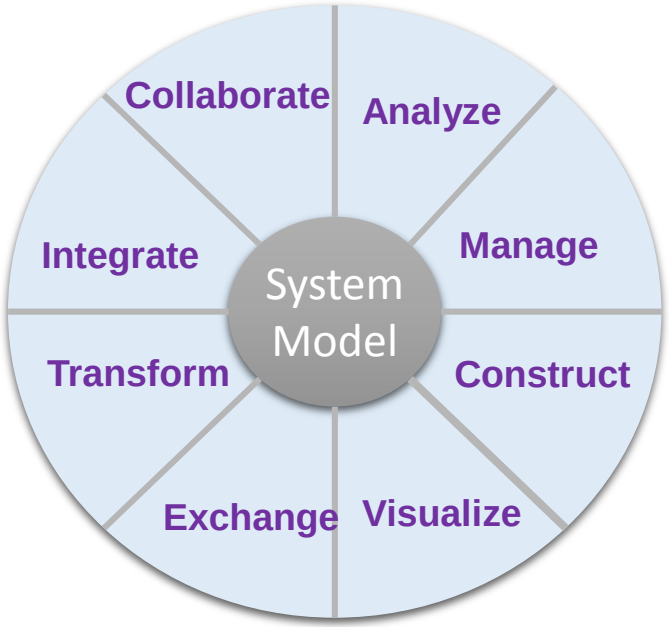
System Modeling Assessment & Roadmap
Joint OMG/INCOSE Working Group

Systems Engineering Model Construction Focus Area



Snapshot
June, 2016

OMGSysML Model Construction Wiki

System Modeling Assessment & Roadmap
Joint OMG/INCOSE Working Group

- **Objectives:**
  - Assess effectiveness of system modeling with SysML in support of MBSE Adoption and Use
  - Develop a preliminary System Modeling Roadmap to improve effectiveness
  - Use the Roadmap to influence the SysML specification, tool vendor implementations, related standards efforts, and industry collaborations

- **Scope:**
  - SysML modeling language and tools
  - Modeling languages and tools that support use of SysML (e.g. constraint language, transformations)
  - Reuse libraries (e.g., models, practices, ..)
  - Integrations with other engineering models and tools

- **Focus Areas:**
  - Systems Engineering Use Cases
  - System Engineering Concept Model
  - SysML v2/MBSE Capabilities including Model Construction, Model Visualization, Model Analysis, Model Management, Model Interoperability,

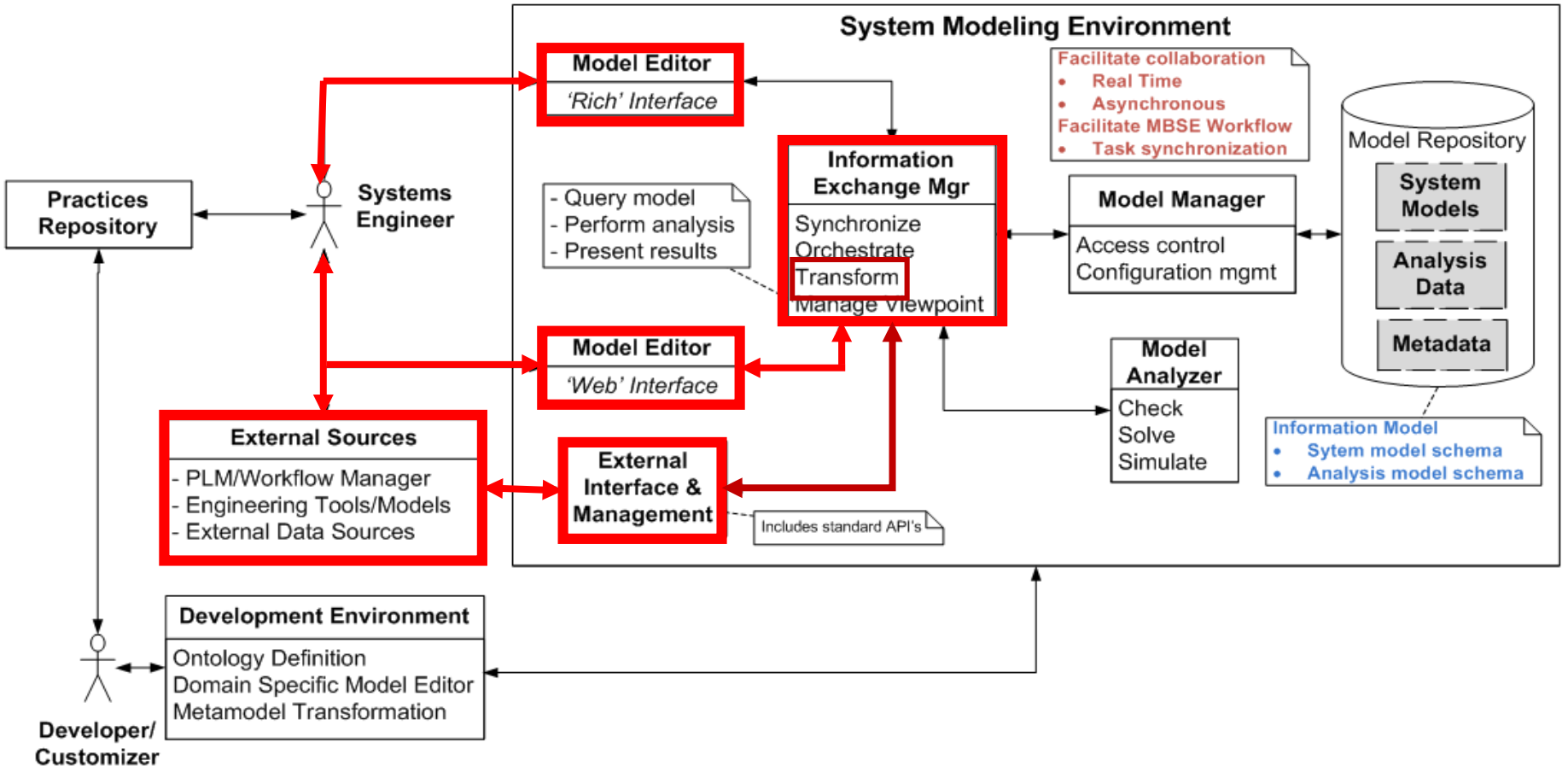
- **Members:**
  - IBM, EADS, LMC, NASA/JPL, Raytheon, John Deere and Various Consultants

MBSE Capability: Construct Model

- **Task objective**
  - Elaborate concepts, requirements, and metrics for effective model construction that support the next generation system modeling language (SysML v2)
- **Use Cases**
  - Systems engineers and other discipline engineers contribute to the development and update of the system model throughout the lifecycle to support system specification, design, analysis, and verification activities
    - Hybrid SUV Change Scenario
- **MoE**
  - Ability to efficiently and intuitively construct models
- **High Level Intent/Driving Requirement:**
  - Intuitive and efficient model construction.
  - It often requires several clicks to capture a core concept in a model.
  - Reduce the time and effort to build and maintain a model.
  - Repeat common modeling patterns with reduced user input
- **Services**
  - Documented in wiki

Systems Modeling Environment
Conceptual Architecture - Construct Model

Initial Scope



Next Generation Systems Modeling Environment – Model Construction

Highlights

From a Macro Model Sketch
to a High Fidelity
Micro Model

Physical – Technical & Non Technical

CRUDEA Services: Create, Retrieve, Update, Delete, Execute, Analyze

Context – Technical & Non Technical

CRUDEA Services: Create, Retrieve, Update, Delete, Execute, Analyze

Logical – Technical & Non Technical

CRUDEA Services: Create, Retrieve, Update, Delete, Execute, Analyze

Synchronized View Model Construction Unstructured Text

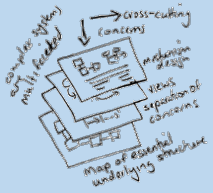
	A	B	D
1	id	name	text
2	REQ-0	HSUV Specification	
3	REQ-0.1	Performance	The HSUV shall have...
4	REQ-0.2	Capacity	The HSUV shall have the capacity...
5	REQ-0.1.1	Braking	The HSUV shall have the braking...
6	REQ-0.1.2	Fuel Economy	The HSUV shall have fuel economy...
7	REQ-0.1.3	Acceleration	The vehicle should have a 0-30 mph...
8	REQ-0.1.4	OffRoad Capability	The HSUV shall have the offroad capability...
9	REQ-0.3	Regenerative Breaking	Regenerative braking should not adversely impact...
9	REQ-0.4	Power	The power of the engine...
10			
Requirement		Problems | Rationale	TestCase

Size, Weight, Location, Interface

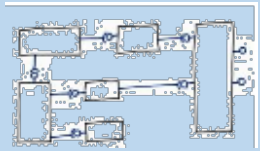
Macro Model Sketch

Environment, Location, Mission

Systems, Subsystems, Products, Components, Interfaces



Micro Model High Fidelity

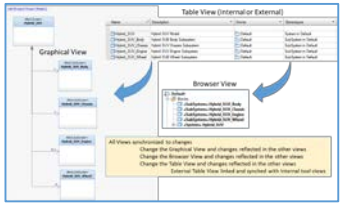


Time, Power, Temperature, Resource Consumption

Cost, Schedule, People, Political

Sense, Control, Command, Effect, Communicate

Synchronized View Model Construction with Tables



CRUDEA Services: Create, Retrieve, Update, Delete, Execute, Analyze

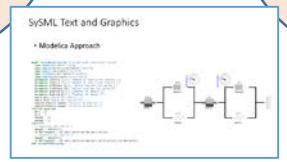
Performance – Technical & Non Technical

CRUDEA Services: Create, Retrieve, Update, Delete, Execute, Analyze

Constraints – Technical & Non Technical

CRUDEA Services: Create, Retrieve, Update, Delete, Execute, Analyze

Functional – Technical & Non Technical



Model Construction with Tables

Highlights

Synchronized View Model Construction with Tables

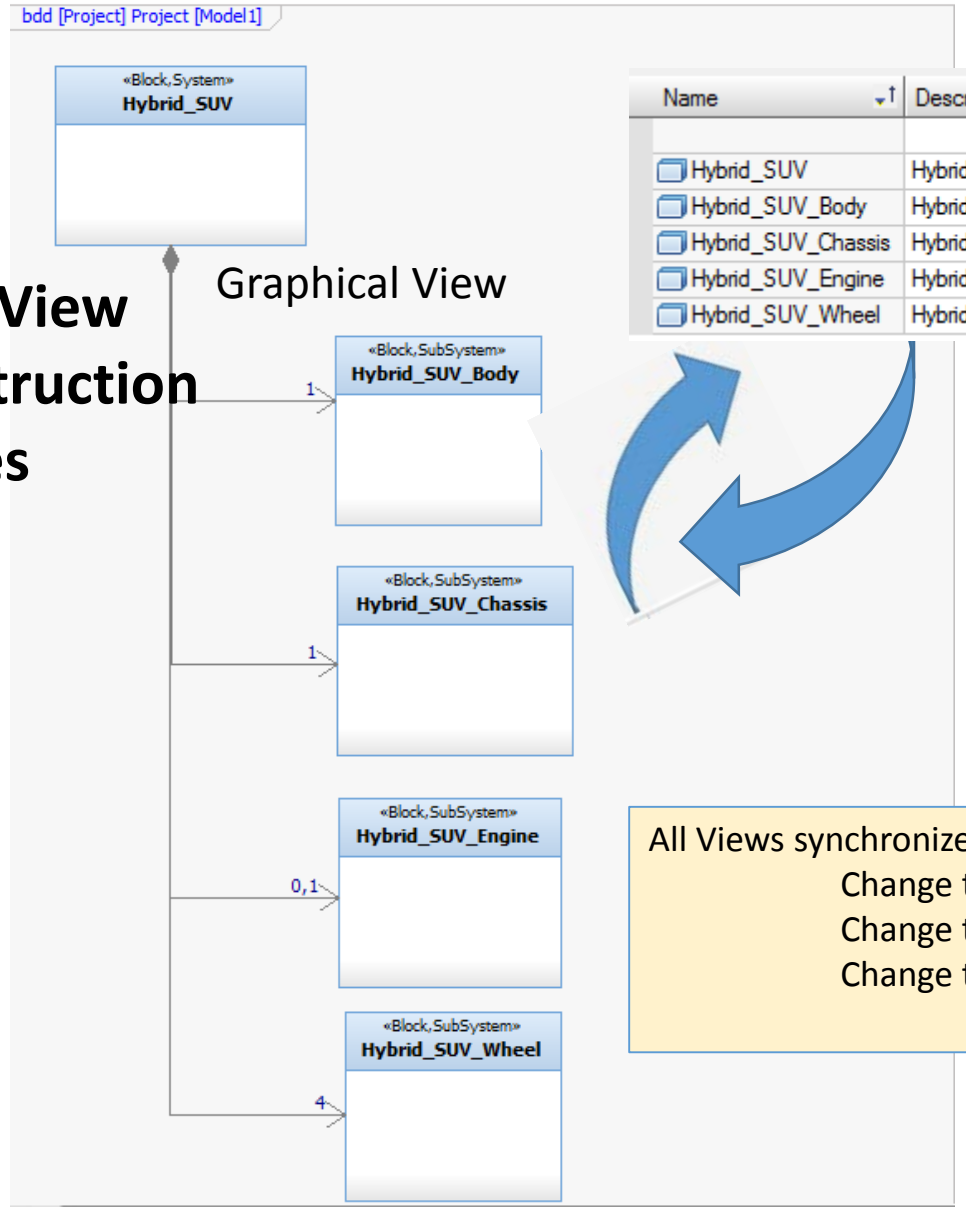
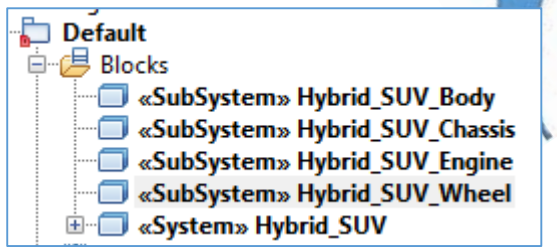


Table View (Internal or External)

Name	Description	Owner	Stereotypes
Hybrid_SUV	Hybrid SUV Model	Default	System in Default
Hybrid_SUV_Body	Hybrid SUB Body Subsystem	Default	SubSystem in Default
Hybrid_SUV_Chassis	Hybrid SUV Chassis Subsystem	Default	SubSystem in Default
Hybrid_SUV_Engine	Hybrid SUV Engine Subsystem	Default	SubSystem in Default
Hybrid_SUV_Wheel	Hybrid SUB Wheel Subsystem	Default	SubSystem in Default

Browser View



All Views synchronized to changes

Change the Graphical View and changes reflected in the other views

Change the Browser View and changes reflected in the other views

Change the Table View and changes reflected in the other views

External Table View linked and synched with internal tool views

Model Construction with Unstructured Text

Synchronized View
Model Construction
Unstructured Text

Unique Requirement Name Established

Unique Requirement ID Established

Requirement Text Semantically Parsed to capture system components, characteristics, functions, constraints, timing, value properties, etc

	A	B	D
1	id	name	text
2	REQ-0	HSUV Specification	
3	REQ-0.1	Performance	The HSUV shall have...
4	REQ-0.2	Capacity	The HSUV shall have the capacity...
5	REQ-0.1.1	Braking	The HSUV shall have the braking...
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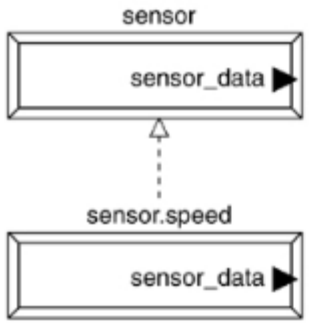
9	REQ-0.4	Power	The power of the engine...
10	...	...	...

Requirement | Problems | Rationale | TestCase

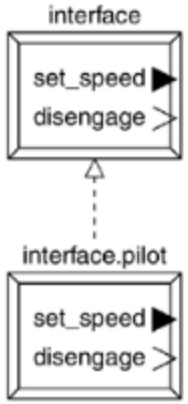
SysML Text and Graphics

- AADL Approach



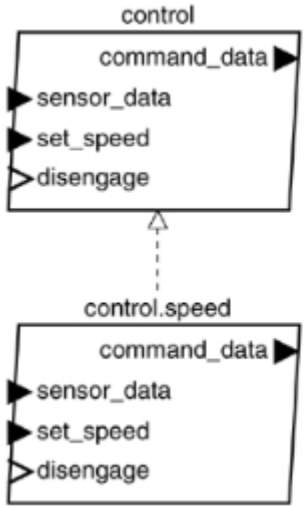

```
device sensor
  features
   sensor_data: out data port;
end sensor;


device implementation sensor.speed
end sensor.speed;
```



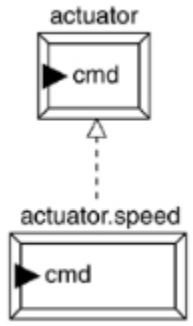

```
device interface
  features
   set_speed: out data port;
   disengage: out event port;
end interface;


device implementation interface.pilot
end interface.pilot;
```




```
process control
  features
   command_data: out data port;
   sensor_data: in data port;
   set_speed: in data port;
   disengage: in event port;
end control;


process implementation control.speed
end control.speed;
```




```
device actuator
  features
   cmd: in data port;
end actuator;


device implementation actuator.speed
end actuator.speed;
```

SySML Text and Graphics

- Modelica Approach

```
model SecondOrderSystem "A second order rotational system"
  type Angle=Real(unit="rad");
  type AngularVelocity=Real(unit="rad/s");
  type Inertia=Real(unit="kg.m2");
  type Stiffness=Real(unit="N.m/rad");
  type Damping=Real(unit="N.m.s/rad");
  parameter Inertia J1=0.4 "Moment of inertia for inertia 1";
  parameter Inertia J2=1.0 "Moment of inertia for inertia 2";
  parameter Stiffness k1=11 "Spring constant for spring 1";
  parameter Stiffness k2=5 "Spring constant for spring 2";
  parameter Damping d1=0.2 "Damping for damper 1";
  parameter Damping d2=1.0 "Damping for damper 2";
  Angle phi1 "Angle for inertia 1";
  Angle phi2 "Angle for inertia 2";
  AngularVelocity omega1 "Velocity of inertia 1";
  AngularVelocity omega2 "Velocity of inertia 2";
initial equation
  phi1 = 0;
  phi2 = 1;
  omega1 = 0;
  omega2 = 0;
equation
  // Equations for inertia 1
  omega1 = der(phi1);
  J1*der(omega1) = k1*(phi2-phi1)+d1*der(phi2-phi1);
  // Equations for inertia 2
  omega2 = der(phi2);
  J2*der(omega2) = k1*(phi1-phi2)+d1*der(phi1-phi2)-k2*phi2-d2*der(phi2);
end SecondOrderSystem;
```