



**2021**  
Annual **INCOSE**  
International Workshop  
Virtual Event  
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Premier Systems Engineering Workshop

# Integrated Model-based Systems Engineering (*iMBSE*) in Engineering Education

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# Outline



## 1. Rationale

1. Product development: Modern products
2. Current practice in Academia: Capstone Design Limitations in Engineering programs (ME, EnE, EE, CE, BME, IE, etc.)
3. Document based Systems Engineering: Current limitation

## 2. iMBSE: 3D extension of Capstone Design & Digitalization of SE

1. iMBSE characteristics & modern products
2. 3D extension of Capstone Design

## 3. Curriculum for Industry 4.0: Engineering Education 4.0

1. 3 Level curriculum
2. Revised curriculum (for Engineering Education 4.0)

## 4. iMBSE: Framework & Digital innovation platform for Industry 4.0

1. Proposed iMBSE framework
2. Digital Innovation platform for Industry 4.0

## 5. Case study: Electric skateboard

## 6. Summary & conclusions



# Rationale → Product Development → Modern Products



Modern products are increasingly becoming complex, typically smart connected systems or systems of systems (SoS). To develop modern products competitively, there is need to address complexities resulting from:

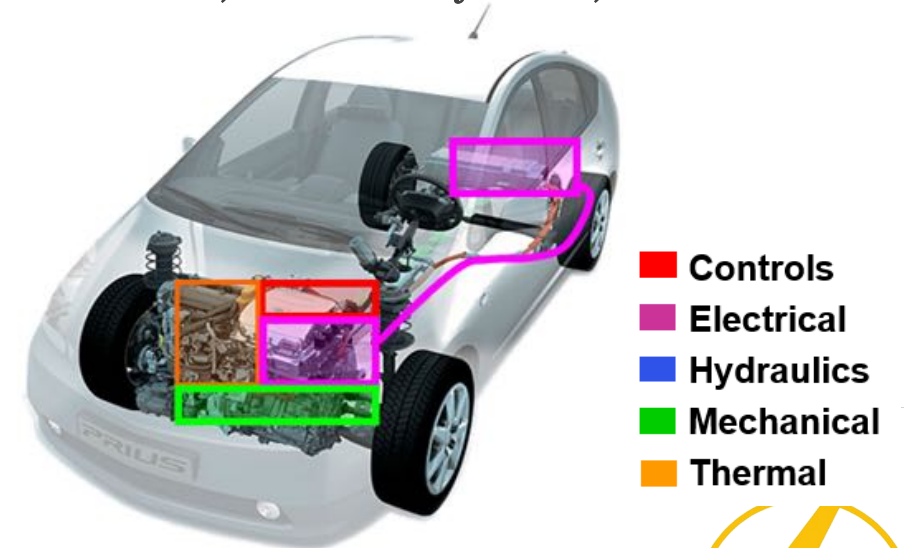
## ....managing:

- Multiple sub-systems
- Multiple engineering domains
- Multiple variants and system architectures
- Growth of software / electronic systems
- Exploding requirements
- Fast growing number of V & V
- Multiple disparate tools in each domain
- Multiple design groups and multiple sites

## ....dealing with:

- Subsystems interactions
- System integration

Example of modern product: Multi-domain, multi-subsystems, etc. SoS



Siemens PLM publication

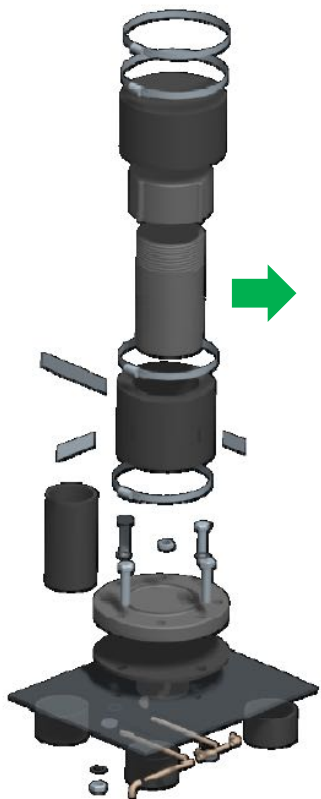


# Current practice in Academia → Engineering programs: Capstone Design Limitations

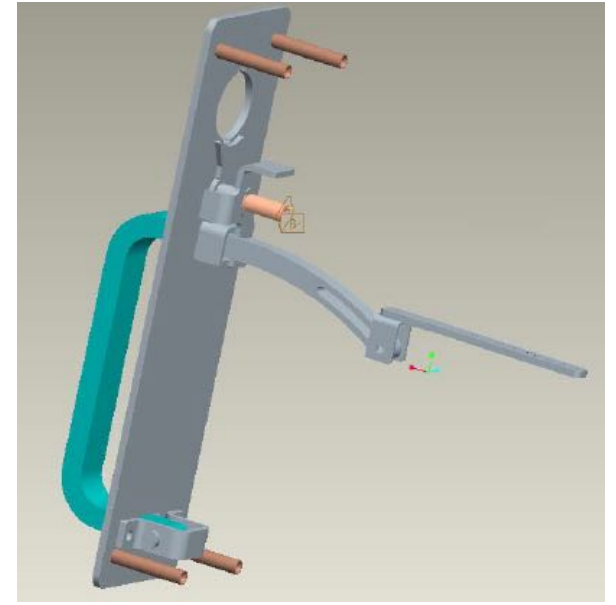


## Capstone Design Limitations

- Simple product
- Single Domain
- Limited scope: “Development” (not “Lifecycle”)
- Limited Digitalization
- Validation: Mostly through Physical prototyping



Fin Heat Transfer Apparatus



Arm-A-Door Outside Entry: Exterior Handle Assembly

Example of typical capstone design products:  
Mostly Mechanical

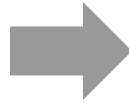




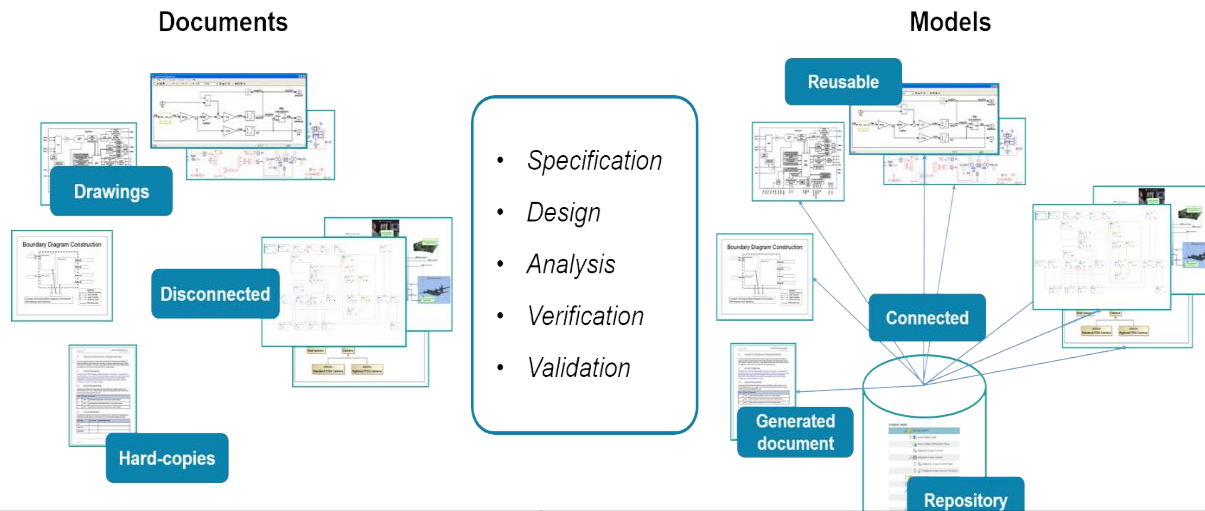


# Current practice in Industry → Document-based Systems Engineering Limitations

**Definition:** MBSE is a model-centric (v.s. document-based) approach providing a **single point of truth** which is reflected in a set of living artefacts [INCOSEUK].



The successful implementation of Model based Systems Engineering (MBSE) leads to lower cost, better quality and lower risk. These are the results of the following:



The system model allows early detection of errors and inconsistencies enabled by the ability perform analysis

The system model uses modern modeling languages with clearer semantics that lower miscommunication

The system model provides a single source of information ensures consistency between different stakeholders

The system model can be used to automatically generate up to date deliverables (e.g. documents)

The system model supports multiple views to address different stakeholders' needs using a single source of information

The system model helps better manage complexity

The system mode enables early debugging and refinement of requirements, including behavioral ones, through simulation of state machines

Document-based process	Model-based process
Error prone - Missing elements - Poor element traceability Vulnerable to company silos	Workflow enforced Design element based Source driven through design elements Fully integrated



# iMBSE: 3D extension of Capstone Design → iMBSE characteristics & modern products



## 3D extended CD driven by iMBSE

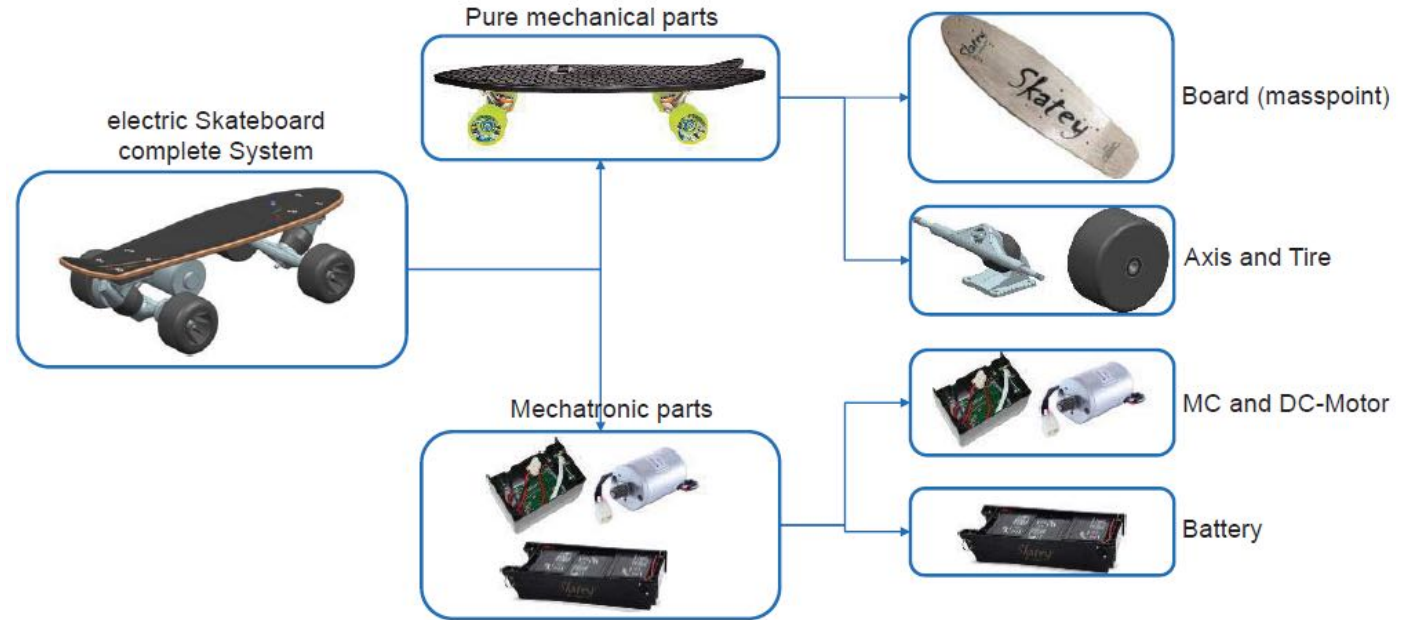
Complex product (system or SoS)

Multi Domain

Extended scope: “Lifecycle” (not just “Development”)

Full Digitalization

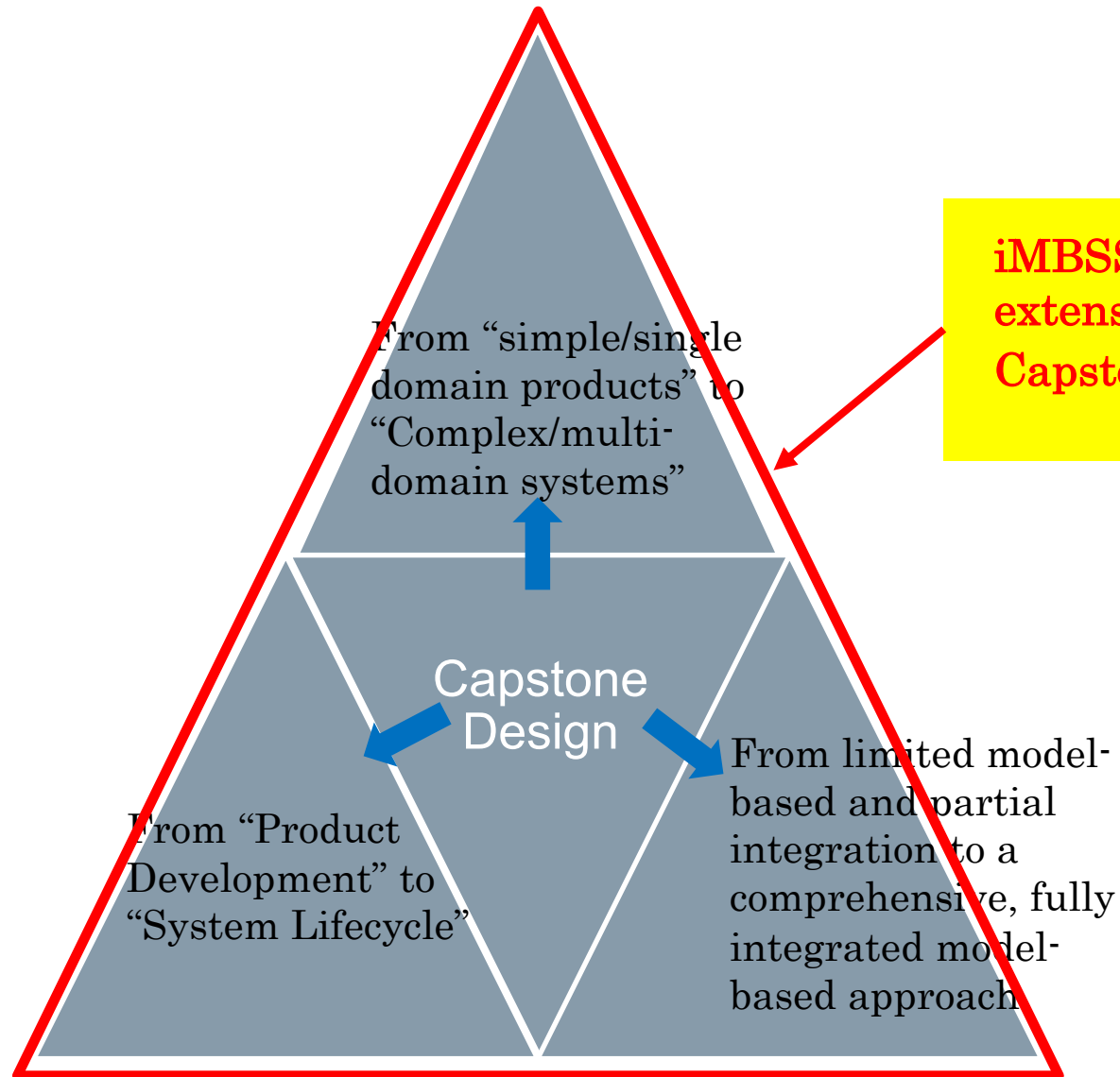
Validation: SIL, HIL, MIL, and Virtual prototyping



Example of a complex product: Multi-domain system



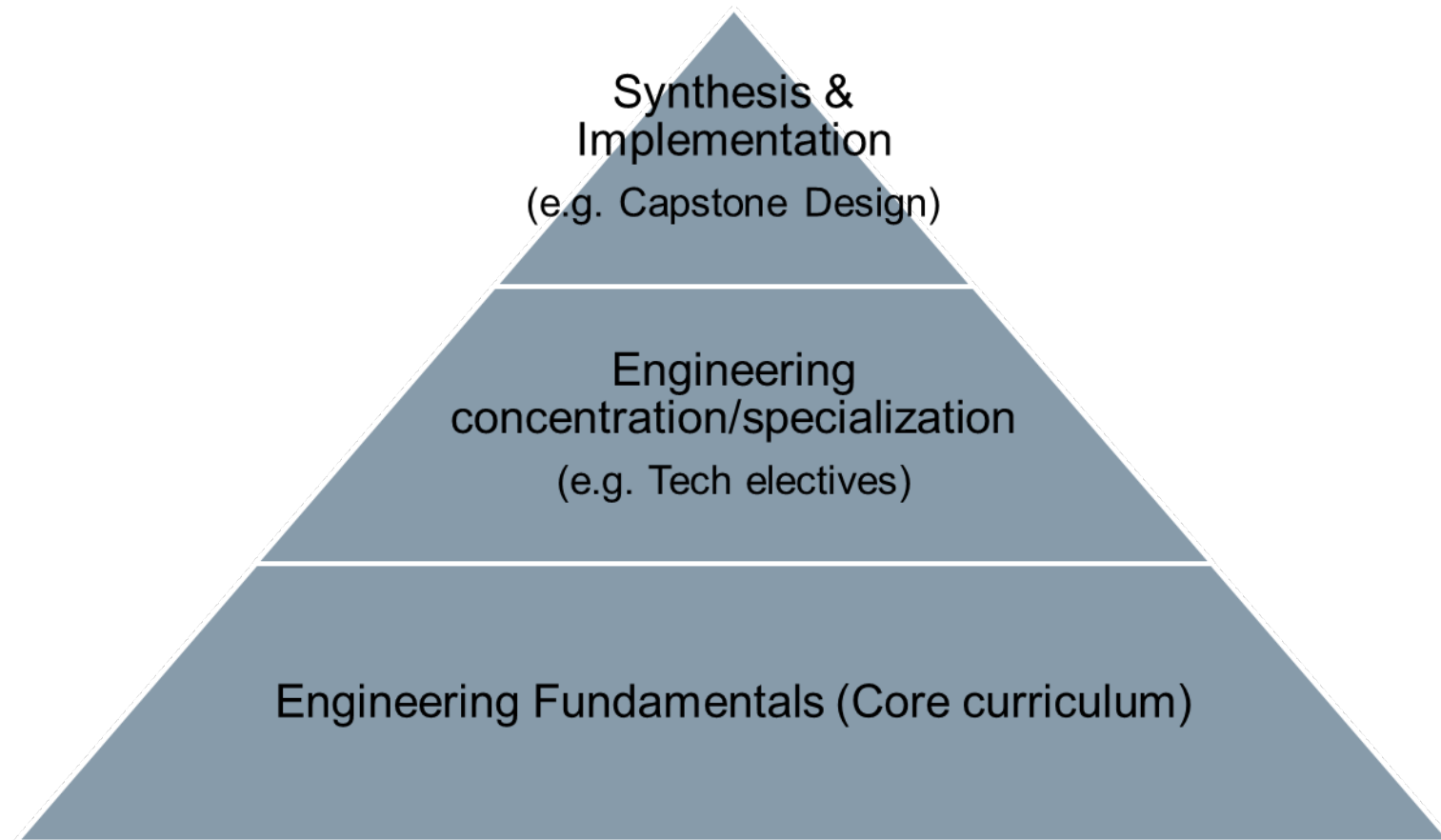
# iMBSE: 3D extension of Capstone Design → 3D extension of CD



**iMBSSE as a 3D extension of Standard Capstone Design**

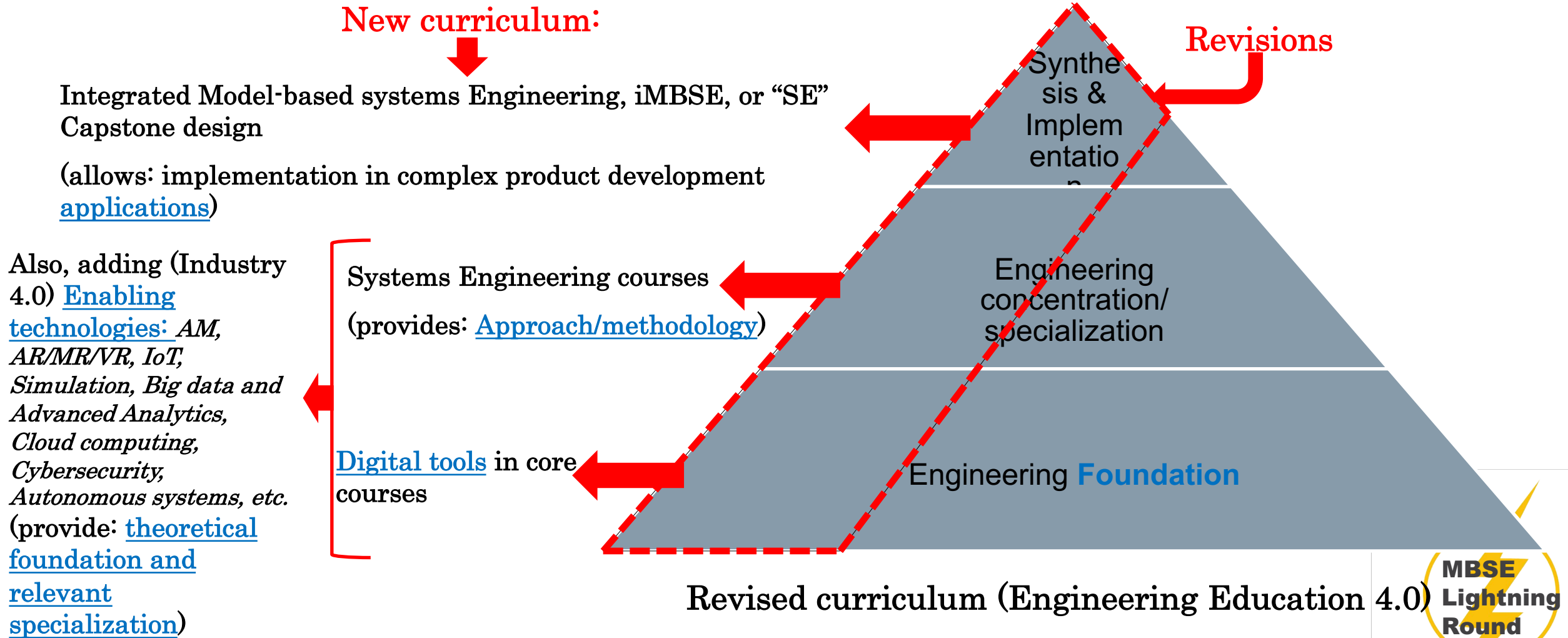


# Curriculum for Industry 4.0: Engineering Education 4.0 → 3 Level curriculum



Three levels of typical Engineering curriculum (e.g. ME)

# Curriculum for Industry 4.0: Engineering Education 4.0 → Revised curriculum (Eng. Education 4.0)



# Curriculum for Industry 4.0: Engineering Education 4.0

## → 3 Level curriculum



### iMBSE curriculum

- It is a unique curriculum that demonstrates the **digitalization of the SE** (Systems Engineering) **process** through the integration of modelling and simulation continuum (in the form of MBSE) with Product lifecycle management (PLM).
- *iMBSE* is a form of MBE (Model-based Engineering) that drives the product lifecycle from the systems requirements and traces back performance to stakeholders' needs through a RFLP traceability process. At the core of this coursework is a shift of focus from theory to implementation and practice, through an *applied synthesis of engineering fundamentals and systems engineering, that is driven by a state-of-the-art digital innovation platform for product (or system) development*. The curriculum provides training to the next generation of engineers for Industry 4.0.





# Curriculum for Industry 4.0: Engineering Education 4.0 → Curriculum of Engineering Education 4.0

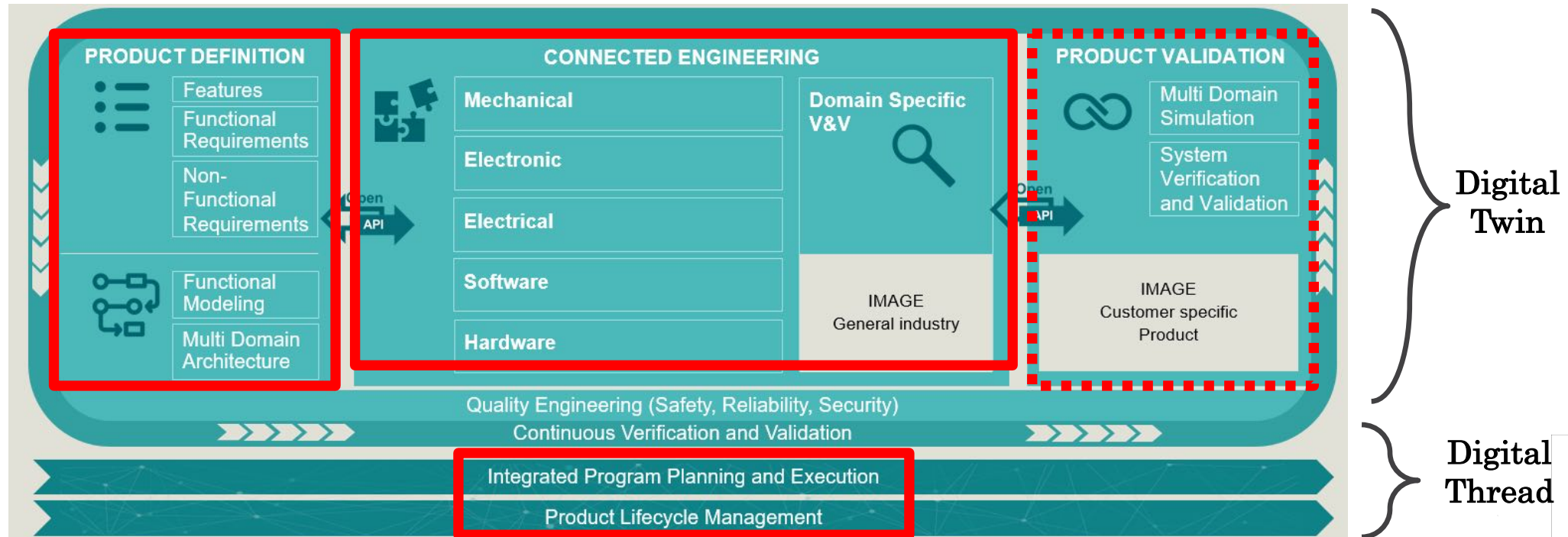


	SE Capstone course (iMBSE)	Typical Capstone course
Process (methodology)	SE process	Design process
Product (application)	Multi-domain system	Mechanical product
Digitalization	Integrated digital platform (to enable both digital twin and digital thread) that spans the lifecycle	Limited digital capabilities

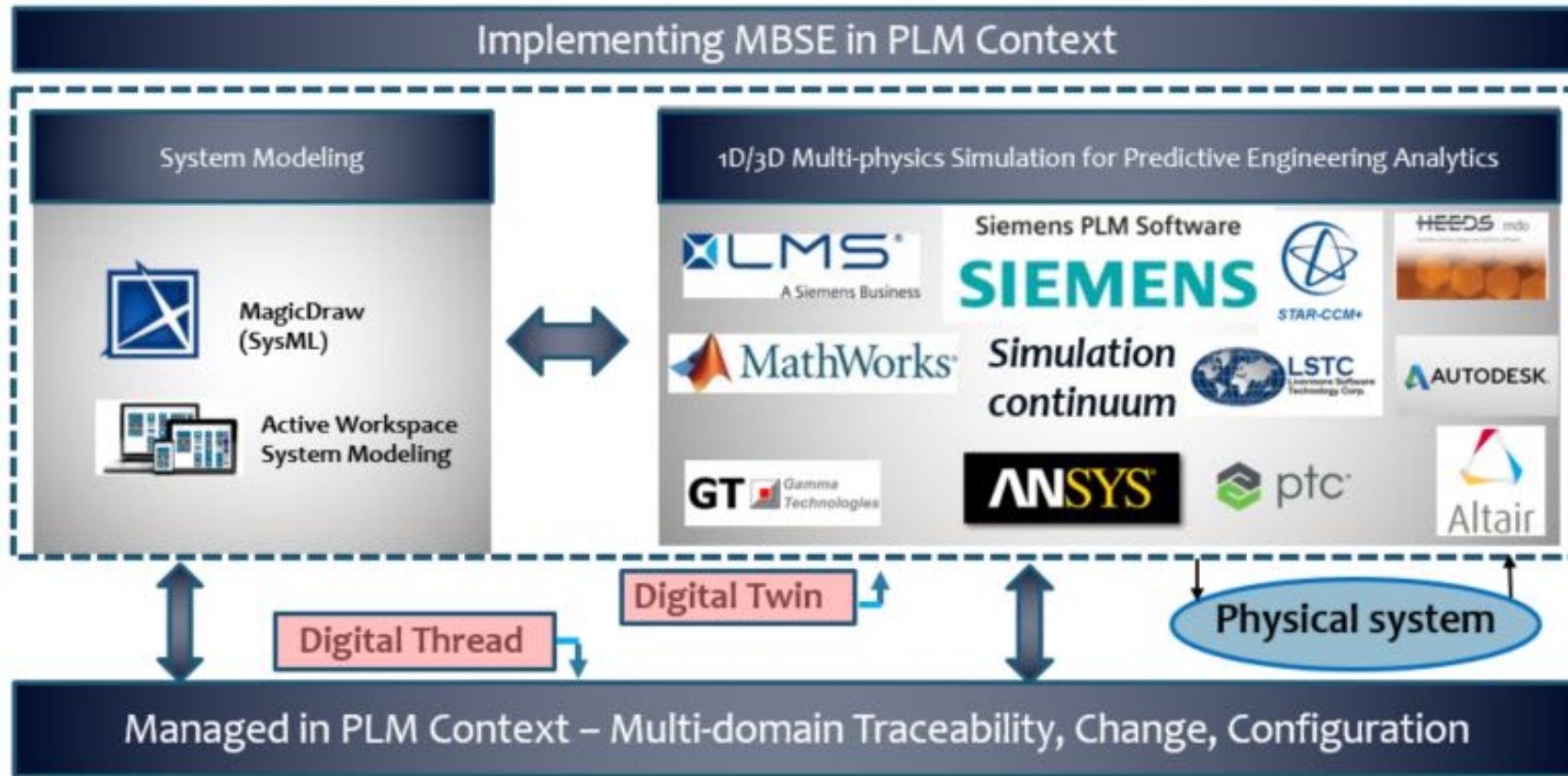
Capstone: Traditional vs. iMBSE driven



# iMBSE: Framework & Digital Innovation Platform for Industry 4.0 → Proposed Siemens iMBSE framework



# iMBSE: Framework & Digital Innovation Platform for Industry 4.0 → Digital Innovation platform for Industry 4.0



Digital Innovation platform for Industry 4.0: Integrating Digital twin with Digital thread



# iMBSE Curriculum



## Main characteristics:

*Digital twin:* Multi-domain architecture integrated with domain specific simulation models

*Digital Thread:* PLM providing integrated platform for multi-domain product architecture, requirements, etc., supporting communication throughout product development

*Traceability:* Linking requirements to design artifacts

MBSE course	MBSE tools	MBSE solution
Model-based Systems Engineering (MBSE) using SysML	Cameo / MagicDraw tool	
Model-based Systems Driven Product Development (SDPD or iMBSE)	Ecosystem of software tools (Siemens digital innovation platform for iMBSE, including Capella tool)	

MBSE curriculum: Two courses offered as part of SE program







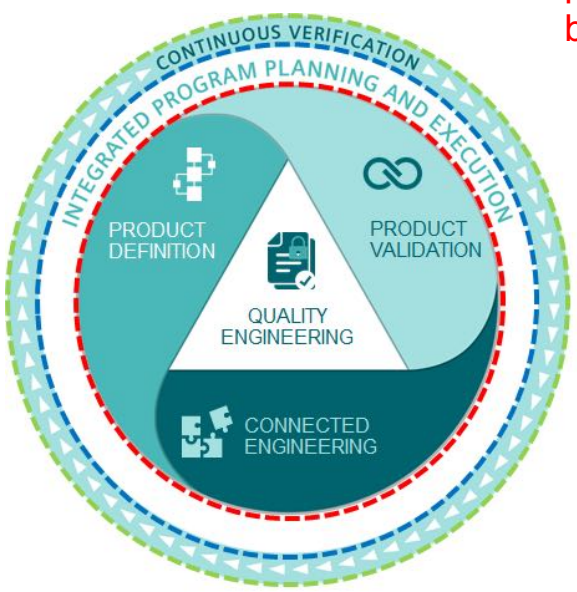
# iMBSE Curriculum (cont')

The iMBSE curriculum consists of three key elements:

- 1) Modelling and simulation continuum;
- 2) Traceability;
- 3) Digital thread.

The digital thread is implemented using **PLM** as the backbone to support the integration of the different models used throughout the development cycle.

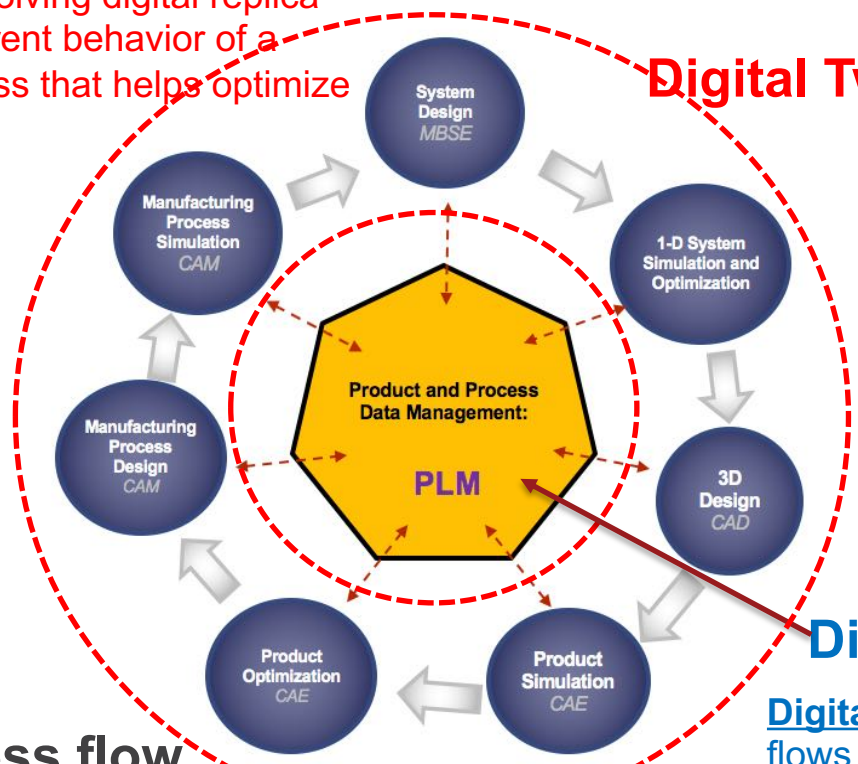
**Digital twin:** A "live", evolving digital replica of the historical and current behavior of a physical object of process that helps optimize business



Implementation in SDPD curriculum



iMBSE process flow



Digital Twin



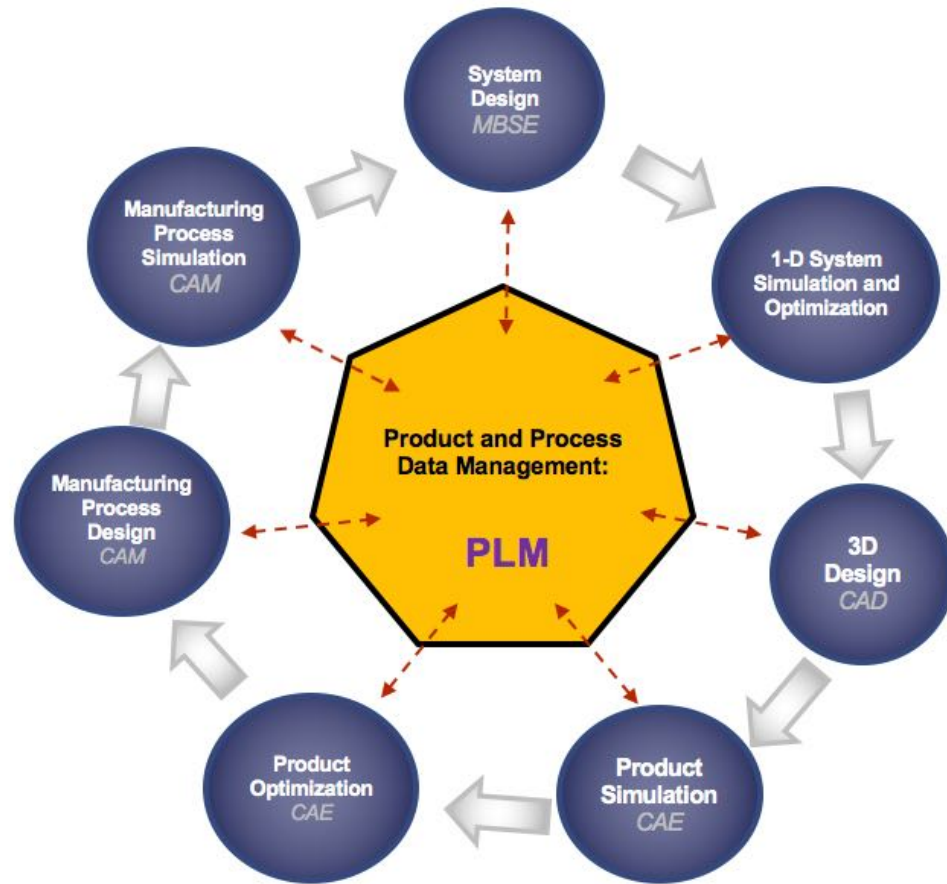
Basic System V diagram

Digital Thread

Digital thread: Connects data flows across lifecycle



# Case study: Electric Skateboard → iMBSE implementation workflow



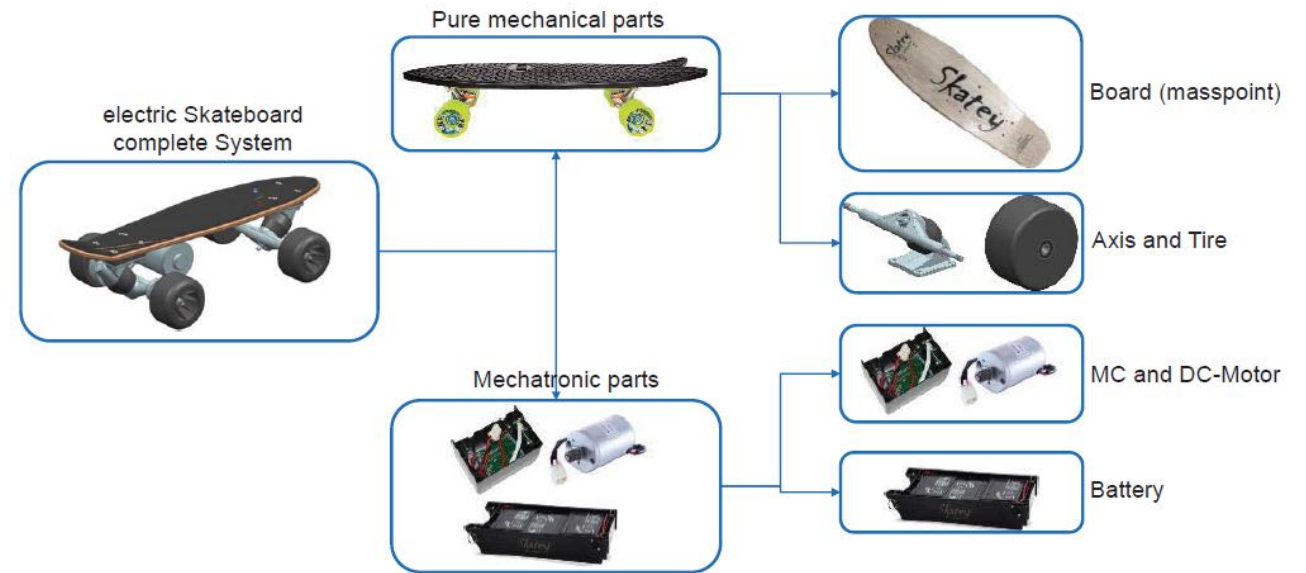
Electric Skateboard – iMBSE implementation workflow







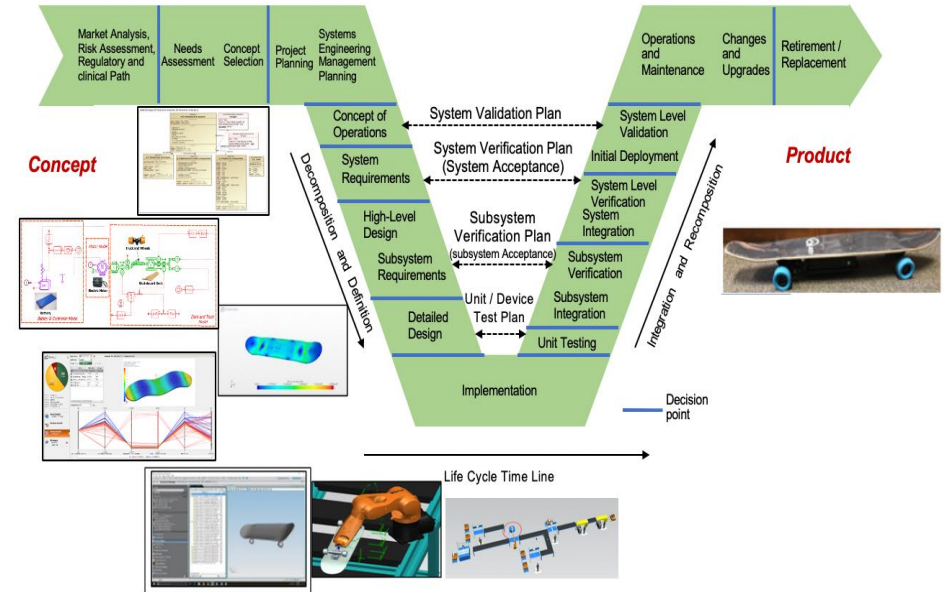
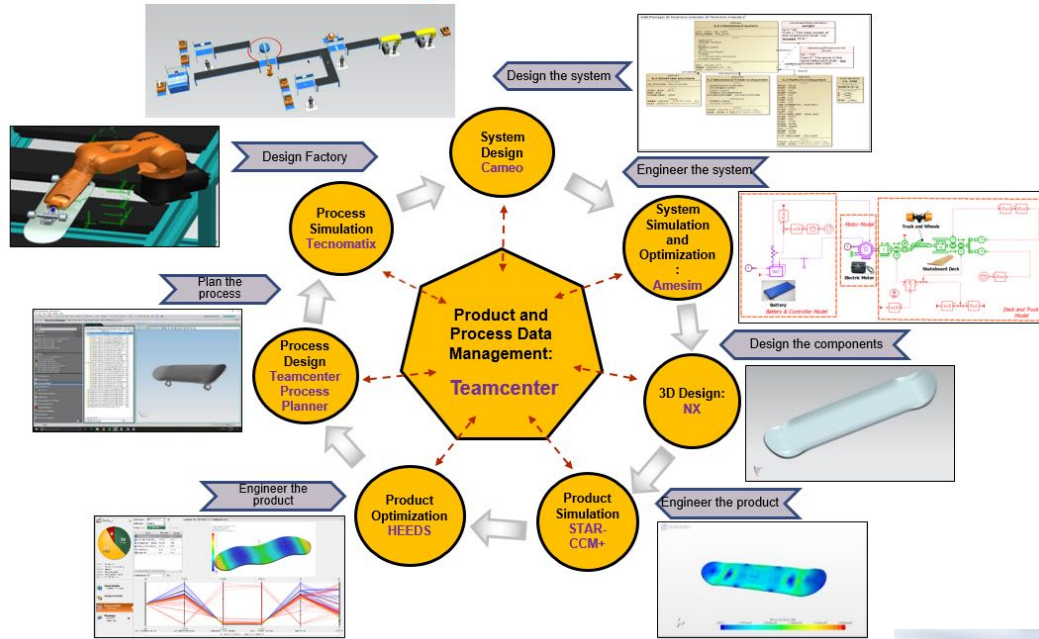
# Practice – Case studies → Electric Skateboard/Longboard



Electric Skateboard as a **multi-domain** system



# Practice – Case studies → Electric Skateboard/Longboard





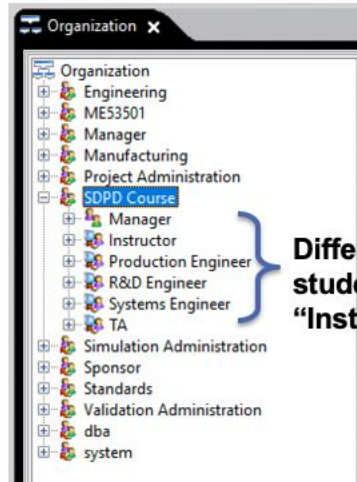
# Practice –Case Studies → Electric Longboard: Project Workflow (Project Definition and Planning)



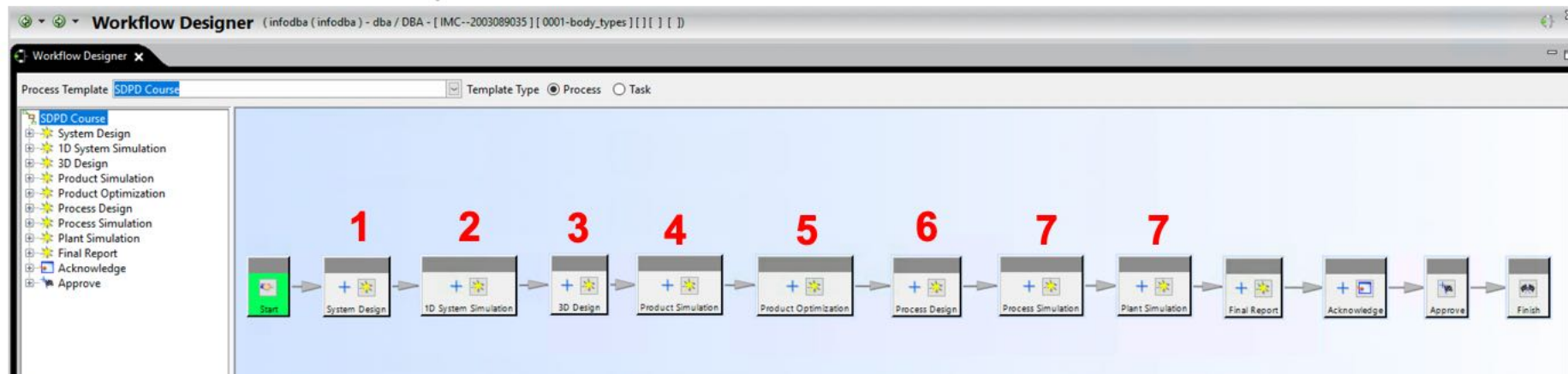
- Creating groups/teams and assigning roles for each team member

Creating workflow process template describing individual tasks and the task sequence required to model the workflow process

## Teamcenter Workflow



Different roles (all for students except “Instructor” and “TA”)



# Practice – Case studies → Electric Longboard: Project Workflow (Project definition and Planning)



## Teamcenter Workflow

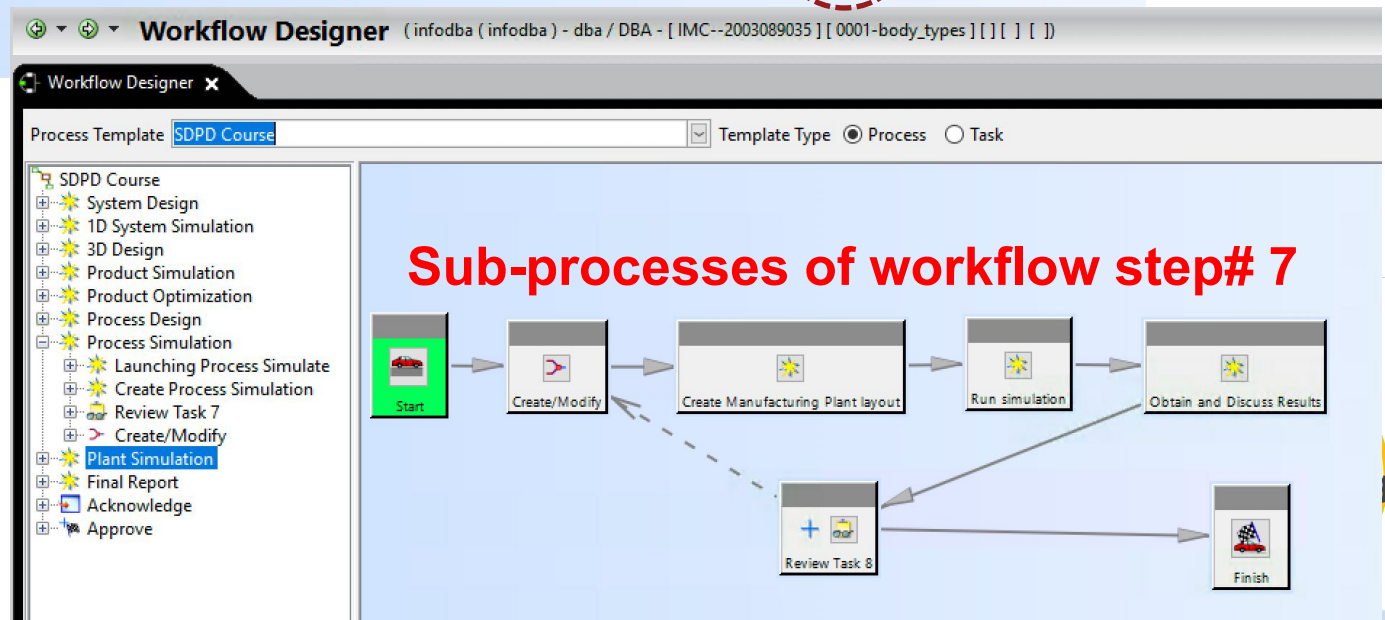
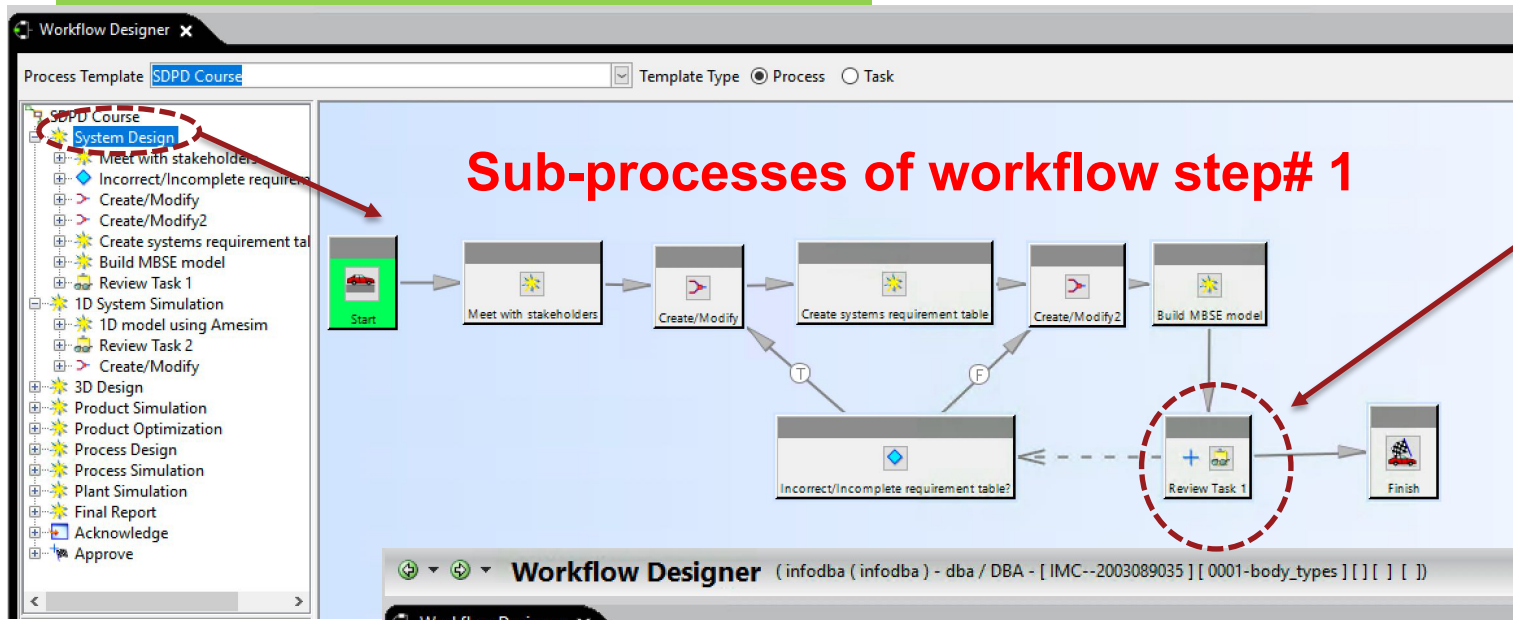
- Each task defines a set of actions, rules, and resources used to accomplish that task

### Workflow steps

Workflow Designer x

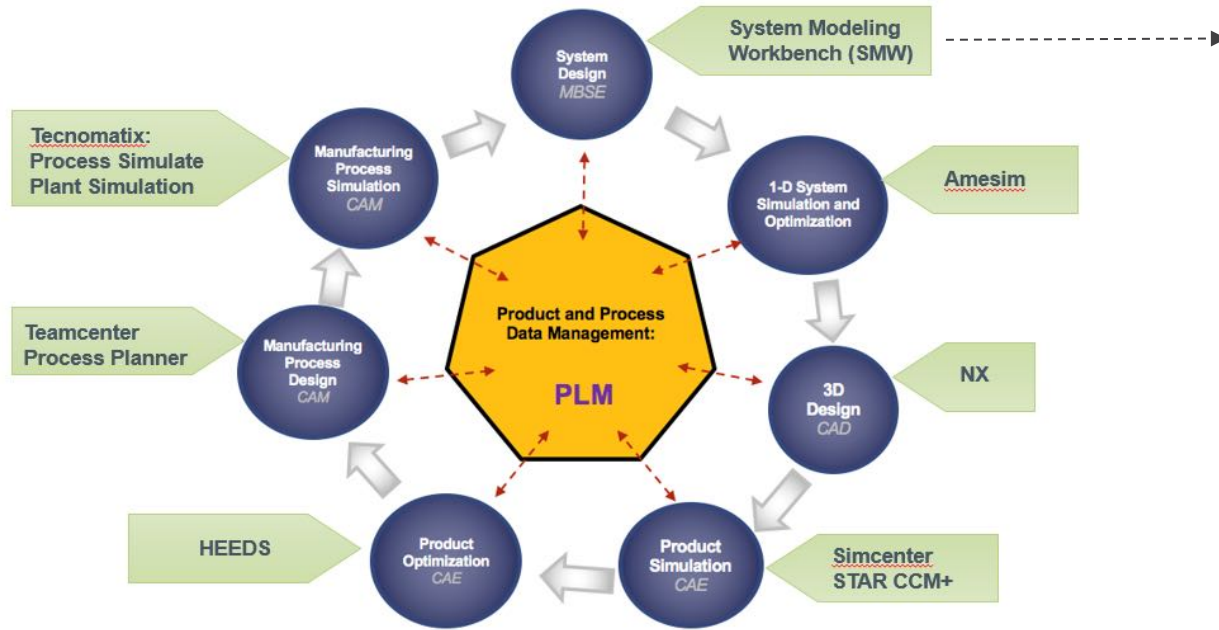
Process Template: SDPD Course

- System Design
- 1D System Simulation
- 3D Design
- Product Simulation
- Product Optimization
- Process Design
- Process Simulation
- Plant Simulation
- Final Report
- Acknowledge
- Approve





# Practice – Case studies → Electric Longboard: System architecture using Systems Modeling Workbench/Cameo



- Model Based Systems Engineering (MBSE)
- Create a systems model and a single source of information
- Requirements, structure, behaviors
- General insight of purpose of creating the Skateboard

**Deliverable: System Architecture of Electric Skateboard**

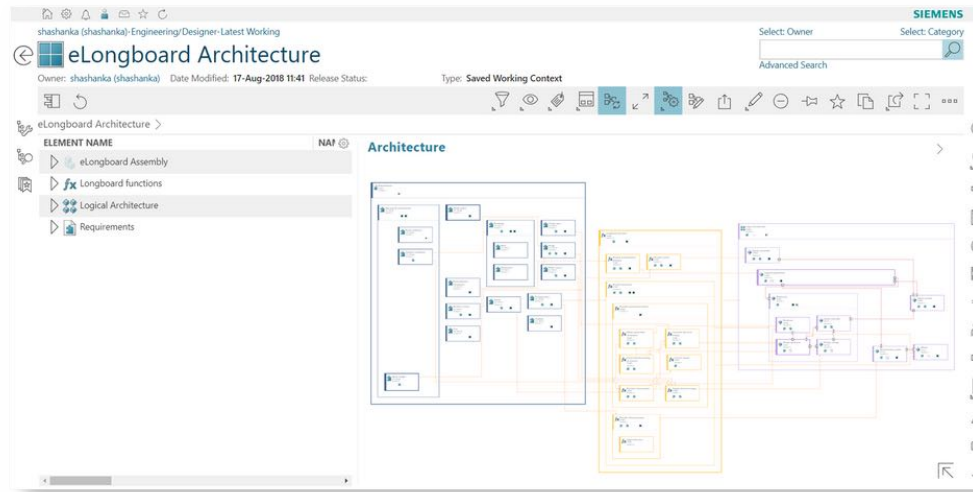
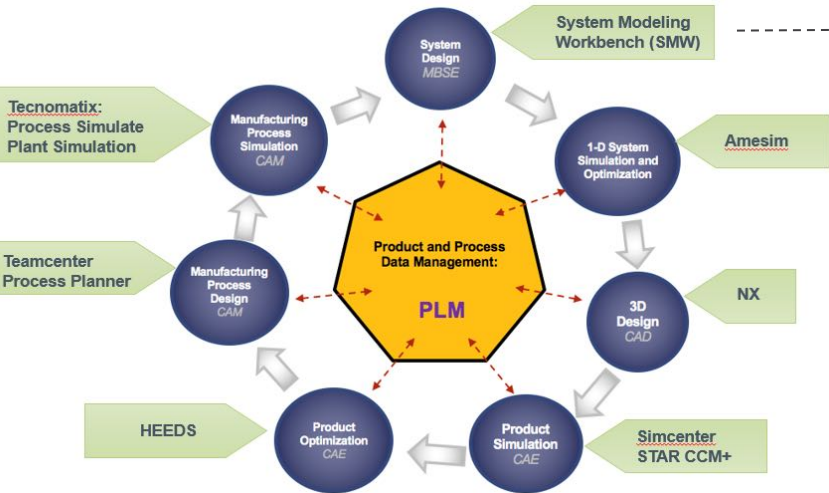
**iMBSE implementation workflow**

#	△ Name	Text
1	<input type="checkbox"/> <input checked="" type="checkbox"/> R 1 SN01	The system shall transport the user <u>at least</u> 10 miles at an average speed of 10 miles per hour in a single charge
2	<input type="checkbox"/> <input checked="" type="checkbox"/> R 1.1 SN01-1	The system shall transport user with a speed <u>greater than</u> 10 meter per second
3	<input type="checkbox"/> <input checked="" type="checkbox"/> R 1.2 SN01-2	The system shall transport user for <u>at least</u> 10 miles in a single charge
4	<input type="checkbox"/> <input checked="" type="checkbox"/> R 2 SN02	The user <u>shall be</u> able to control the speed and stop within safe distance
5	<input type="checkbox"/> <input checked="" type="checkbox"/> R 2.1 SN02-1	The user <u>shall be</u> able to control the speed
6	<input type="checkbox"/> <input checked="" type="checkbox"/> R 2.2 SN02-2	The user <u>shall be</u> able to stop within safe distance
7	<input type="checkbox"/> <input checked="" type="checkbox"/> R 4 SN03	The skateboard shall stop within safe distance
8	<input type="checkbox"/> <input checked="" type="checkbox"/> R 5 SN04	The skateboard <u>shall have</u> speed setting for Novice, Regular and expert levels
9	<input type="checkbox"/> <input checked="" type="checkbox"/> R 6 SN05	The skateboard shall use commercially available off the shelf materials (COTS)
10	<input type="checkbox"/> <input checked="" type="checkbox"/> R 7 SN06	The skateboard shall use readily available energy source with sufficient energy to meet daily needs
11	<input type="checkbox"/> <input checked="" type="checkbox"/> R 8 SN07	The system <u>shall have</u> a portable controller to energize the skating engine, control speed and monitor operation status

**Stakeholder requirements**

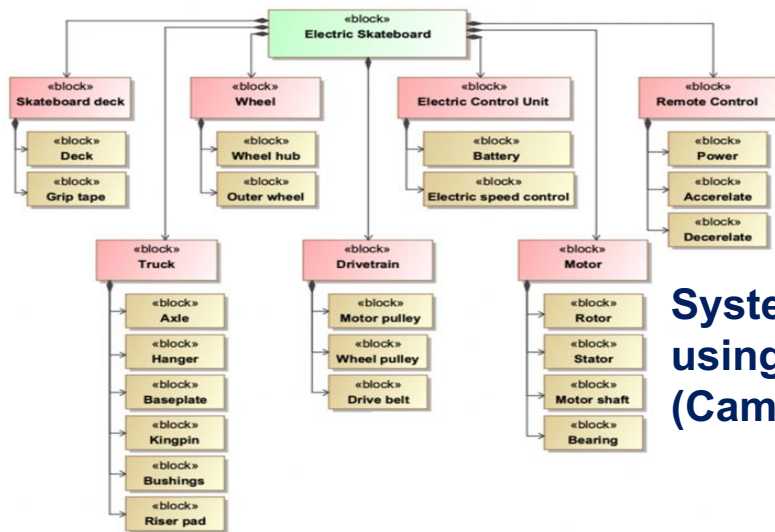


# Practice – Case studies → Electric Longboard: System architecture using Systems Modeling Workbench/Cameo

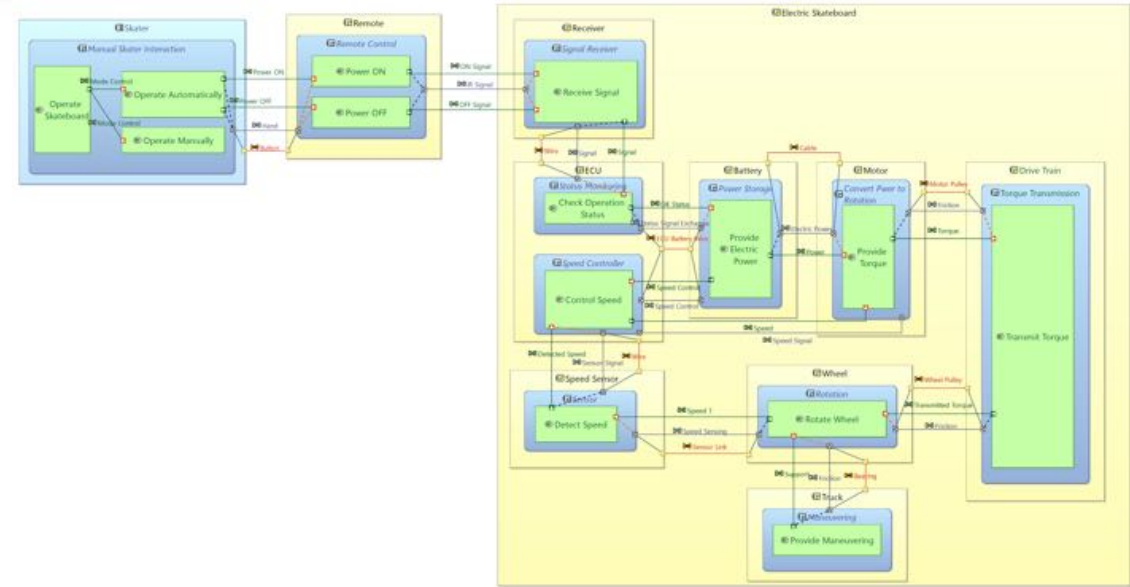


System architecture (Siemens SMW)

## iMBSE implementation workflow



System structure using BDD diagram (Cameo)

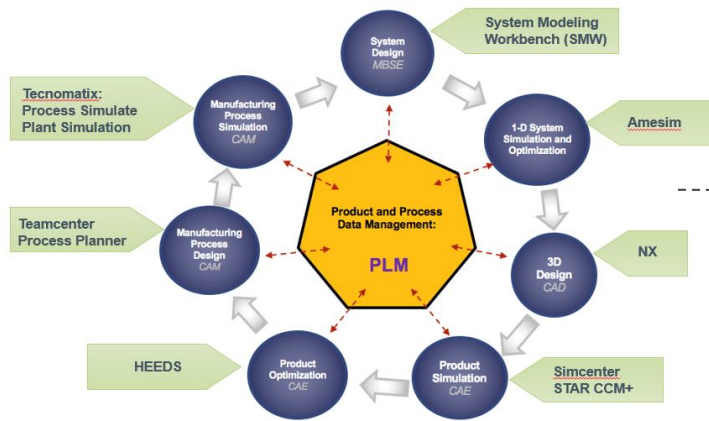


Physical Architecture of E-board (using Capella tool)





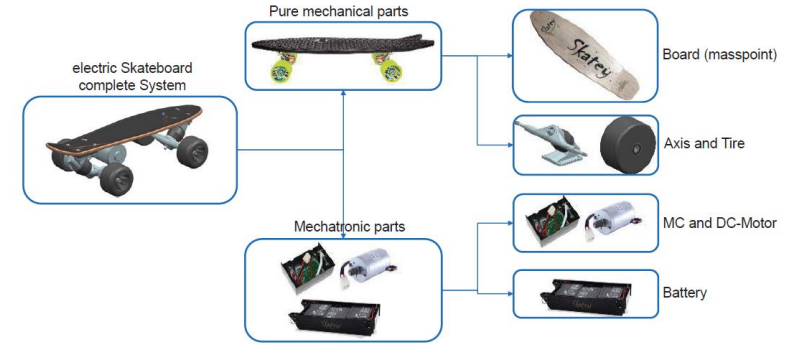
# Practice – Case studies → Electric Longboard: 1D simulation and optimization using Amesim



LMS Imagine. Lab Amesim:

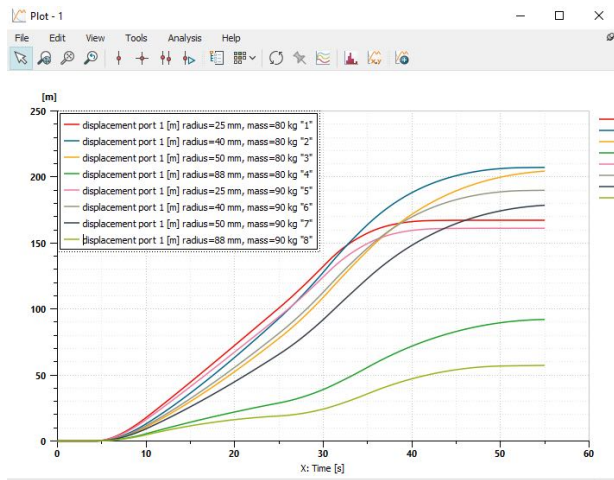
- Modeling and analysis of multi-domain systems
- Create 1D system simulation
- Graphical representation of the whole system
- Performance plots of the skateboard as the output
- Outputs caused by different user's weight

**Deliverable: System Architecture of Electric Skateboard**

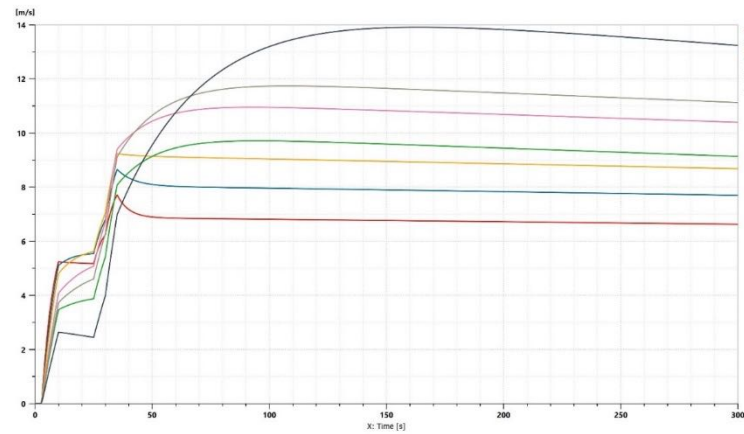


**Electric Skateboard: Multi-domain System**

## iMBSE implementation workflow

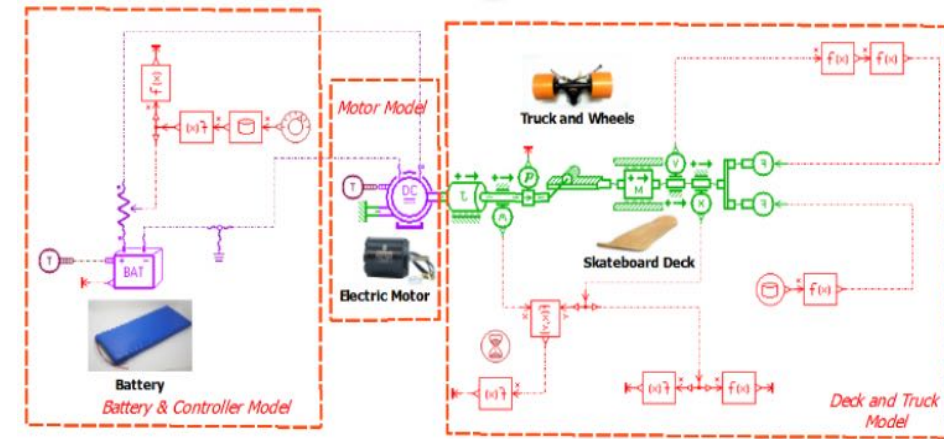


Displacement for different wheel radius & user's weight



Max. velocity for different wheel radius

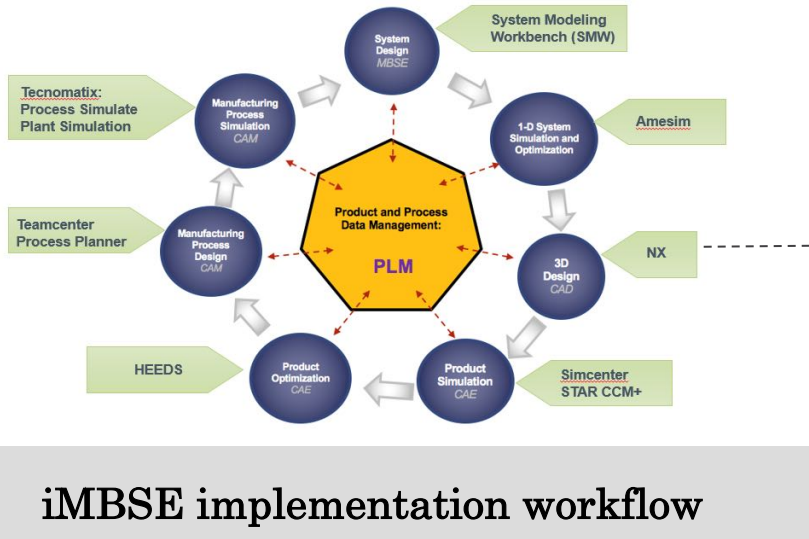
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**1D multi-domain system simulation model (Siemens Amesim)**

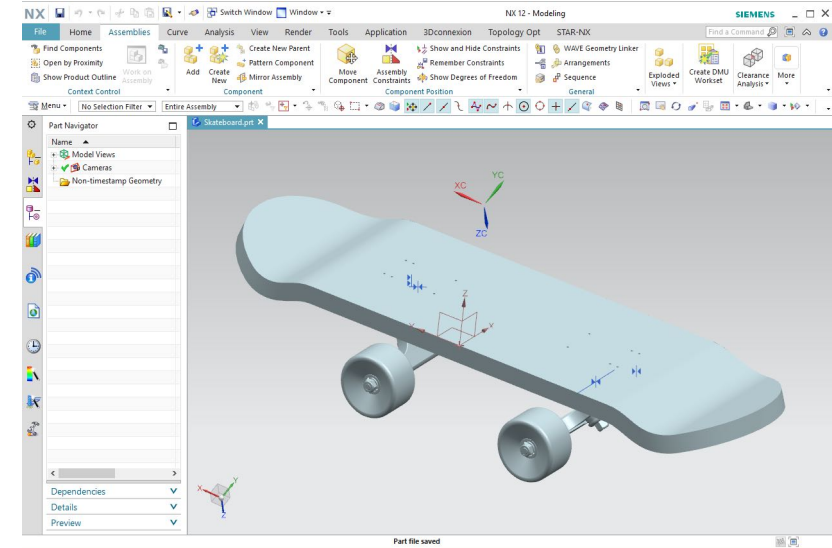


# Practice – Case studies → Electric Longboard: 3D modeling using NX CAD



**NX:**  
• Design and modelling of skateboard

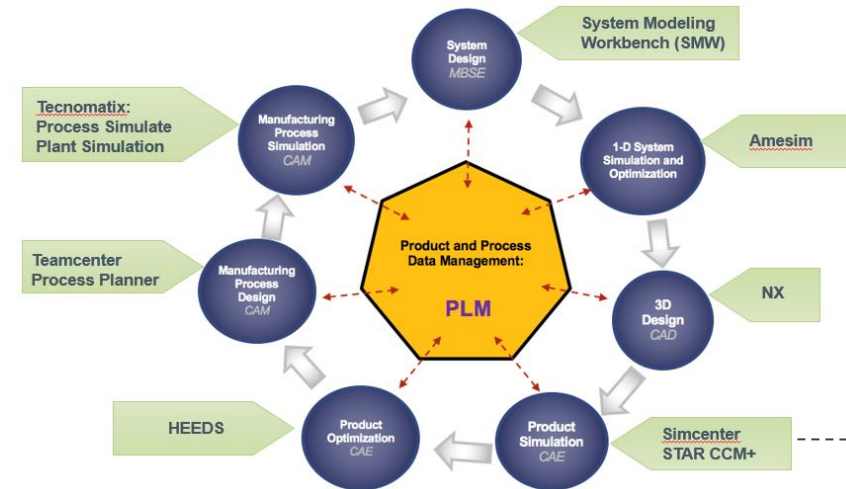
**Deliverable:** 3D model of Electric Skateboard



3D model of Skateboard



# Practice – Case studies → Electric Longboard: 3D simulation using NX Nastran / Star-CCM+

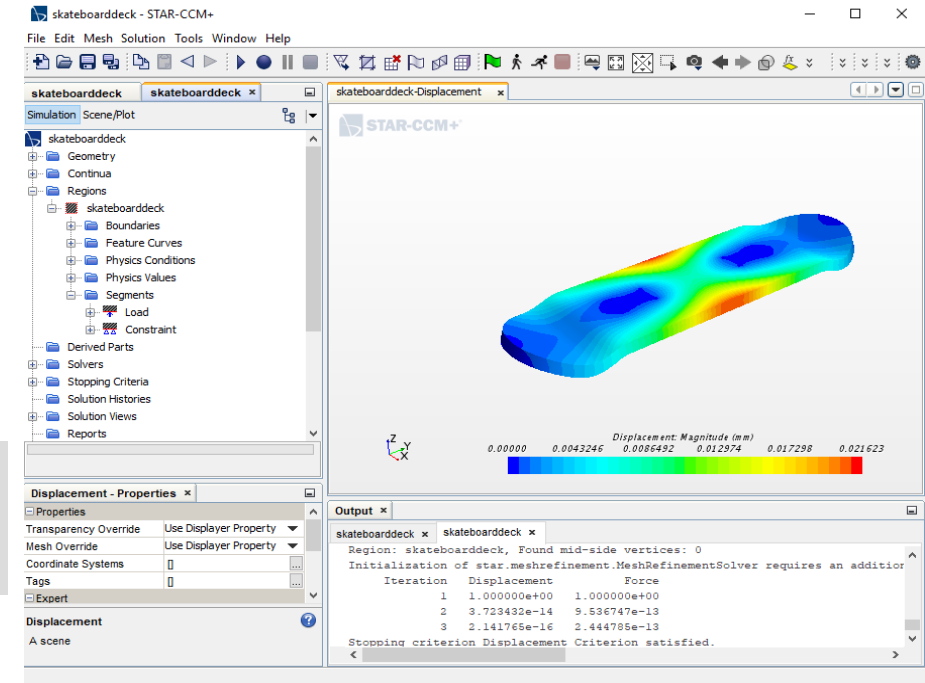


iMBSE implementation workflow

Star-CCM+ / Nastran:

- CFD and Structural analysis
- The structural analysis of the board with static loads 200 lb
- Von-Mises stress and displacement of the board

Deliverable: 3D Simulation model of Electric Skateboard

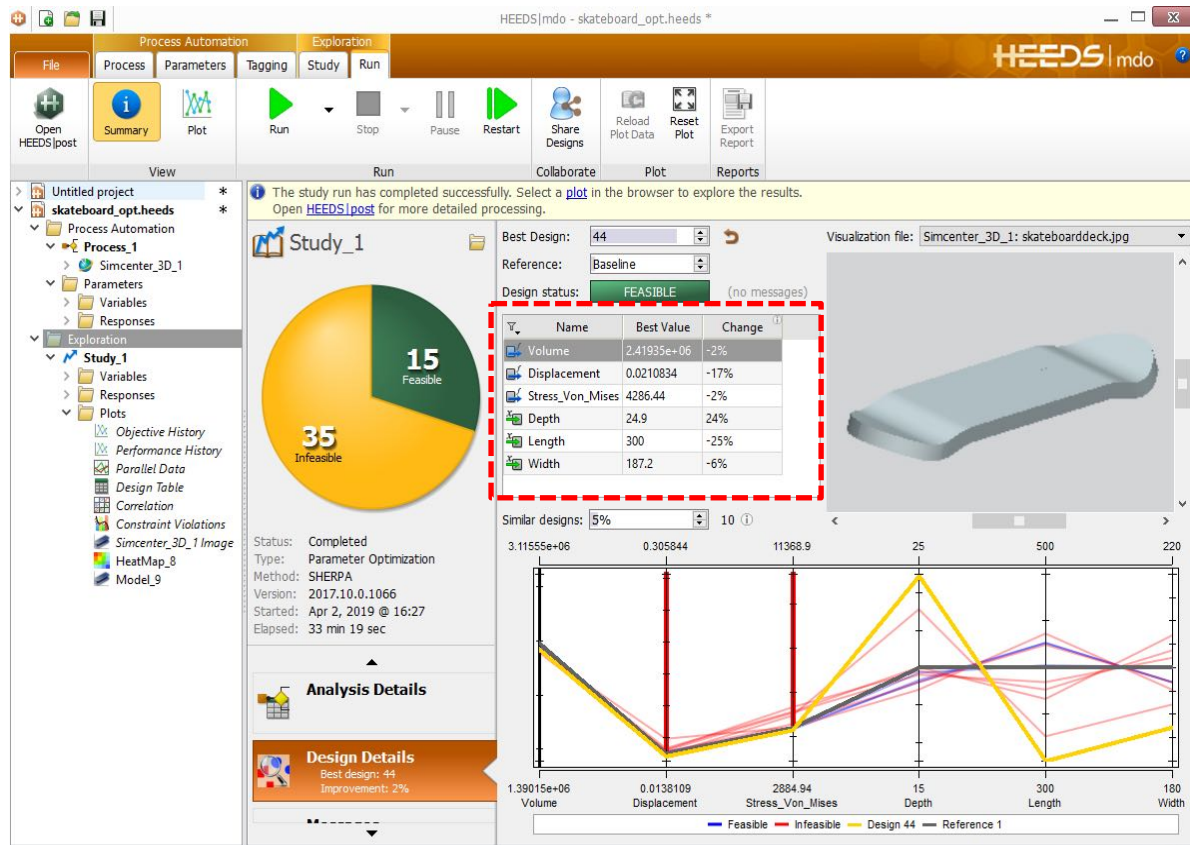


3D simulation: Von-Mises stress in skateboard deck





# Practice – Case studies → Electric Longboard: 3D optimization using HEEDS

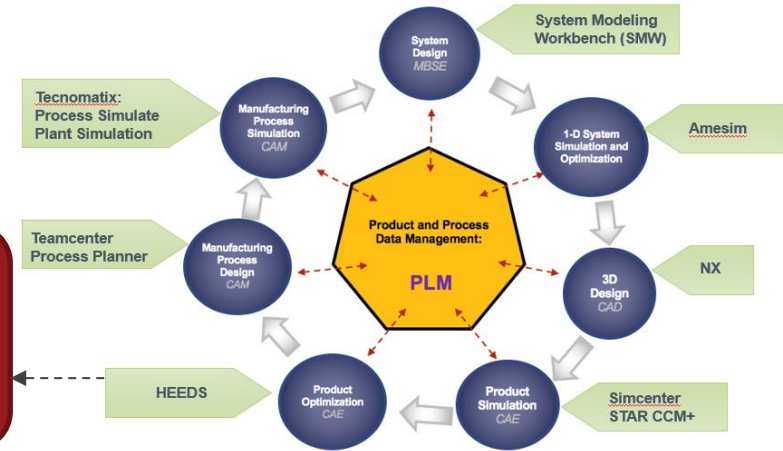


Optimization of 3D geometry of skateboard deck

HEEDS (Hierarchical Evolutionary Engineering Design System):

- Optimization for better and more robust solutions within a given design space

**Deliverable:**  
Optimized 3D deck geometry



**iMBSE implementation workflow**



# Practice – Case studies → Electric Longboard: Manufacturing process design using MPP



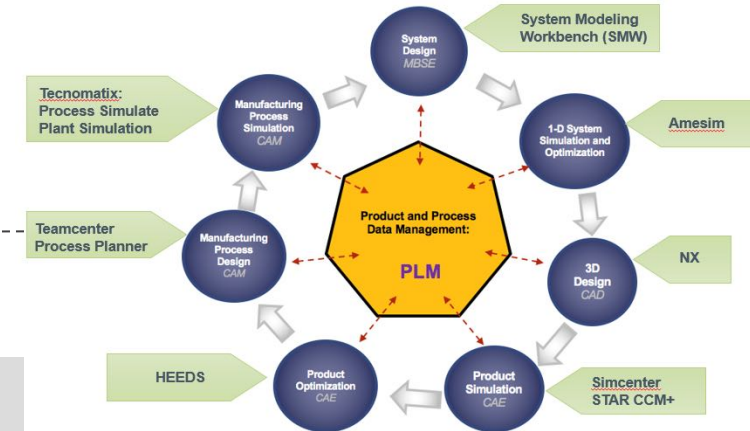
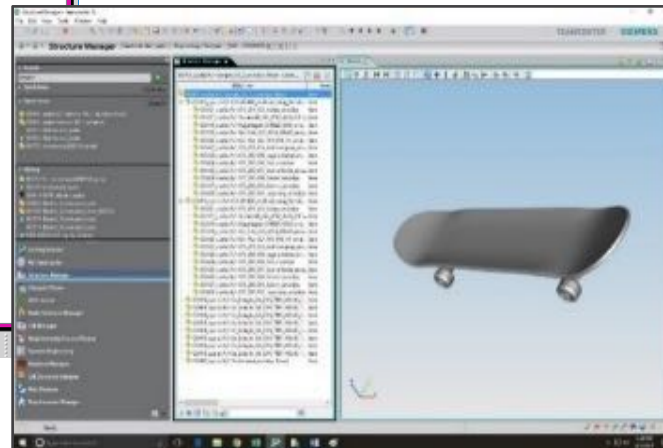
Teamcenter Manufacturing Process Planner (MPP):

- Product Lifecycle Management (PLM)
- Develop product and manufacturing process
- Manage manufacturing data, process, resource and plant information
- Seamless alignment between engineering bill of materials (BOM), manufacturing BOM and the manufacturing bill of process (BOP)

**Deliverables: Manufacturing Process (BOM, BOP, etc.) of Electric skateboard assembly**

BOM Line	Item Description
003925/A;1-Skateboard_Process_PS	Skateboard_Process_PS
003926/A;1-Final_Assy_PS	Final_Assy_PS
003927/A;1-Front_Assy_PS	Front_Assy_PS
078.201.000_Aufhaengung/Skateboard;1	078.201.000_Aufhaengung
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
078.201.026/Skateboard;1	078.201.026
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
003923/A;1-Front_Assy_PS	Front_Assy_PS
kawasaki_uz100/A;1	kawasaki_uz100
gripper/A;1	gripper
vr5264280_cnv.cojt/A;1	vr5264280_cnv
box_gripper/A;1	box_gripper
fin gripper/A;1	fin gripper
kr6_r700sixx/A;1	kr6_r700sixx
003928/A;1-Rear_Assy_PS	Rear_Assy_PS
box_gripper/A;1	box_gripper
fin gripper/A;1	fin gripper
kawasaki_uz100/A;1	kawasaki_uz100
kr6_r700sixx/A;1	kr6_r700sixx
078.201.000_Aufhaengung/Skateboard;1	078.201.000_Aufhaengung
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
Se-Schr In-6kt DIN 7991-M5x10/A;1	Se-Schr In-6kt DIN 7991-M5x10
003924/A;1-Rear_Assy_PS	Rear_Assy_PS
vr5264280_cnv.cojt/A;1	vr5264280_cnv
Final_Assy_PS	Final_Assy_PS
box_gripper/A;1	box_gripper
kawasaki_uz100/A;1	kawasaki_uz100

**BOM of Skateboard**



**iMBSE implementation workflow**



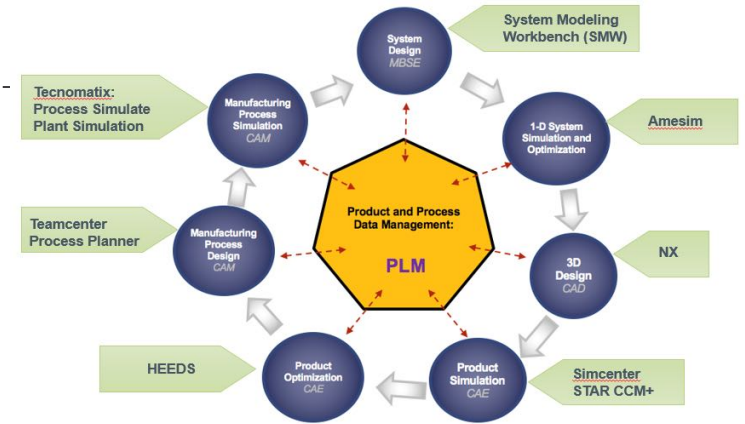
# Practice – Case studies → Electric Longboard: Manufacturing Process simulation using Tecnomatix



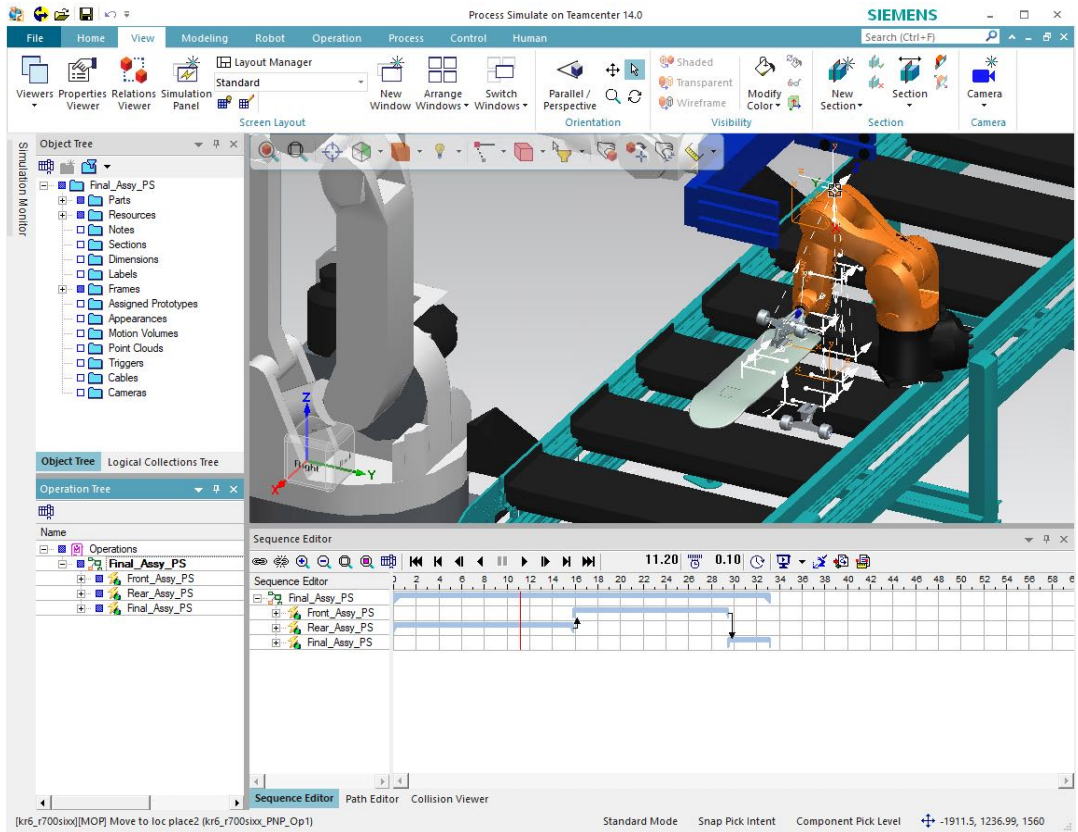
Tecnomatix Process Simulate :

- Simulation and optimization of production systems and processes
- Taking skateboard through assembly
- Verify reachability and collision clearance
- Simulating the full assembly sequence of the product and the required tools

**Deliverable:** Simulation model of Electric skateboard assembly



**iMBSE implementation workflow**

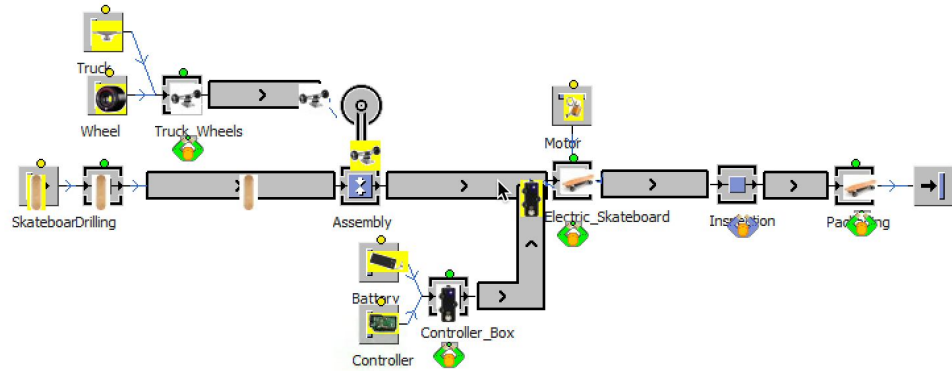


**Simulation of Skateboard assembly**





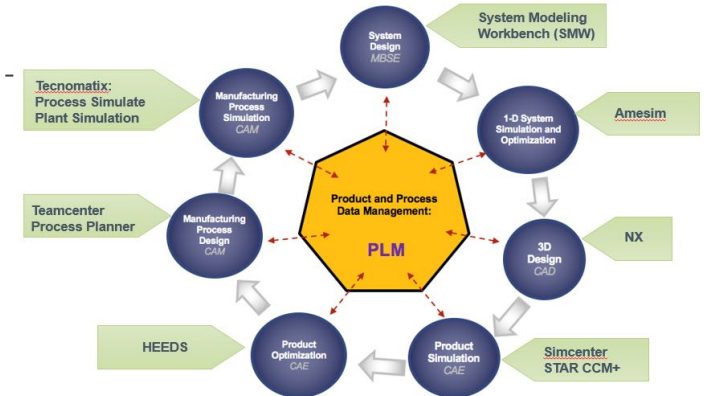
# Practice – Case studies → Electric Longboard: Plant Simulation using Tecnomatix



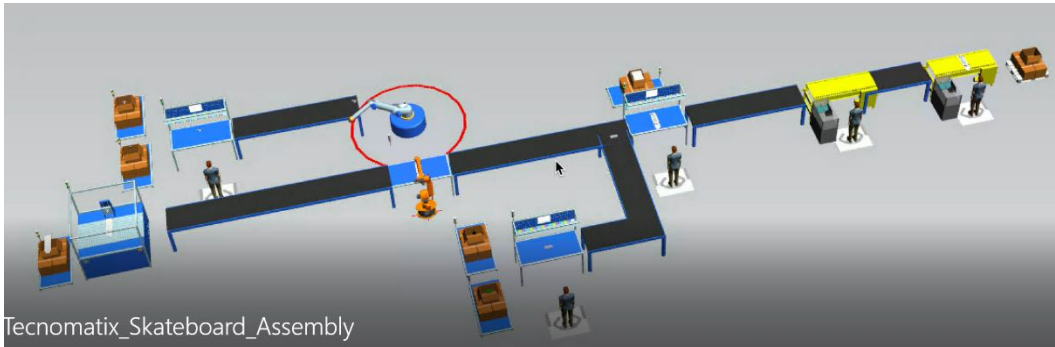
**Tecnomatix Process Plant Simulation:**

- Simulation and optimization of production systems and processes
- Taking skateboard through production
- Simulating the full production of the product

**Deliverable: Simulation model of Electric skateboard production line**



**iMBSE implementation workflow**



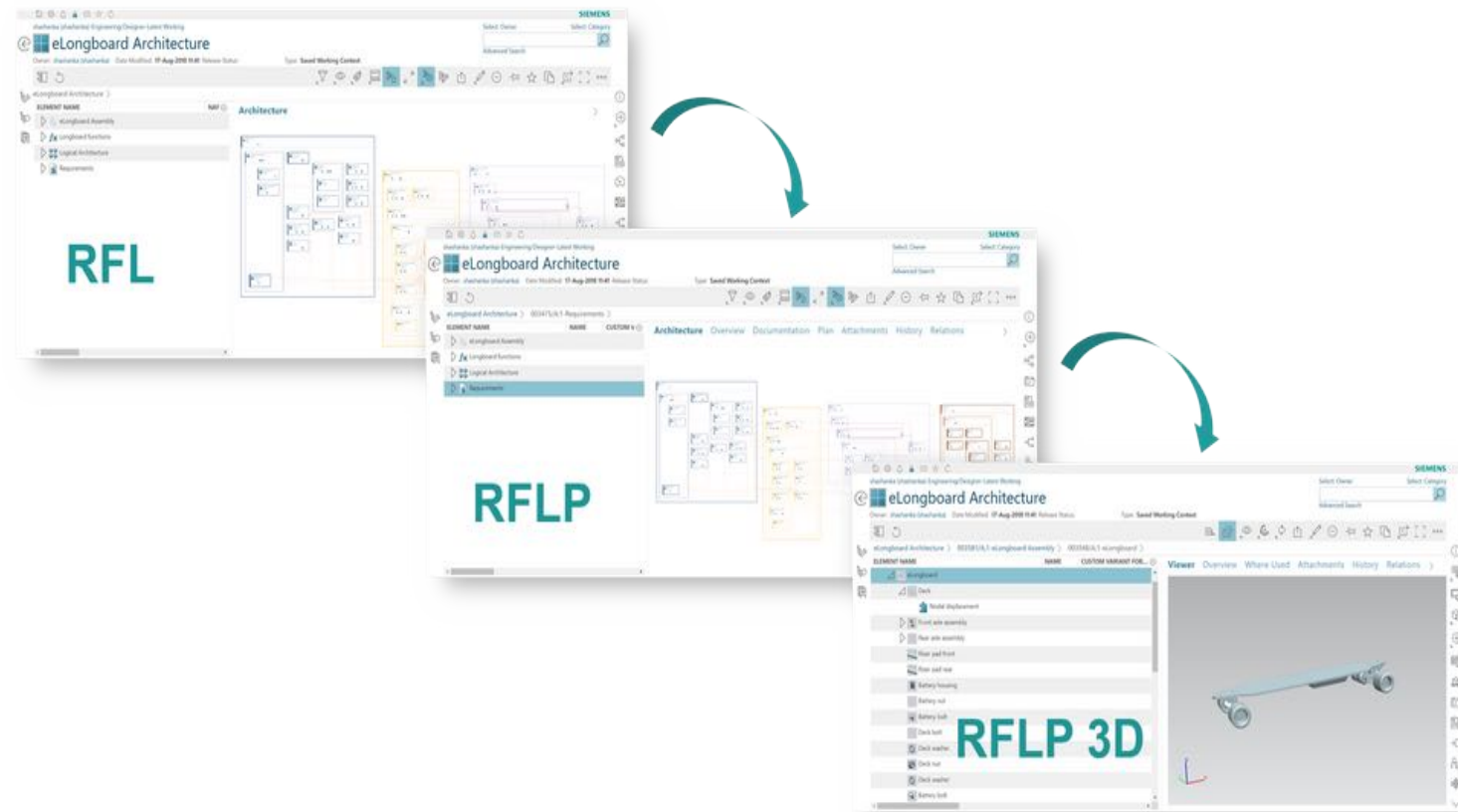
Tecnomatix\_Skateboard\_Assembly

**Simulation of Skateboard production line (Top: 2D; Bottom: 3D)**





# Practice – Case studies → Electric Longboard: Traceability

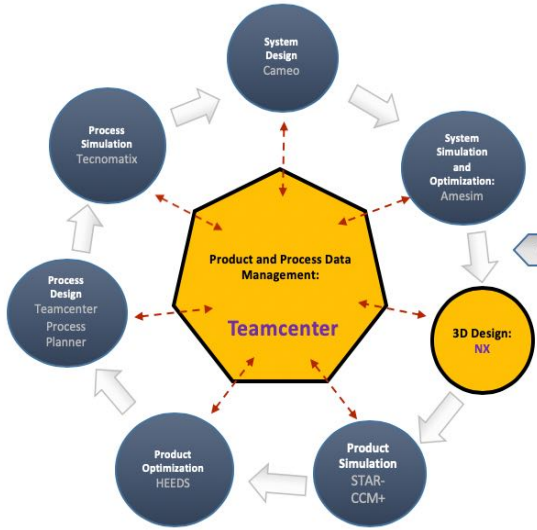


Electric Skateboard/Longboard RFLP

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# Practice – Case studies → Electric Longboard: Traceability → TC ↔ NX



**iMBSE  
implementation  
workflow**

The screenshot shows the Siemens Teamcenter 10 Systems Engineering interface. The top window displays the BOM for "SkateboardDeckRP/A;1". The bottom window shows the Traceability table for the same scope.

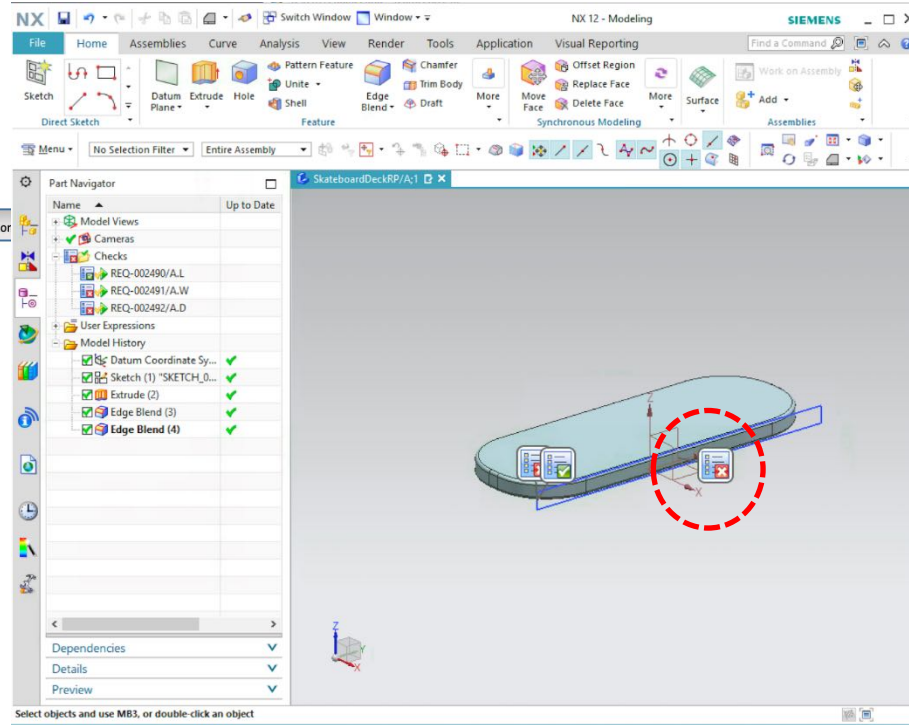
Defining Object	Type	Complying ...	Defining Co...
SkateboardDeckRP/A;1	Item Revision		
REQ-002491/A;1-Width	Validation Requirement...		
REQ-002490/A;1-Length	Validation Requirement...		
REQ-002492/A;1-Depth	Validation Requirement...		

- NX Design
- Create traceability between requirements and Design geometry (3D model)

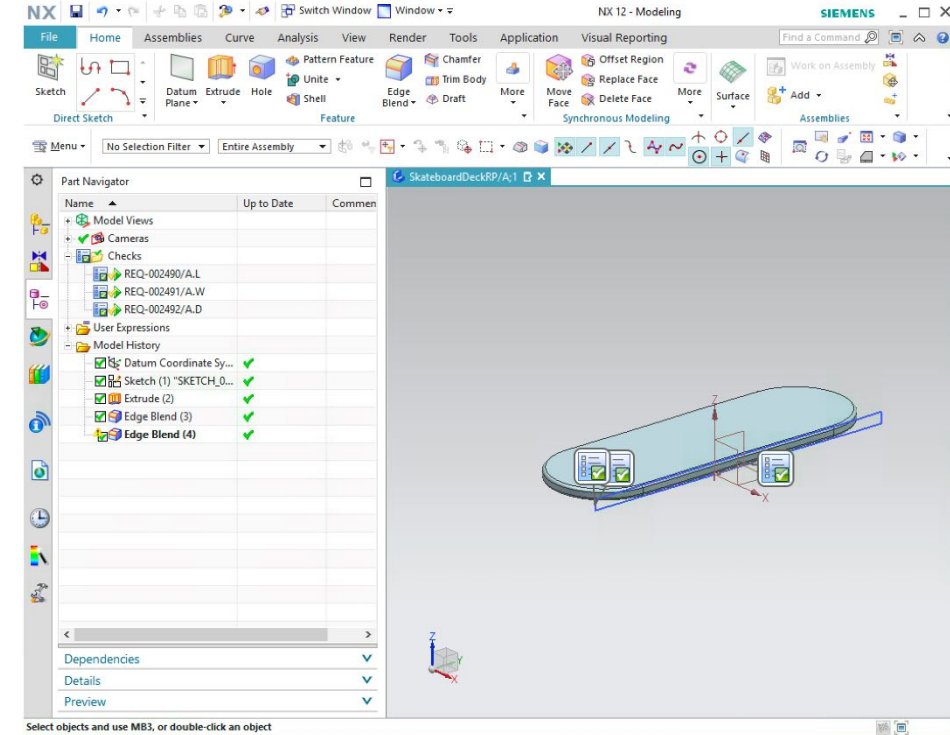
**Deliverable: 3D NX design linked to validation requirements in TC SE**

The screenshot shows the Siemens NX 12.0 Modeling interface. The main window displays a 3D model of a skateboard deck. The left-hand side shows the Part Navigator with a tree structure including "Model Views", "Cameras", "Checks", "User Expressions", and "Model History". The "Checks" folder is expanded, showing a list of validation requirements: "REQ-002490/A.L", "REQ-002491/A.W", and "REQ-002492/A.D". The "Model History" shows features like "Datum Coordinate Sy...", "Sketch (1) 'SKETCH\_D...", "Extrude (2)", "Edge Blend (3)", and "Edge Blend (4)".

# Practice – Case studies → Electric Longboard: Traceability → TC ↔ NX (cont')



The validation results failed two of the requirements.

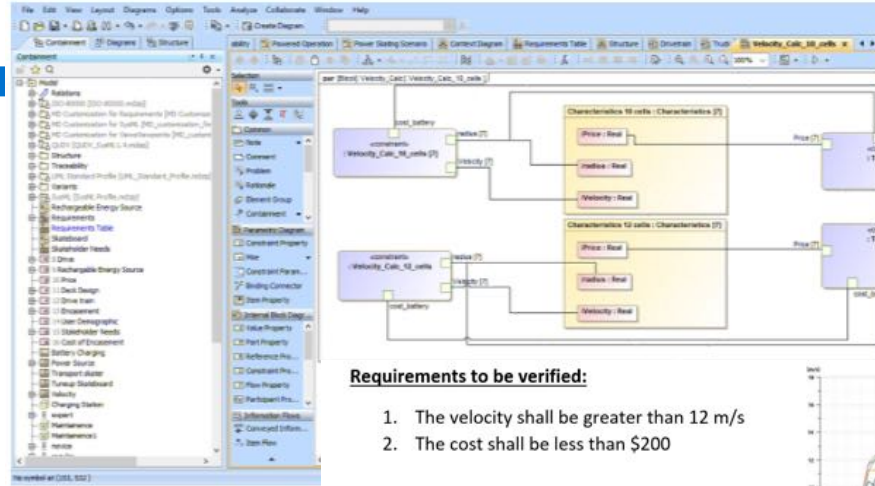
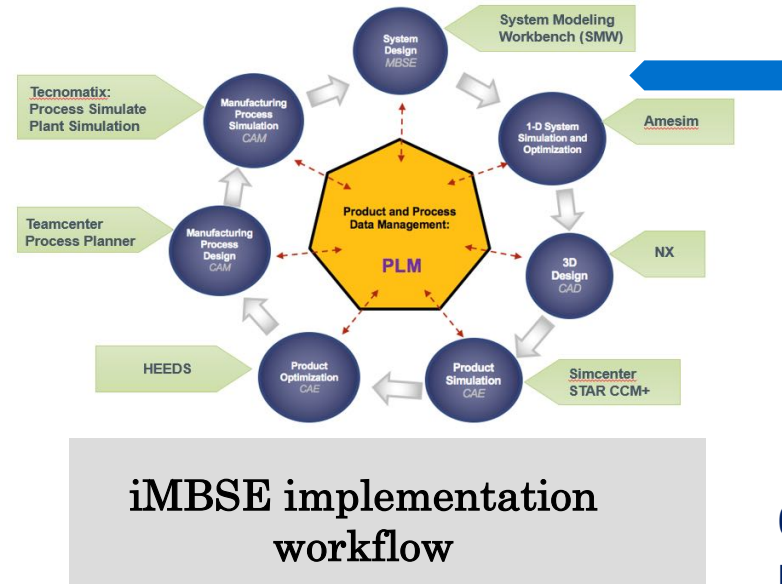


The validation results passed all the requirements.





# Practice – Case studies → Electric Longboard: Traceability → Cameo ↔ Amesim



- 1D Simulation model
- 0D requirement model

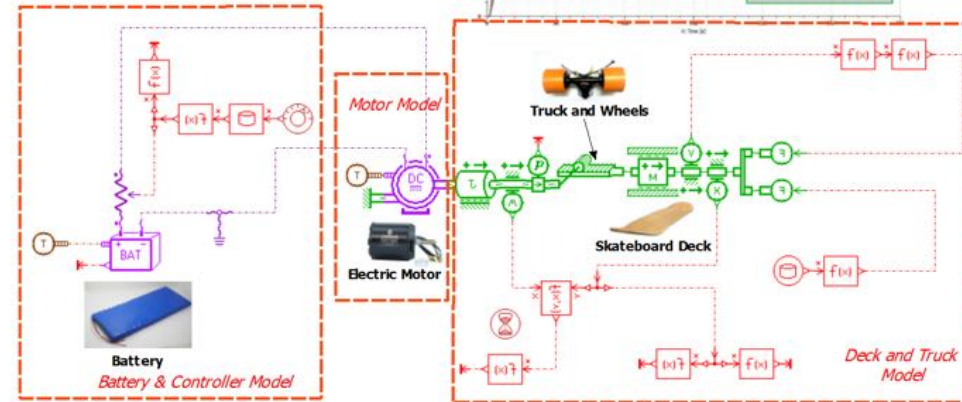
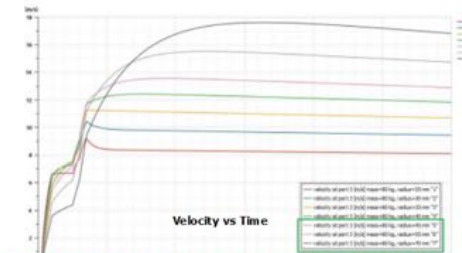
**Deliverable:** System design that meets requirements

**Requirements to be verified:**

1. The velocity shall be greater than 12 m/s
2. The cost shall be less than \$200

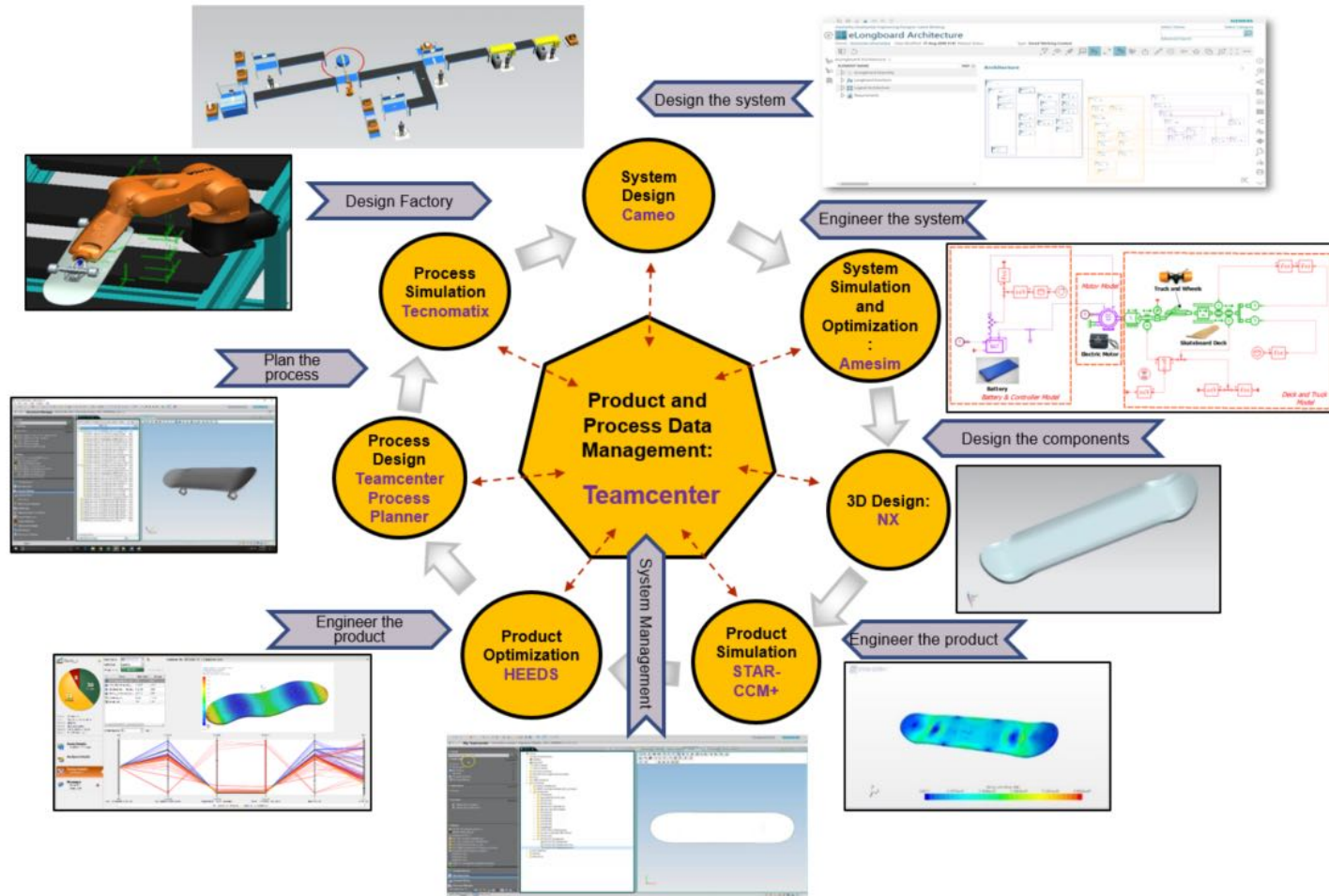
**Parameters to be varied:**

1. Wheel radius
2. Battery size (# of cells)



1D Simulation for predicting system's performance: Max. velocity, etc,

# Practice – Case studies → Electric Longboard: Summary of digital implementation

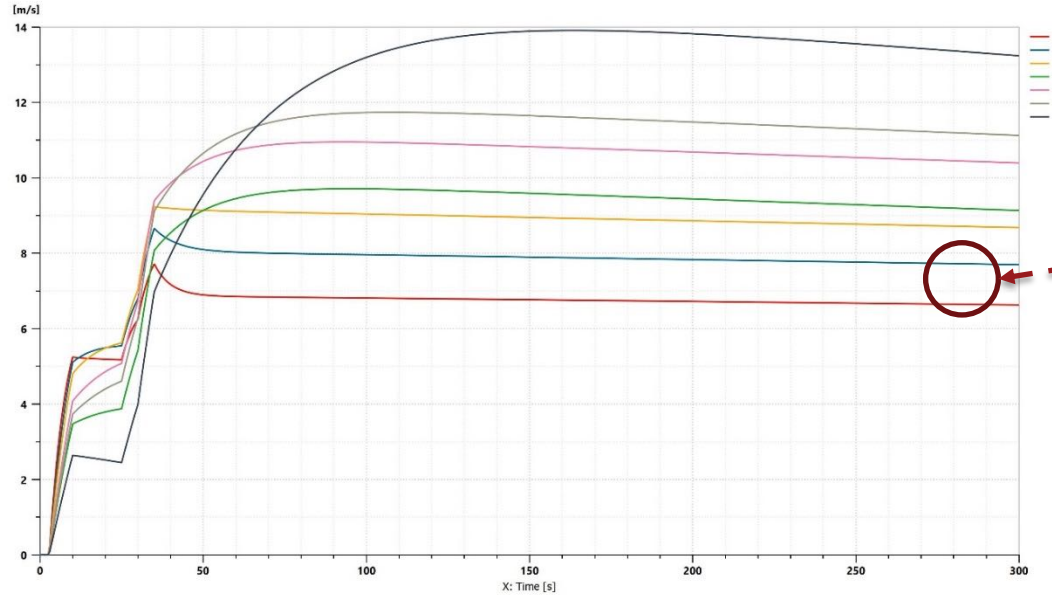


Implementing iMBSE workflow: Summary of deliverables

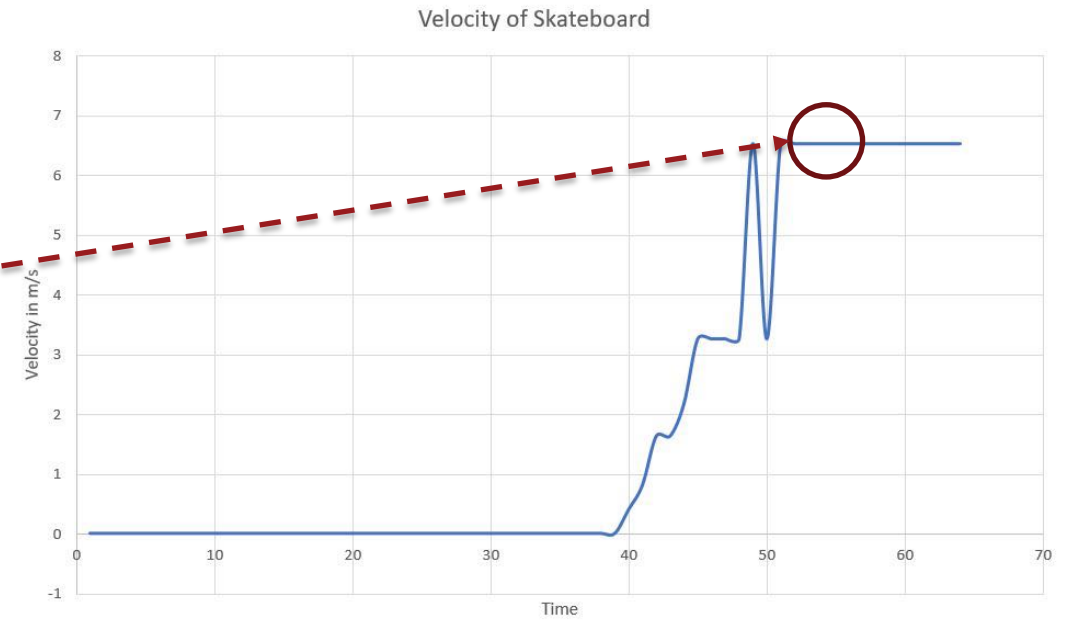




# Practice – Cases studies → Electric Longboard: Validation



Simulation results from Amesim 1D (Digital twin)



Experimental results from Optical Encoder (Physical)

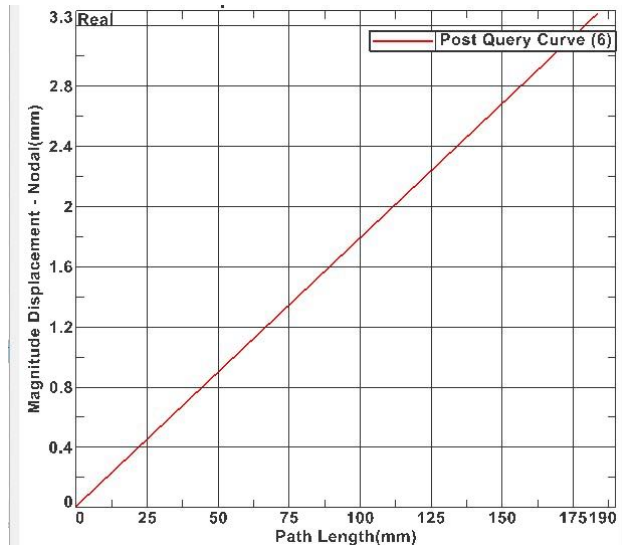
Velocity m/s (no load condition)	
Amesim	6.8
Optical Encoder	6.6

Electric Sakerboard/Longboard Validation: Max. velocity

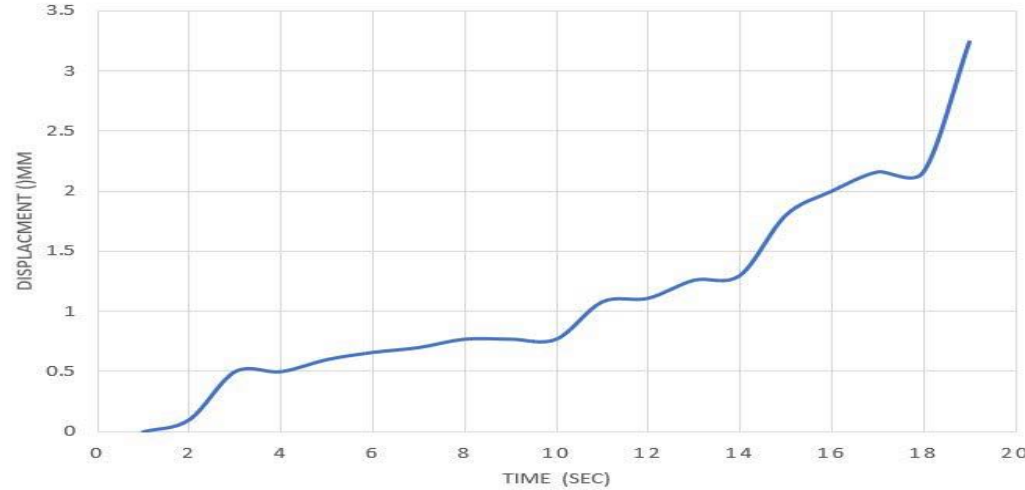




# Practice – Case studies → Electric Longboard: Validation



Simulation results from Simcenter 3D (Digital twin)



Experimental results from Flex Sensors (Physical twin)

Deflection mm	Flex Sensor	<u>Simcenter</u>
<b>Flex 1</b>	0.91	0.7
<b>Flex 2</b>	1.71	1.354
<b>Flex 3</b>	3.3	3.45

**Electric Longboard Validation: Deformation**





# Summary & conclusions

## Key aspects of iMBSE implementation for the electric skateboard

1. Modeling and Simulation Continuum
2. Traceability
3. Digital Thread

## Industry 4.0: Current challenges/Limitation faced by Academia

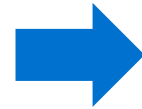
1. Lack of education (curriculum/certification) for Industry 4.0, including iMBSE, MBE, Digital twin, Digital Thread, etc.
2. MBE/iMBSE skills not clearly articulated/defined by industry
3. Cost of infrastructure (both hardware and software)
4. Limited ability to deliver graduates with the required skills to support/drive the digital transformation
5. Limited ability to support the needs of industry for the digital transformation





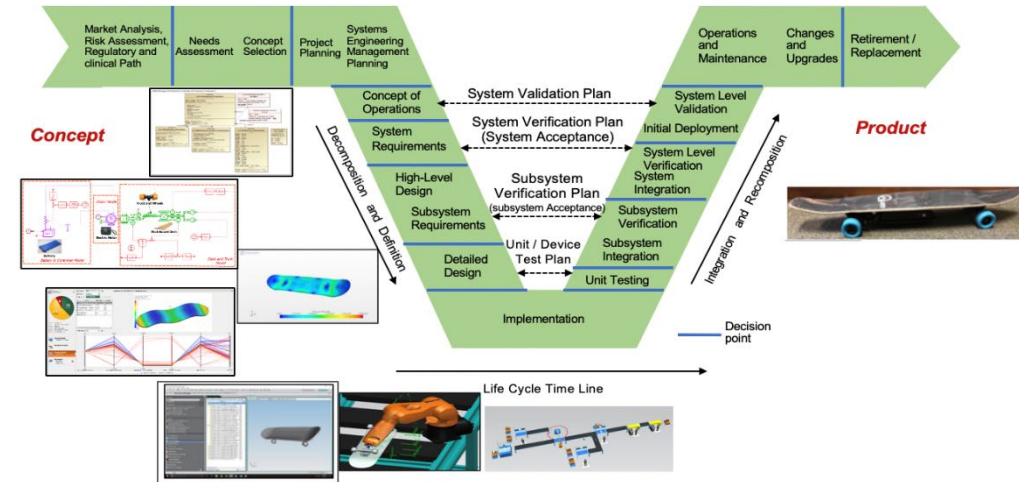
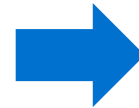
# Summary & conclusions

Engineering Education: Traditional vs. Industry 4.0



Current Engineering Education landscape	Engineering Education for Industry 4.0
Single domain/discipline	Multi-disciplinary, Integrated
Technology/Tools taught by technology programs/community colleges	Offered by Engineering colleges (4 year)
Limited relevance to Industry practice, including Industry 4.0	Driven by Industry (consortium): Applied as well as closely relevant/related engineering curriculum to Industry 4.0

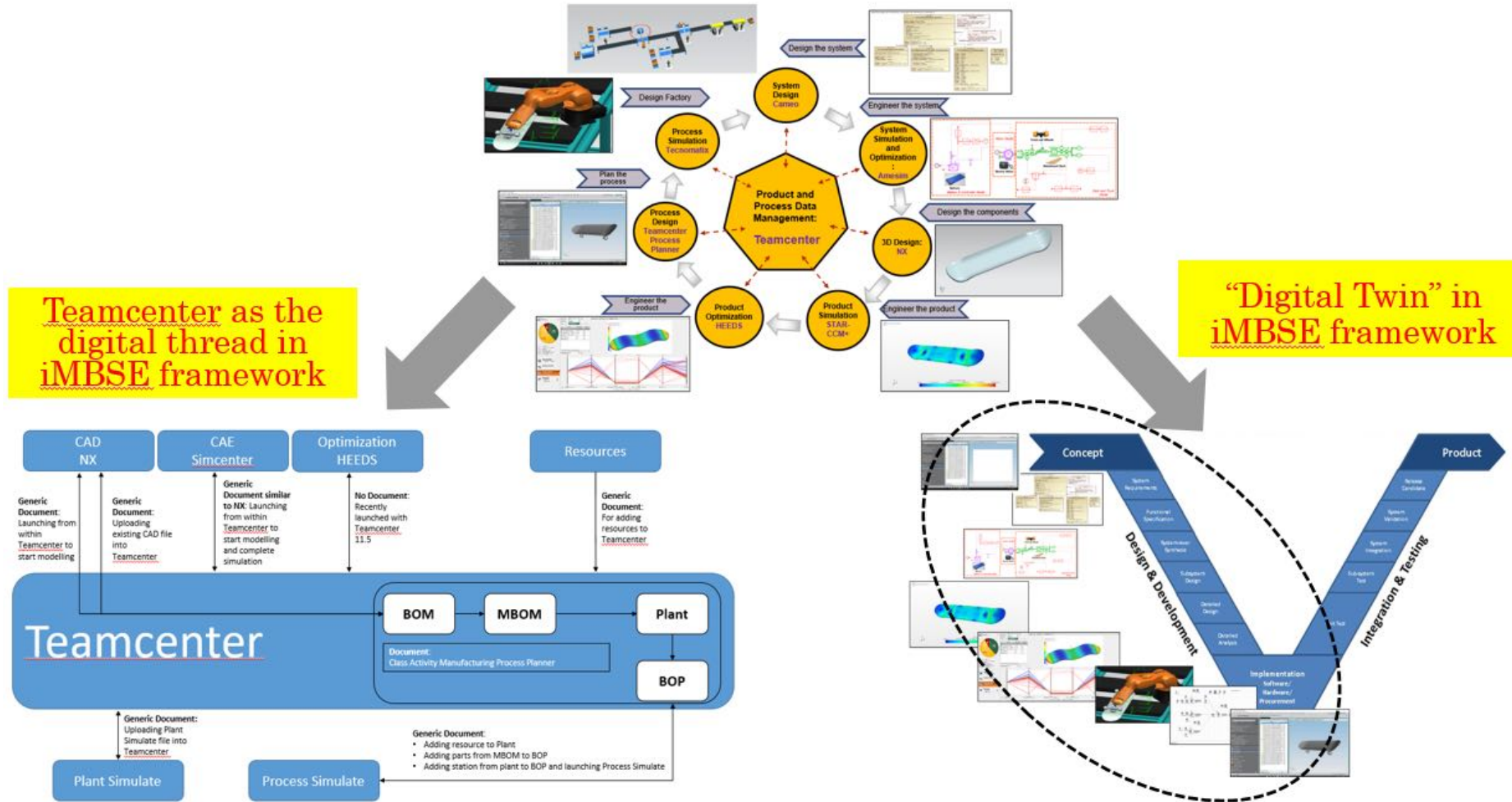
The proposed iMBSE workflow is about the “Digitalization” of the SE process







# Summary & conclusions



iMBSE = Digital twin + Digital thread

[www.incose.org/iw2021/](http://www.incose.org/iw2021/)



# Summary & conclusions



## BENEFITS FOR STUDENTS:

SDPD (or MB-SDPD) curriculum allows a paradigm shift in engineering education, for improved synthesis of engineering knowledge and its implementation in different modern product lifecycle applications

SDPD approach and framework allows student (teams) to successfully complete modern product development within the timeline of one semester, which is a paradigm shift in engineering education.

## BENEFITS FOR INDUSTRY:

Greater innovation in product development

Increased efficiency

Faster time-to-market

Increased adaptability/agility/customization

Knowledge re-use

Better ability to comply with standards

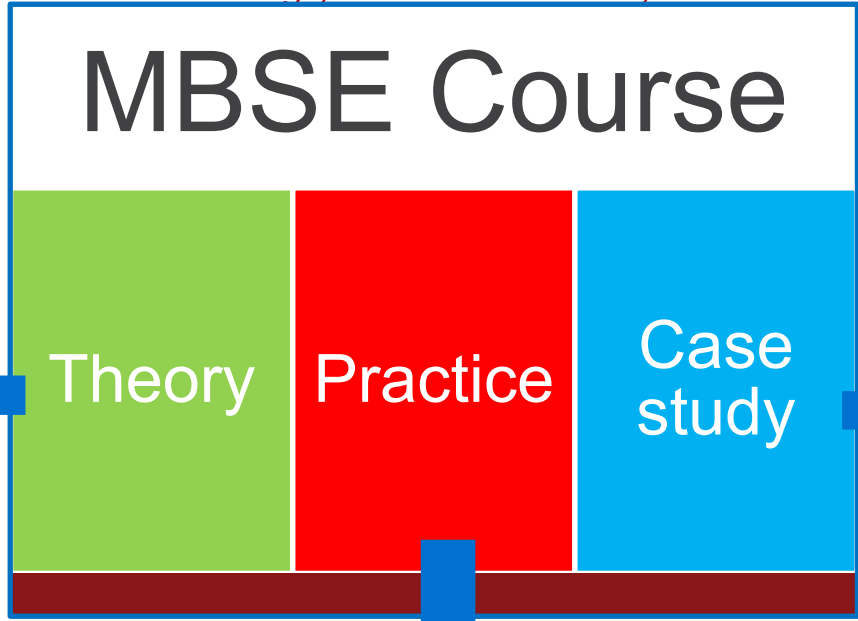
overall, *MBSE (SDPD) can lead to significant competitive advantage.*



# Siemens Integrated Model-based Systems Engineering (iMBSE) Course for Universities – Theory, Practice, and Case Study

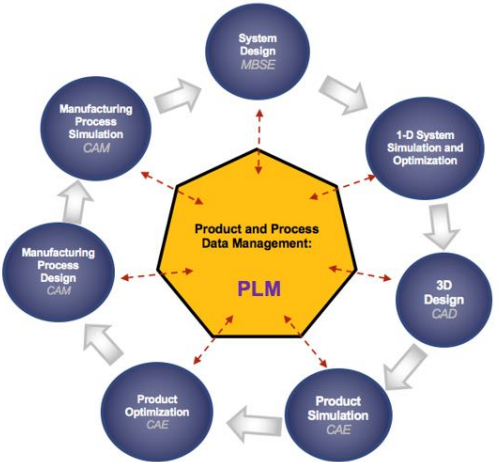


This part of the course consists of lecture material on MBSE, covering the underlying theory of the subject, a detailed overview focusing on MBSE and its relation to SE, as well as Siemens iMBSE framework. In addition, it covers the three pillars of MBSE solution (Methodology, Language, and Tools), and present two of the most applicable solutions, and compares them.



This part of the course demonstrates the implementation of iMBSE using an Electric skateboard/longboard (“E-board”) as the case study. A workflow consisting of 7 major steps integrated through a PLM platform is documented in details. The workflow is implemented using Siemens tools.

This part of the course provides training on the different Siemens tools used to implement the iMBSE workflow for the E-board case study. Tools include, SMW, Amesim, NX, Simcenter (Nastran), HEEDS, MPP, Teenomatix, and Teamcenter (AW, Rich Client, and SE)





**2021**  
Annual **INCOSE**  
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