Model – PDM (Vehicle Specific)

Model Based Testing/Hardware-in-the-Loop



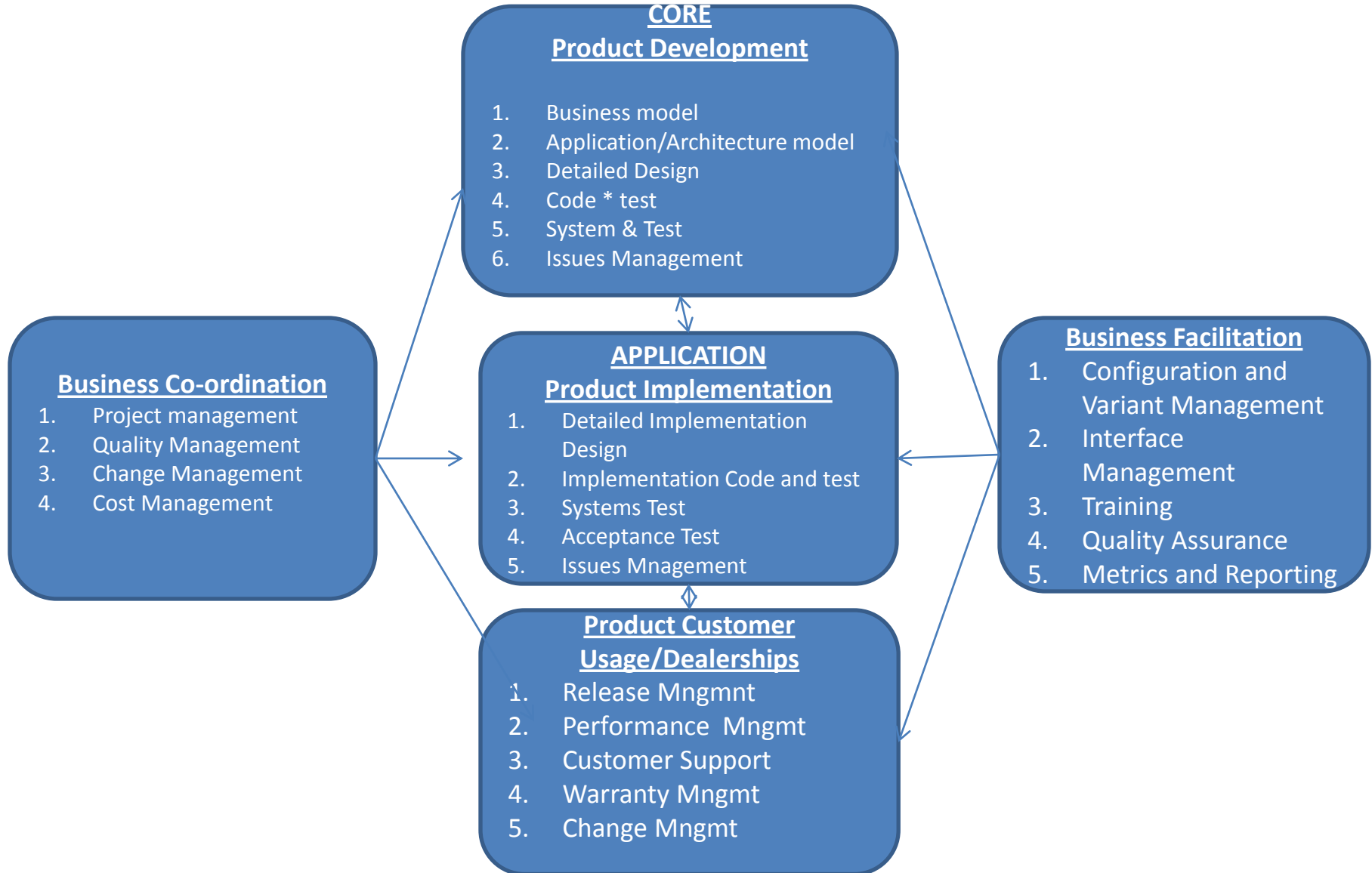
Efficient Utilization of Model-in-the-Loop, PiL & Hardware-in-the-Loop Testing requires:

- Adoption of Platform Independent Models
- Platform Dependant Model
- Signal Abstraction Layer Mapping to Maximize Artifact Re-use
- Management of Test Artifacts: Test Environments, Test Vectors, Model Parameterization Data, Plant Models

When, What and How to Model - Considerations

- **Business Process Modelling**
 - How dependent are the Development, Production and Service Process-Objects?
 - What degree of Business/Engineering visibility do you want to provide?
- **Business Operational Models**
 - In-house Software System Development (SwSystDev)
 - Outsourced-Supplier SwSystDev
 - Hybrid SwSystDev (Internal/Supplier) (Feature/Function Co-linking)
- **Suitability of Feature/Subsystem for Executable modelling**
 - Degree of re-use
 - Feature Complexity
 - Feature Stability
 - Feature Distributed Nature
 - Degree of newness...
 - Domain Competency/skillset
- **Type of Model Framework**
 - Standards (Industry, Corporate, Domain, Organisation.).
 - Degree of Compliance/Leveraging of Standards

- Big picture processes and models...



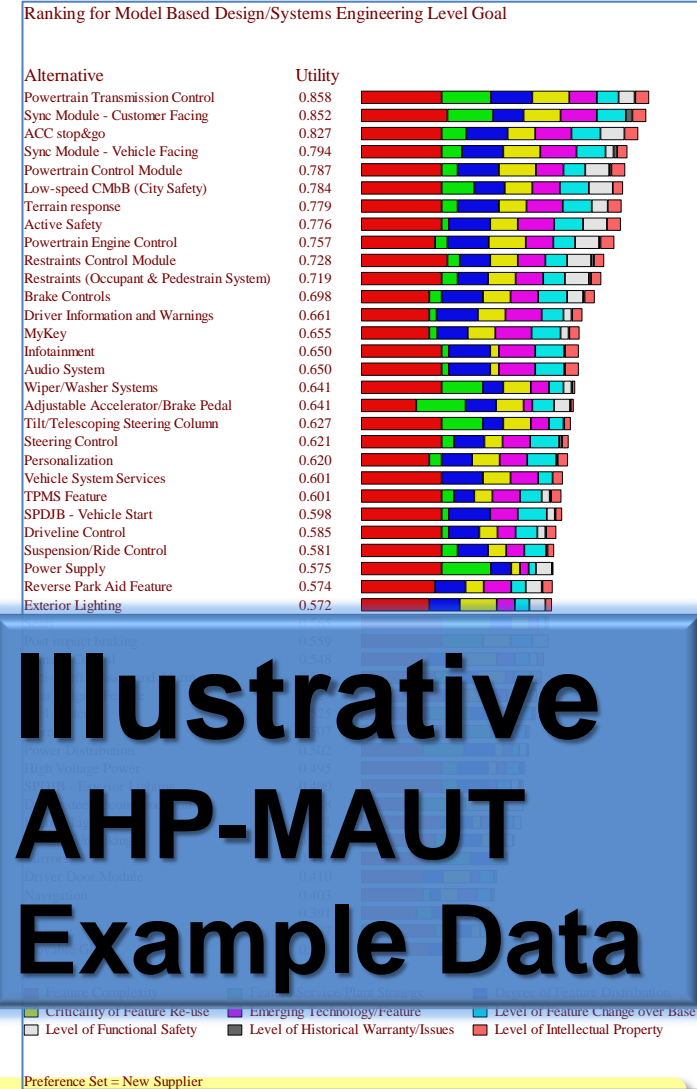
Architectural Views

	Module Views				C&C Views	Allocation Views				Other documents			
	Decomposition	Uses	Generalization	@@@		Data Model	Deployment	Implementation	@@@	@@@	@@@	@@@	@@@
Project Manager	S	S		S									
Development team	D	D	D	D									
Test Engineers	D	D	D	D									
Integration Engineers	D	D	D	D									
Design Engineers													S
Service Engineers	D	D	D	D	D								
Product-Line Engineer	D	D	S	O	S								
Internal Customers													
End Users/Customers													
Analysts	D	D	S	D	D								
Infrastructure/EcoSystem IT support	S	S			S								
New Stakeholders	X	X	X	X	X								
Current/Future Architects	D	D	D	D	D								
	Key: D - Detailed Information; S - Some Details; O - Overview Information; x - anything												
	Derived from Data within "Documenting Software Architectures, 2nd edition, Paul Clemens et al"												

- Which Architectural Perspectives are Critical to Business Success?
- What degree of interoperability do you need between the Architectural Views?
- What Degree of Executable Architecture Model do you need to implement ?

Effectiveness? Failures Models, Causal Factors & PCA Study

- Six Sigma Studies (DFSS & DMAIC)
 - Process Maps
 - Hidden Factories
 - Capability Assessments
 - Causal factor - Defect Correlation statistical studies
 - The Critical Few – Critical to Business (CTB) Process, Methods, Tools and Information Management
 - CTB Metrics
- Hierarchical Decision Process to Prioritise the Critical Few



• DMAIC and DFSS based analysis identifies and prioritises the key areas that need to be addressed

Model Driven Architecture - MBSE Process?

Functional Requirements

Functional Requirements
Marketing Requirements
Stakeholders
Context Diagram
Stories
Constraints

Non-Functional Requirements

Requirements Engineering

Feature Definition



Architecture Design Phase

Logical Architecture View

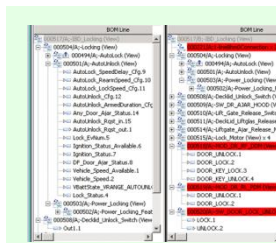


Functional Architecture View



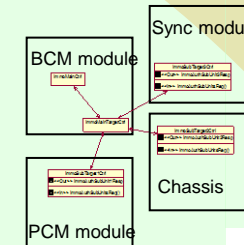
Deployment Phase

Physical View



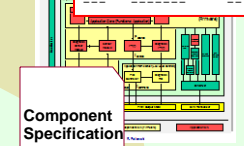
EE-SW BoM

Functional Deployment View

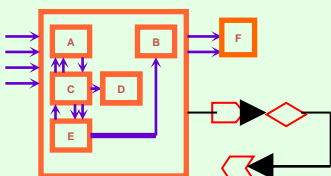


Component Phase

Signal Database
EMS EngineSpeed 45
EMS EngineTemp 22



Detailed Control Design Phase



Coding Phase

```
#define _SYS_CTRL_LOGIC_CAL
#include "tl_types.h"

CAL F32 dg_master_enb_delay_c = 0.4F;

}
if (!BFd37.Cd31_veh_motion_logic) {
    BFd37.Cd31_veh_motion_logic = 1;
} else {
    Cd31_reverse_motion = (cf_reverse != 0) || (cf_veh_dim == 1);
    Cd31_vehicle_moving = lp_out > vkph_moving;
}

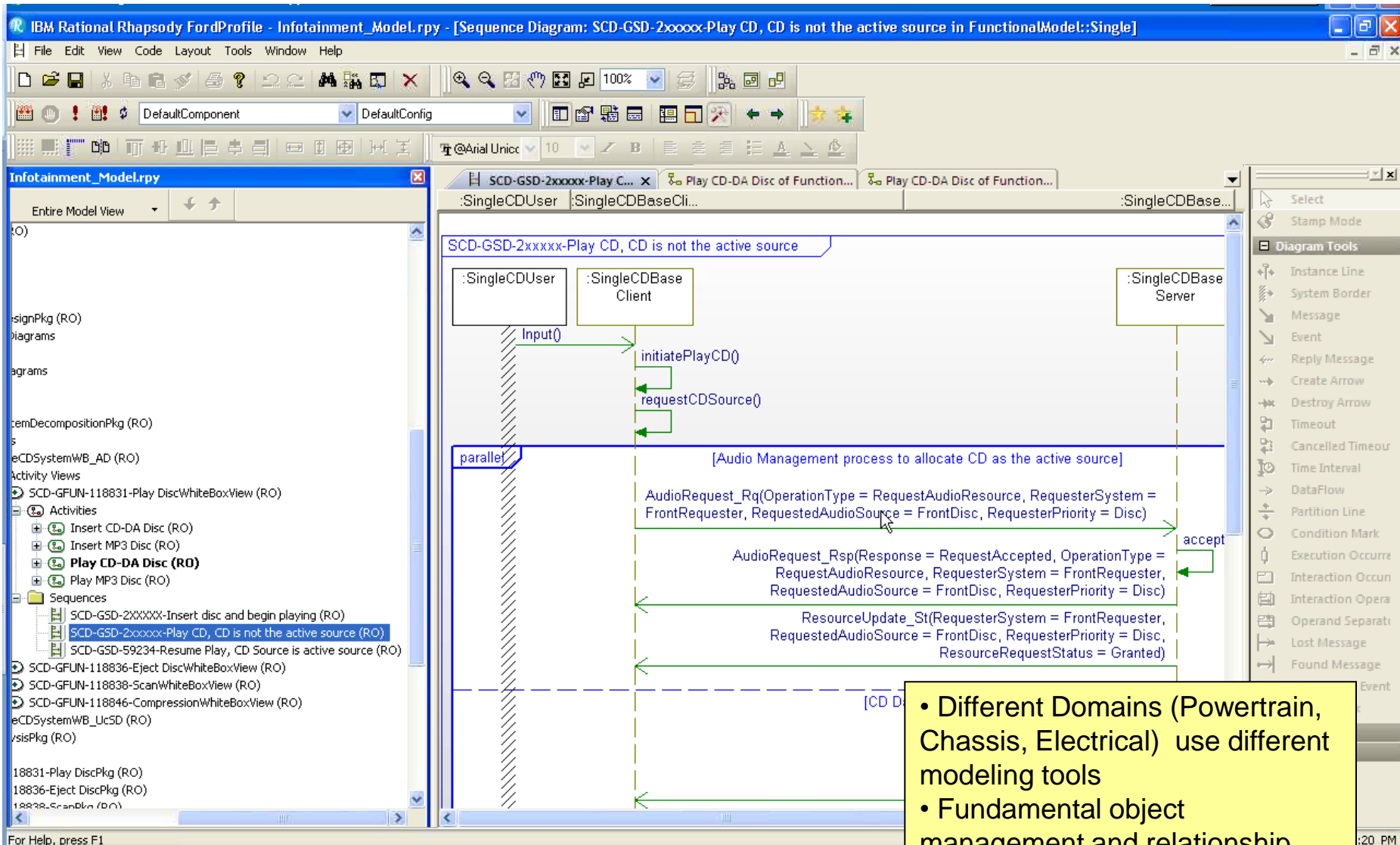
```

Textual Requirements & Executable Model Mapping

The screenshot displays the Systems Engineering environment. On the left, a tree view shows a hierarchy of requirements, with 'REQ-000644/A;1-Autolock (View)' selected. The center window shows a Microsoft Word document with a grid of diagrams. A yellow arrow points from the selected requirement to a diagram in the Word document. The right window shows a Model Browser with a tree view of components, including 'AutoLock' and 'AutoUnlock'. A yellow box highlights a component in the Model Browser, which is linked to the diagram in the Word document.

- Fundamental capability is to have full Linkages, Dependency info and Version Visibility between:
 - Requirements/Functional Specifications
 - Test Vectors
 - Executable Models
 - Parameters/Signals
 - Configuration Data Sets
 - Calibration Data Sets
 - Software Binaries and Build configurations

UML – Infotainment Modeling

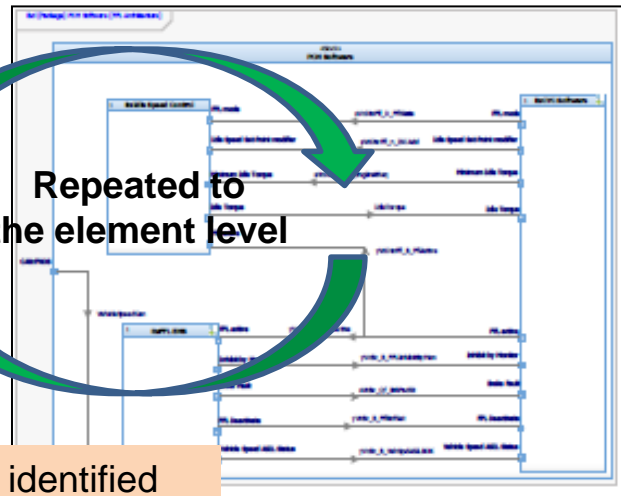
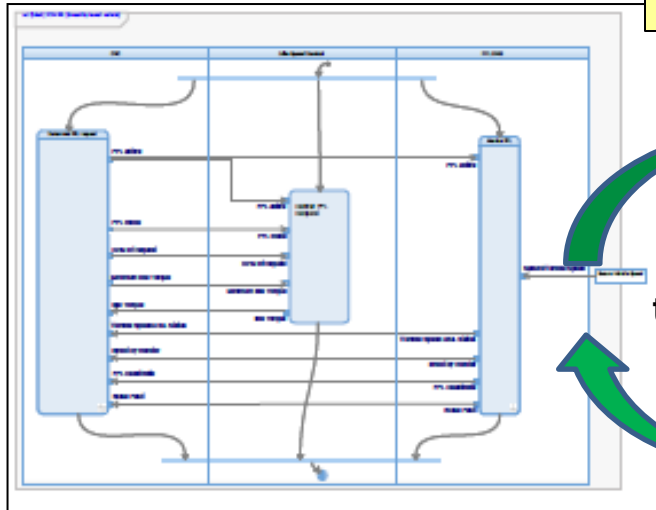


SysML – Powertrain Feature Modeling

System high level functional requirements are modeled in SysML which are then decomposed into lower level behavior models

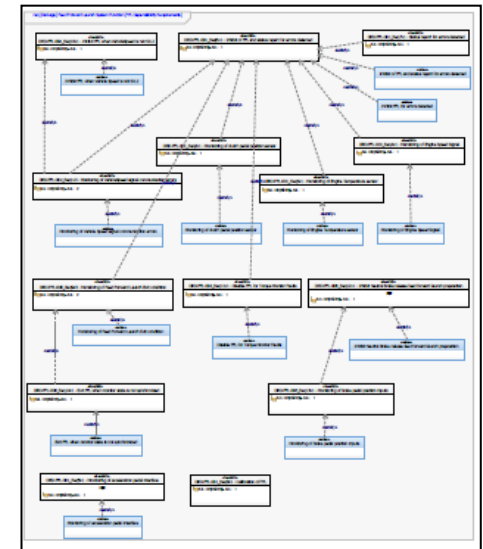
Behaviors are partitioned into a logical architecture and physical architecture

The functional system requirements and derived requirements are linked to the SysML behaviors using a Requirements Diagram



Repeated to the element level

Requirements gaps were identified when modeling the behaviors which were not apparent from the textual requirements alone



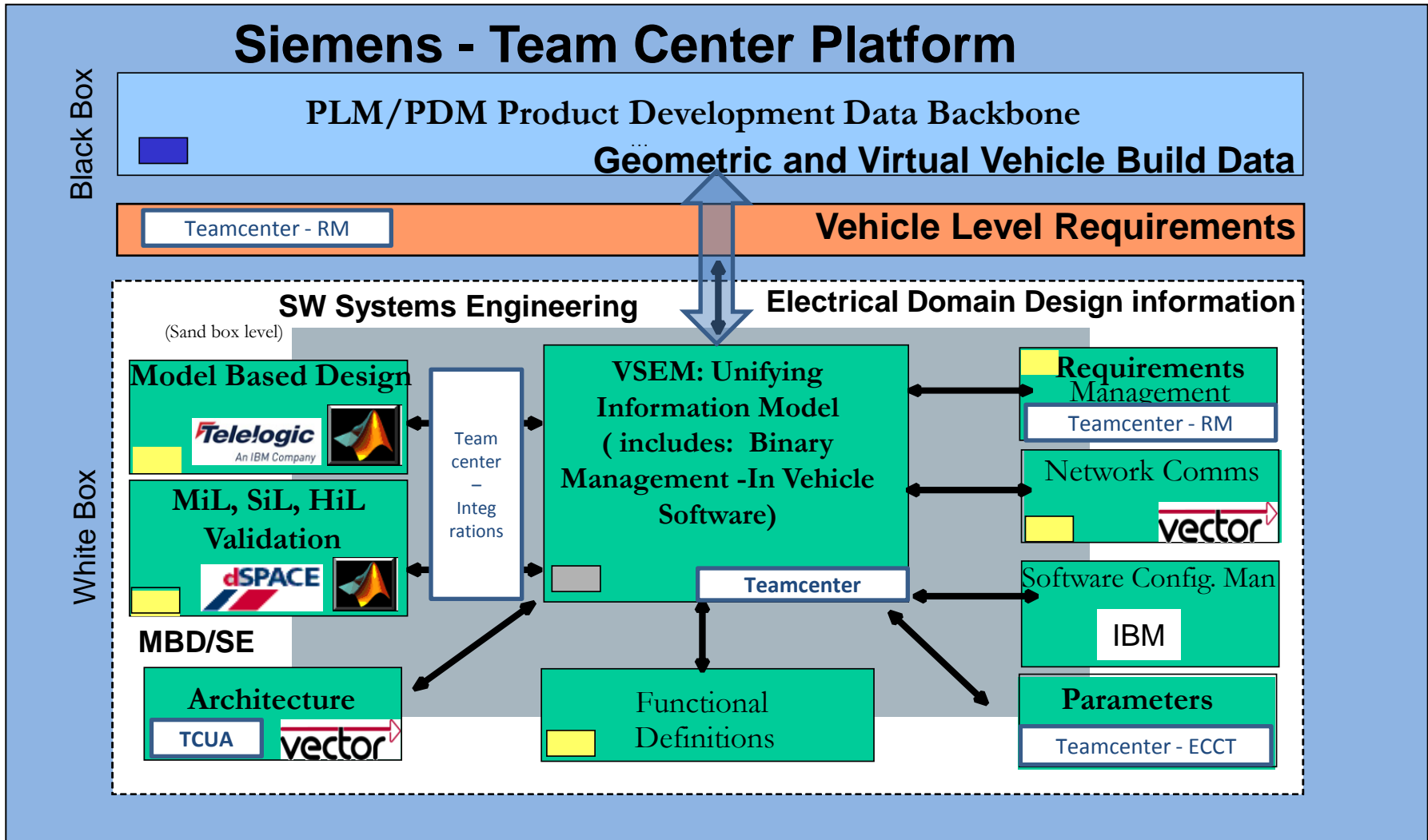
Courtesy of Kyle Post, Ford Motor Company

Vehicle Software & Electrical Management – VSEM

Create a global information platform with seamless information management of engineering data from function to ECU S/W & H/W inclusive to create a complete PLM/ALM solution for electronic/software area.

- **Provide a fully traceable, object level work product framework**
- **Support a Model Based Systems Engineering EE development process**
- **Single source for all information E/E development data**
- **Support change, version, and configuration management with full traceability**
- **Based on standardised open tool framework** to enable utilisation of “best-in-class” commercial state-of-the-art “plug-in” tools.
- **Designed on industry engineering standards** and aligned to the AUTOSAR architectural framework

Siemens - Team Center Platform

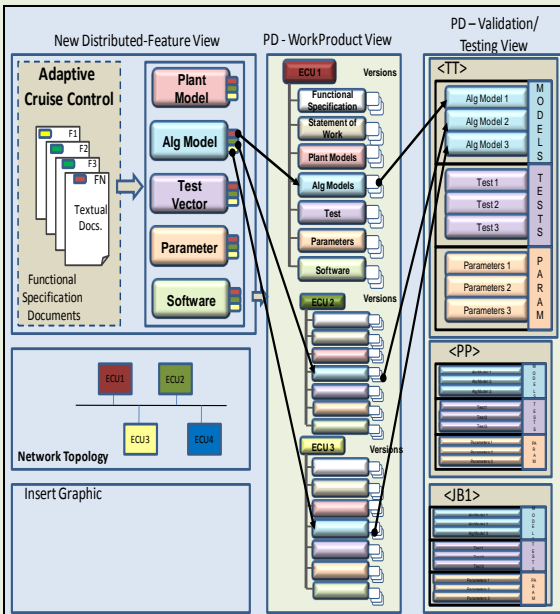


■ Global Enterprise information
 ■ Electrical domain information
 ■ Local information in point tools
 ↔ Defined Exchange formats

- Adoption of Single Corporate data backbone and authoring tools enables WP and relationship Meta data re-use across Corporate PD systems.
- Must support data objects that require rapid iteration (ALM) Vs structured management (PLM).

VSEM Project Scope and Implementation

Product Development



- Systems Engineering,
- Software Systems Engineering
- Software Engineering

> **Model Based Systems Engineering** <

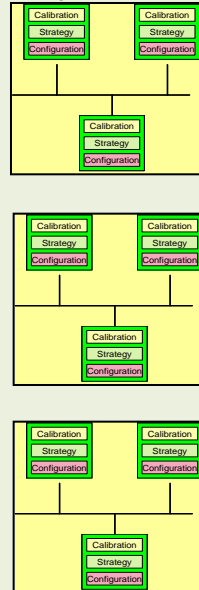
EE System Artifacts that derive a Released BOM

Requirements, Tests, Models, Parameters, Devices, Calibrations, Configurations, Architectures...

(As-Designed)

In-Vehicle Software (IVS)

E/E System BOMs

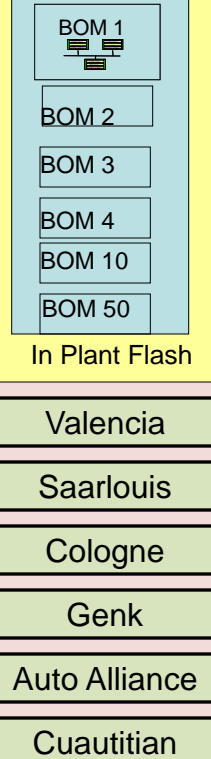


EE System Released BOMs

(As-Released)

Assembly Plants

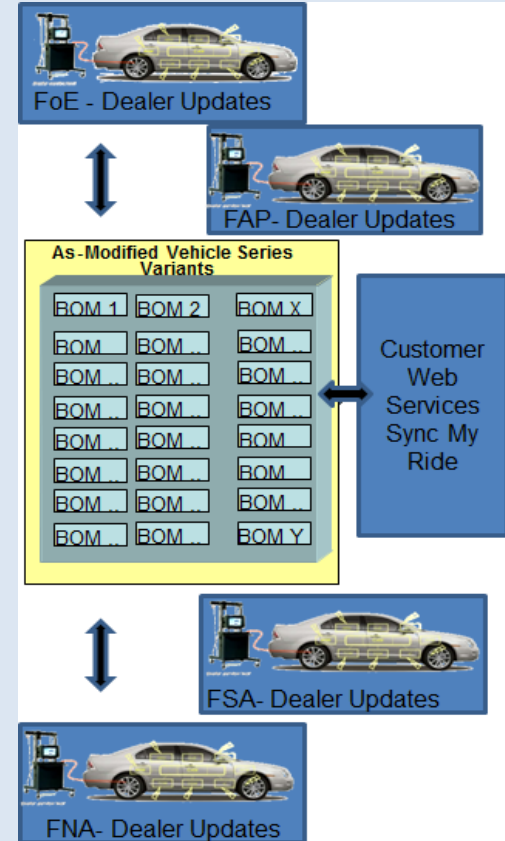
Manufactured Vehicle Series Variants



Global Manufacturing Plant Reprogramming

(As-Built)

Dealerships and Web Services



Global Dealerships & Customer Updates

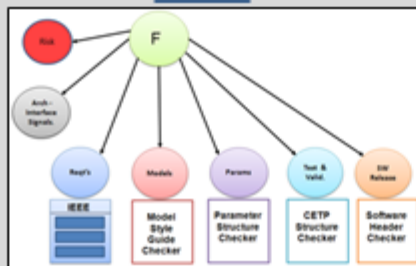
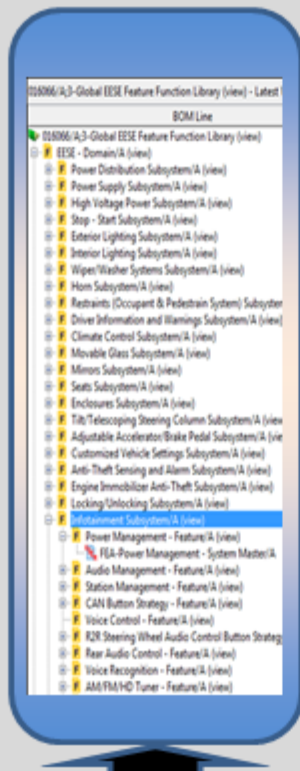
(As-Modified)

Systems Engineering MB Framework

Systems Engineering Work Products

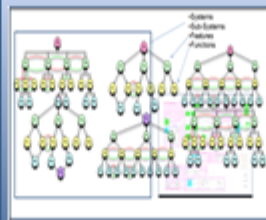
- FMEA
- P-Diagrams
- Boundary Diagrams
- Interface Matrix
- Noise Factor Mangmt Strategy
- DVP
- Safety Plan
- Prelim Hazard Analysis
- Functional Safety Concept

Feature Dictionary



Functional Architecture (Implementation Independent)

Virtual, Model Based Analysis; Dependencies; Coupling; Cohesion & Arch Quality Attribute Studies



Logical Architecture (Re-usable Reference Architectures)

Commodity Specific Reference Architectures

Sync Gen 2 Ref Arch V1.0



BCM Ref Arch V1.x



Physical Architectures (Vehicle Program Specific)

Vehicle Program Specific Architectures



Global Signal Database (GSDB)

- Signal Definitions - Interface Specs
- -CAN Message relationship
- Global Device Transmittal Database (GDT)
- SW-HW interfaces
- EE Devices – Sensors - Actuators

Model Comparisons in BoM View

The screenshot displays two windows from a CAD software interface. The left window, titled 'Structure Manager', shows two BOM trees side-by-side for comparison. The right window, titled 'Viewer', shows a graphical 2D tree view of the BOM.

Structure Manager - BOM Line Comparison:

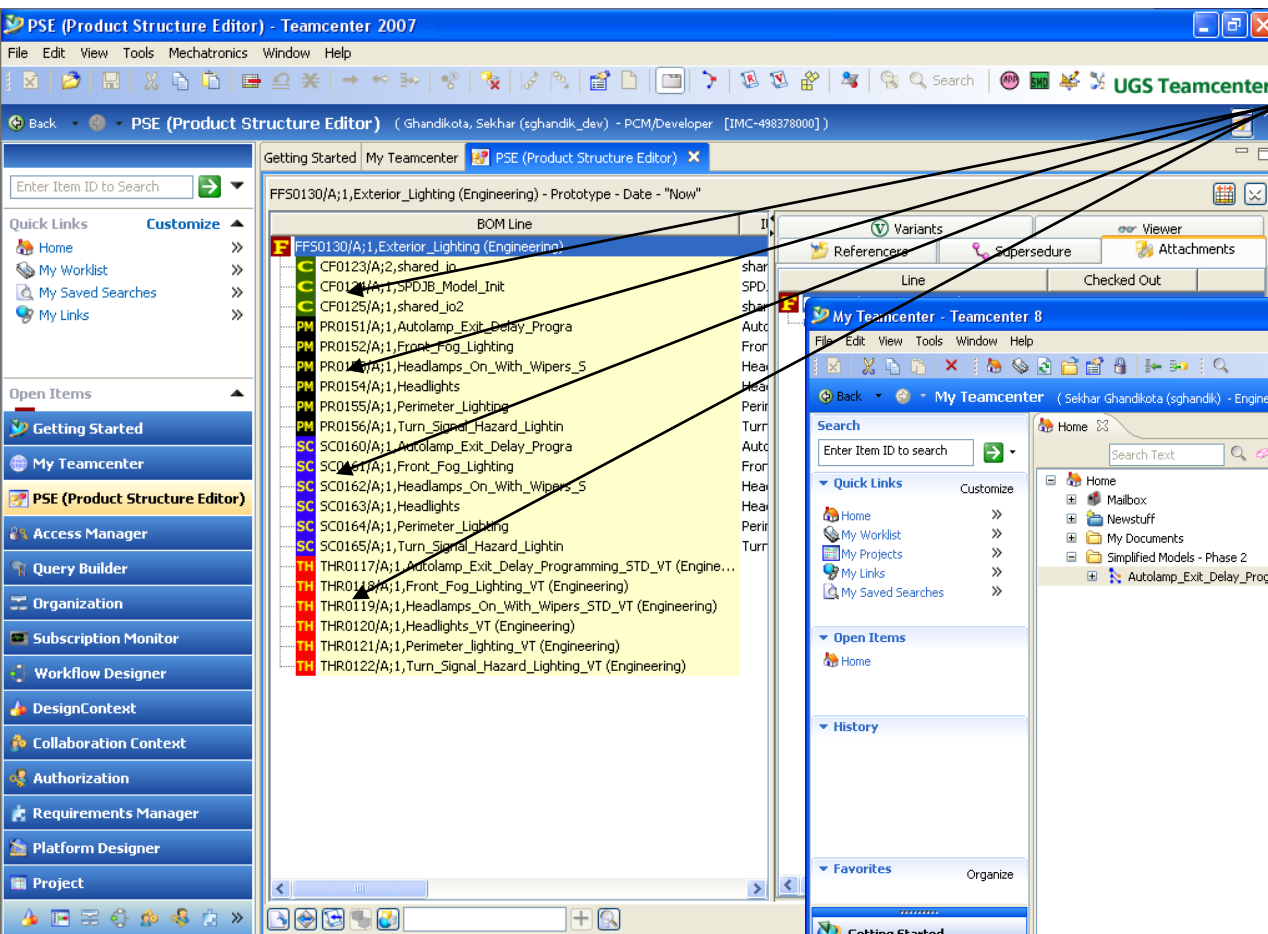
Item Id	Item Name	Find No	Rev	Qty
000517				
000221	lineBhm0Connection	() ->A	0 ->2	
000518	MOD_DR_RF_DDM	() ->A	0 ->1	
000519	MOD_DR_RL_PDM	() ->A	0 ->1	

Viewer - 2D Tree:

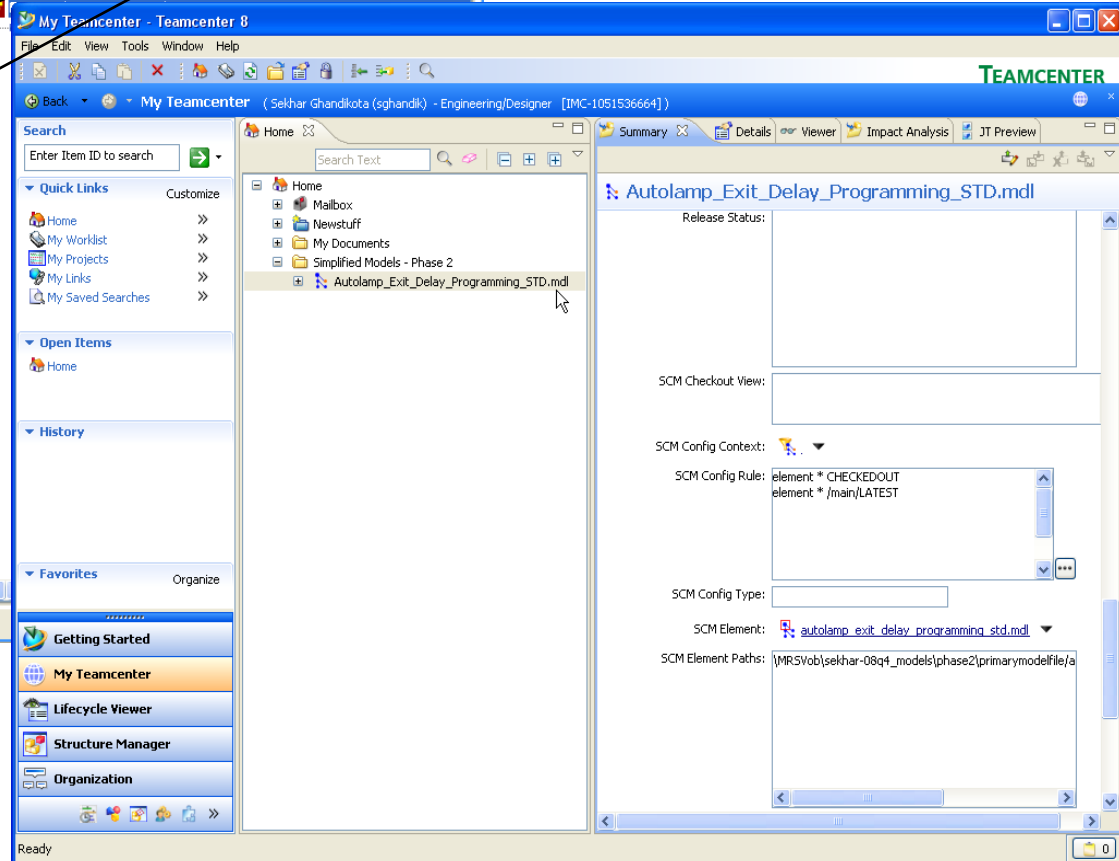
- 2D Tree
 - Base Document
 - IBD_Locking.jp

- BoM based model comparisons or graphical model differencing can be performed.

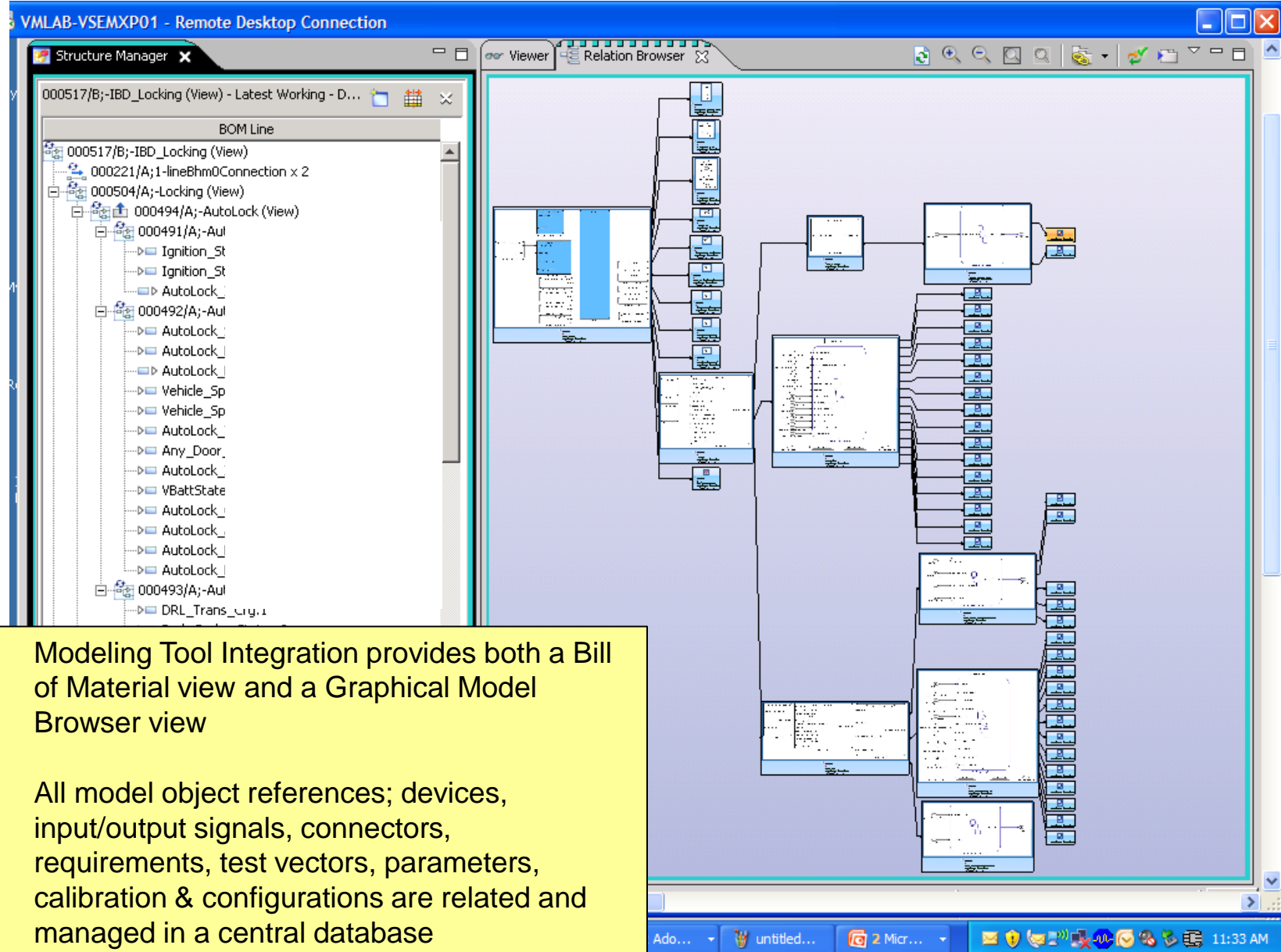
PLM/ALM Based Model Management



• Unique ICONS to provide visual cues to identify and relate feature/model artifacts



Models in a BoM & Object Relationship Viewer



The screenshot displays a software interface for managing models in a Bill of Materials (BoM) and an Object Relationship Viewer. The interface is divided into several panes:

- Structure Manager:** Shows a hierarchical tree of components. The root is '000517/B;-IBD_Locking (View) - Latest Working - D...'. Below it are sub-components like '000221/A;1-lineBhm0Connection x 2', '000504/A;-Locking (View)', and '000494/A;-AutoLock (View)'. The 'AutoLock (View)' component is expanded, showing sub-items such as '000491/A;-Aul', '000492/A;-Aul', and '000493/A;-Aul', each with associated sub-elements like 'Ignition_St', 'AutoLock_', 'Vehicle_Sp', 'Any_Door_', 'VBattState', and 'DRL_Trans_...'. The 'DRL_Trans_...' component is further expanded to show 'DRL_Trans_...'.
- Viewer:** Displays a graphical model browser showing a complex network of interconnected components and data points. The components are represented by small icons and connected by lines, forming a hierarchical and interconnected structure.

The Windows taskbar at the bottom shows the system tray with various icons and the time '11:33 AM'.

- Modeling Tool Integration provides both a Bill of Material view and a Graphical Model Browser view
- All model object references; devices, input/output signals, connectors, requirements, test vectors, parameters, calibration & configurations are related and managed in a central database

Full Traceability into Impacted Work Products

The screenshot displays the Teamcenter 8 Structure Manager interface. On the left, a BOM tree lists various components under 'FLIB0001/A;4-CGEA 1.3 Library'. The selected item is 'LF000135/A;1-My Key'. The main view shows a detailed overview of this item, including its owner (goiket) and last modified date (23-May-2011). Below this, several sections provide context and dependencies:

- Feature Libraries:** Lists libraries such as 'FLIB0001/A;2-Feature Library', 'FLIB0001/A;3-CGEA 1.3 Library', and 'FLIB0001/A;4-CGEA 1.3 Library'.
- Requirements:** Lists requirements like 'REQ-005066/A;1-Use Case', 'REQ-005885/A;1-PATS Myk', 'REQ-005886/A;1-1KD Looku', and 'REQ-005887/A;1-Program N'.
- Vehicle Programs:** Lists programs such as 'Ford Focus', 'Explorer', and 'Fusion'.
- Primary Models:** Lists models like 'PR0177/A;1-Determine Spe', 'PR0180/A;1-Determine Ma', and 'PR0181/A;1-Limit Maximum'.
- ECUs:** Lists ECUs such as '000085/A;2-BCM', '001138/A;1-Anti-Lock Brake', '001147/A;2-Accessory Prot', and '001163/A;2-Audio Digital Sig'.
- Parameters:** Lists parameters like '002488/A;1-Igni', '002488/A;2-Igni', '003841/A;1-Adm', and '003856/A;1-Sym'.

- Environment supports full impact analysis to understand any change in it's Vehicle/Domain/Subsystem and Feature context.
- Enables fully informed, high value decision making.
- Full re-use with context and underlying assumptions

“On Ko Chi Shin” – “Studying the old promotes a better understanding of the new”. Ancient Japanese proverb.

1. Different domains select different modeling tools due to multiple factors
 1. Ability of their domain specific artifacts to be represented completely within a modeling schema/construct set
 2. Number of engineers with a specific modeling competency within the domain
 3. Amount of legacy models of a given modeling tool type within a domain
 4. Level of abstraction required within a domain and across domains
 5. Availability/cost of existing/new Licenses
 6. Lack of engineering staff with modeling competency or allocated resource/time.
2. Some features/commodities do not benefit from detailed modeling (non-changing features that are truly purchased commodities and do not benefit from executable modeling efforts (still may benefit from static architecture models)
3. These forcing functions lead to the need to support a HYBRID MBSE environment that consists of a set of modelling tools with associated style guides, maturity levels, completeness levels
4. For HYBRID environments it is important that all of the critical to quality/function artifacts/Meta data and associated objects/relationships are managed with supporting lifecycle management tools
5. Enterprise wide change is hard, painful, challenging and rewarding AND far better than the alternative.....

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**Thank-you for
Listening**